

K30 Pro Touch Process Data Function

11/16/2022

This document covers the installation and use of a function for Siemens's TIA Portal software package. This function handles cyclic IO-Link Process Data Out to a Banner K30 Pro Touch light via an IO-Link Master from a Siemens PLC. The function covers parsing and display of the K30 Pro Touch sensor Process Data Out.

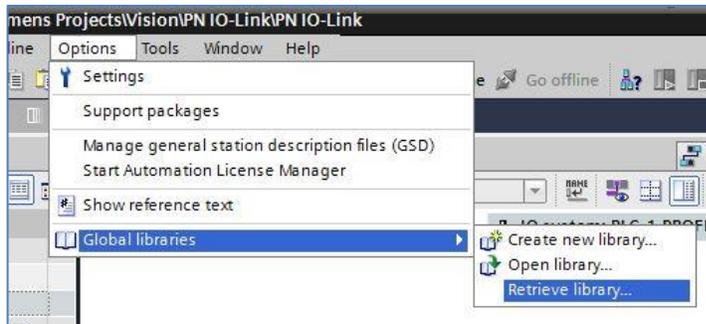
Components

Banner K30 Pro.zal14

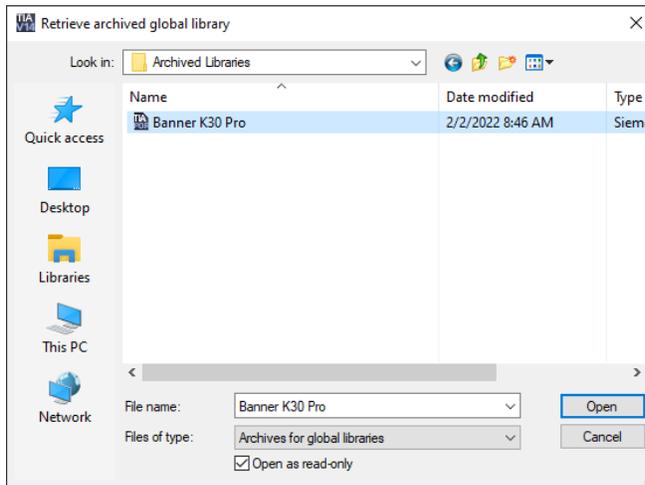
There are two methods for the process data. The first is used when creating a connection to Banner's IO-Link masters. The second set of instructions are for systems using other manufacturer's IO-Link masters.

Installation Instructions

1. Open a project.
2. Go to Options > Global Libraries > Retrieve Library.



3. Select the Banner K30 Pro. Click Open.



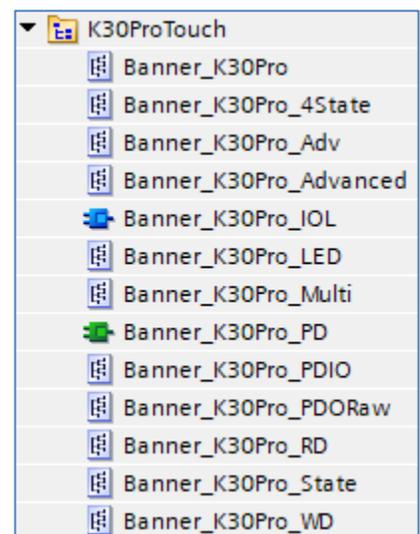
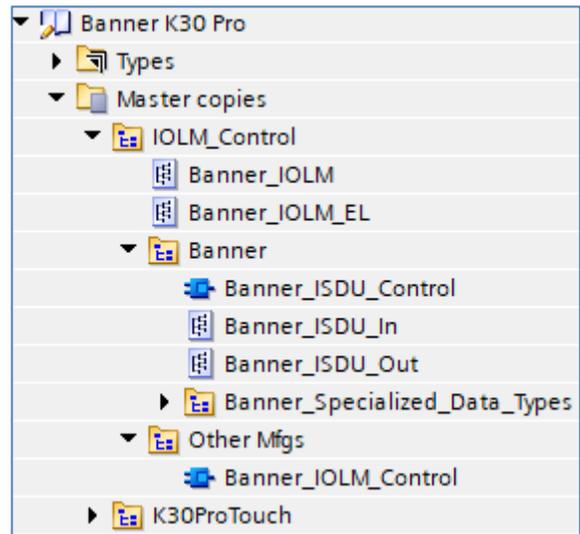
4. The library is now accessible in the Libraries tab.
5. Go to page 3 for Banner IO-Link Masters and to page 7 for all other IO-Link Masters.

Setup of K30 Pro Touch with a Banner DXMR90-4K

1. Go to Device and Networks to configure the DXMR90-4K. Add the DXMR90-4K if it has yet to be added to the system.
2. Add Banner IO-Link Master Info to Slot 1. This sets the DXMR90-4K for IO-Link mode.
3. Open the IO-Link Generic Devices and select the proper module. The 8/8 byte is required for K30 Pro Touch. Make note of the I address for the Slot 2 which represents Port 1. Slot 2 starts are 1 for outputs. The other number needed is I3. The data for the port start at that point (I3). The previous two bytes Port Control.

Module	Rack	Slot	I address	Q address	Type
▼ dxm	0	0			1-port Device
▶ Interface	0	0 X1			dxm
Banner IO-Link Master Info_1	0	1	1...9		Banner IO-Link Master Info
IO-Link In/Out 8/ 8 Byte + Status_1	0	2	10...21	1...22	IO-Link In/Out 8/ 8 Byte + Status

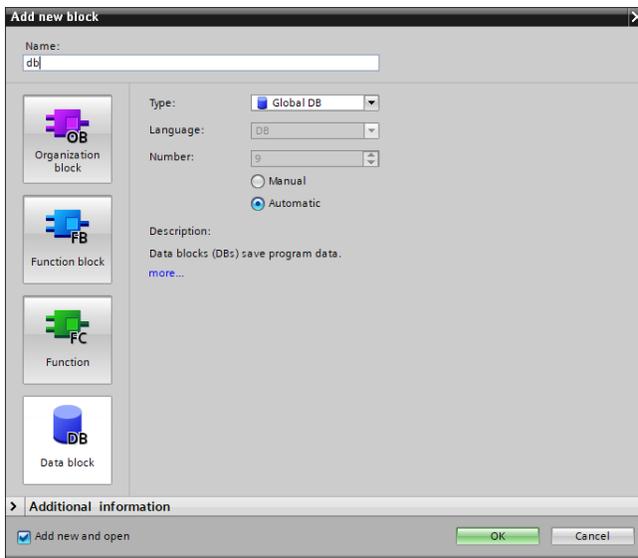
4. Drag the necessary tag from IOLM_Control > Banner > Banner_Specialized_Data_Types. The tag used in this example is "Banner_32out". This tag represents the full raw process data along with port status information.
5. Drag the necessary files from the TL50 Select Folder.
 - a. Move Banner_K30Pro, Banner_K30Pro_4State, Banner_K30Pro_Adv, Banner_K30Pro_Advanced, Banner_K30Pro_LED, Banner_K30Pro_Multi, Banner_K30Pro_PDIO, and Banner_K30Pro_PDORaw to the PLC Data Types area.
 - b. Move Banner_K30Pro_PD to the Program Blocks area.



6. Go to PLC Tags. Create four tags. One set of tags is for the full data structure while the second set creates tags to represent the raw Process Data from the IO-Link Master. In this example, Tag table_1 was created, then the tag “K30Pro IOLM1 01 PDO” was created using a Data Type of “Banner_8out”. This naming convention calls out the type of device in question as well as the specific IO-Link Master and port number where the sensor is connected. A different IO-Link Master might be named IOLM2 or IOLM3, for instance, and other specific sensors may be connected to different port numbers. The “Q” address found in step 2 (%Q1) is tied to this new tag. The tag that represents the raw data is “K30Pro IOLM1 01 outRaw” and uses the “Q” address found in step 2 (%Q3). Tags “K30Pro IOLM1 02 PDI” (%I10) and “K30Pro IOLM1 01 inRaw” (%IW14) are created for the inputs also. This is the tag that will be used in the Function block.

Name	Data type	Address
▶ K30Pro IOLM1 01 PDI	*Banner_8In*	%I10.0
K30Pro IOLM1 01 inRaw	UInt	%IW14
▶ K30Pro IOLM1 01 outRaw	*Banner_K30Pro_PDORaw*	%Q3.0
▶ K30Pro IOLM1 01 PDO	*Banner_8Out*	%Q1.0

7. Go to Program blocks. Add a new Data block if necessary. In this example the new data block is named “db”.



- In the new data block, create a new tag to represent the parsed Process Data Output for our K30 Pro Touch. The tag name again calls out the type of sensor, the IO-Link Master, and the port number. Use the data type "Banner_K30PRO_PDIO" for the new tag.

Name	Data type
▼ Static	
■ ▼ K30Pro IOLM1 01 PD	"Banner_K30Pro_PDIO"
■ ▶ Multicolor	"Banner_K30Pro_Multi"
■ ▶ Four State	"Banner_K30Pro_4State"
■ ▶ Advanced	"Banner_K30Pro_Advanced"
■ ▶ LED	"Banner_K30Pro_LED"

- Add the "Banner_K30Pro_PD" function to an OB ladder. Link the "PDO" to the raw process data variable from step 5. The tag name again calls out the type of device, IO-Link Master, and the port number. Use the variable called "K30Pro IOLM1 01 outRaw" in this example. Link the "PDI" to the raw process data variable from step 5. Use the variable called "K30Pro IOLM1 01 inRaw" from step 5. The "K30 Pro PD" needs to be linked to the variable created in step 7. It was called "K30Pro IOLM1 01 PD" for this example.

The last variable, "Operational Mode", allow the function to correctly interpret the Process Data Out. In the case of the K30 Pro Touch , there are four user-selected modes for the Process Data Out. This function needs to know what choice has been made in the TL50 Pro Select for this Operational Mode variable.

There are two ways to achieve this goal. We can simply type in the correct number for Operational Mode (see Fig. 1), or we can link this K30 Pro Touch Process Data Function to the K30 Pro Touch Parameter Data Function Block (see Fig. 2). See Appendix A for more information about K30 Pro Touch Process Data Out.

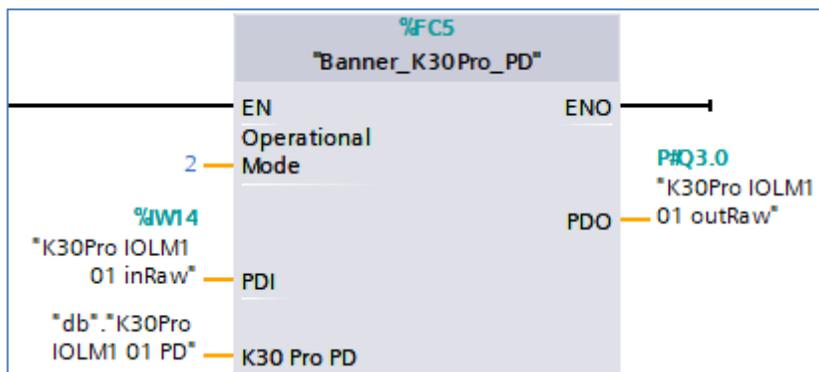


Figure 1: Hand type correct number for Operational Mode

NOTE: if you type in the incorrect number (i.e. it does not match the tower light’s current Operational Mode configuration) you will get incorrectly displayed Process Data Out information.

Operational Mode: the options here are “0” (MultiColor Mode), “1” (Four State Mode), “2” (Advanced Mode), and “3” (LED Mode); where the entire tower light behaves as a level indicator). The default is “2”.

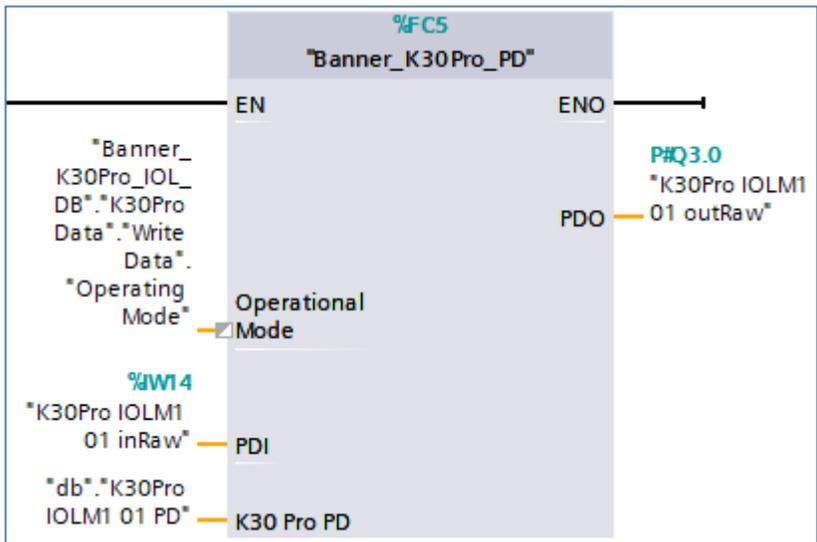
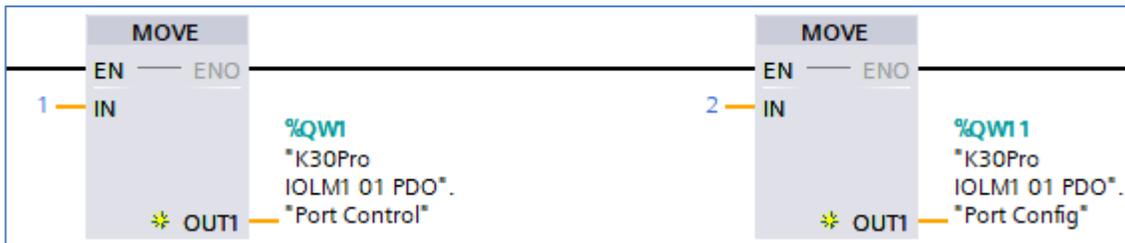


Figure 2: Linking Operational Mode variable to K30 Pro Touch Parameter Data Function Block

10. The final step is to configure the IO-Link output control. This is done by sending a 1 to Port Control and a 2 to Port Config. Both parameters are part of the tag created in step 6 “K30Pro IOLM1 01 PDO”.



11. Process Data Setup is complete.

12. Compile and download the configuration to the PLC, then go online. Open the “db” data block and click Monitor all. The K30 Pro Touch can be controlled now.

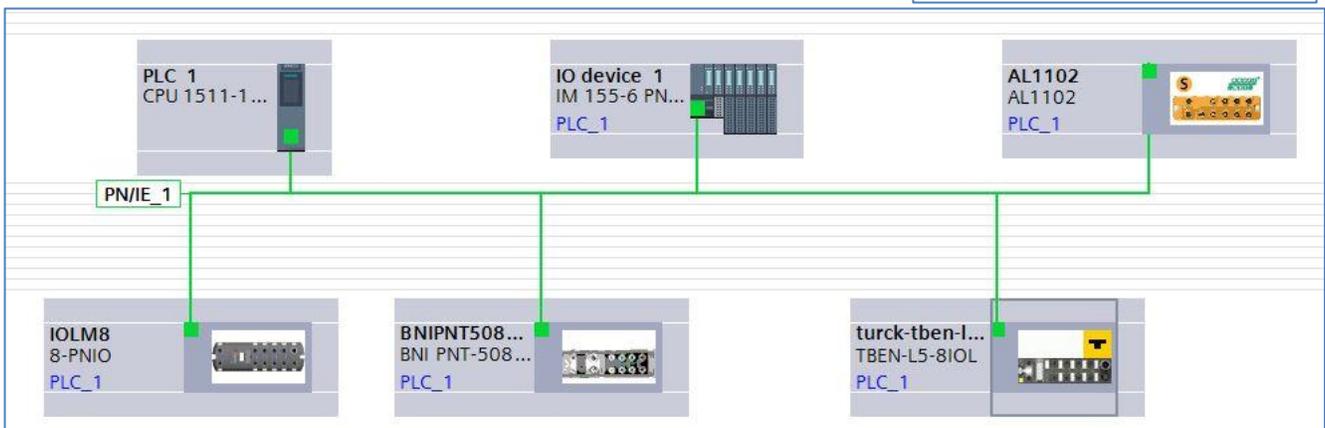
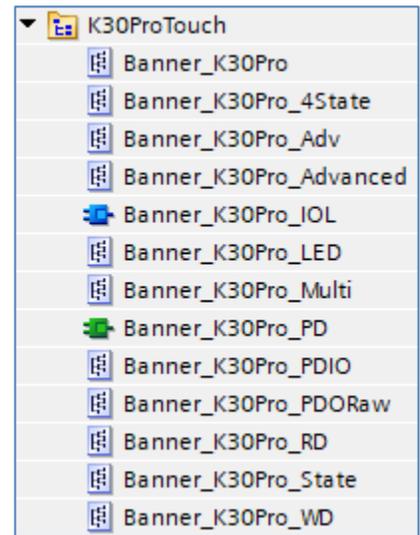
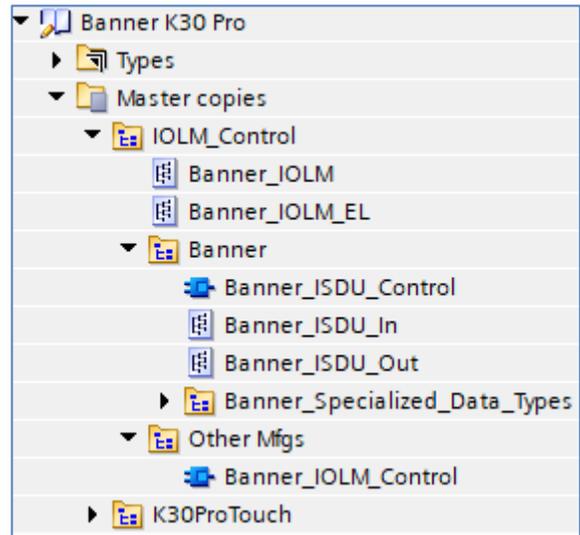
Setup of K30 Pro Touch with other IO-Link Masters

1. The Banner K30 Pro library will now be in the Global Library List. Expand the Master copies section. The K30 Pro Touch folder contains elements for both Process Data and Parameter Data connections to a K30 Pro Touch device. As Process Data is the focus of this paper, we will concern ourselves with these seven items: Banner_K30Pro_4State, Banner_K30Pro_Adv, Banner_K30Pro_Advanced, Banner_K30Pro_LED, Banner_K30Pro_Multi, Banner_K30Pro_PD, Banner_K30Pro_PDIO, and Banner_K30Pro_PDORaw.

2. Drag Banner_K30Pro_PD to the Program Blocks area under your PLC.

3. Drag Banner_K30Pro_4State, Banner_K30Pro_Adv, Banner_K30Pro_Advanced, Banner_K30Pro_LED, Banner_K30Pro_Multi, Banner_K30Pro_PDIO, and Banner_K30Pro_PDORaw to the PLC Data Types area under your PLC.

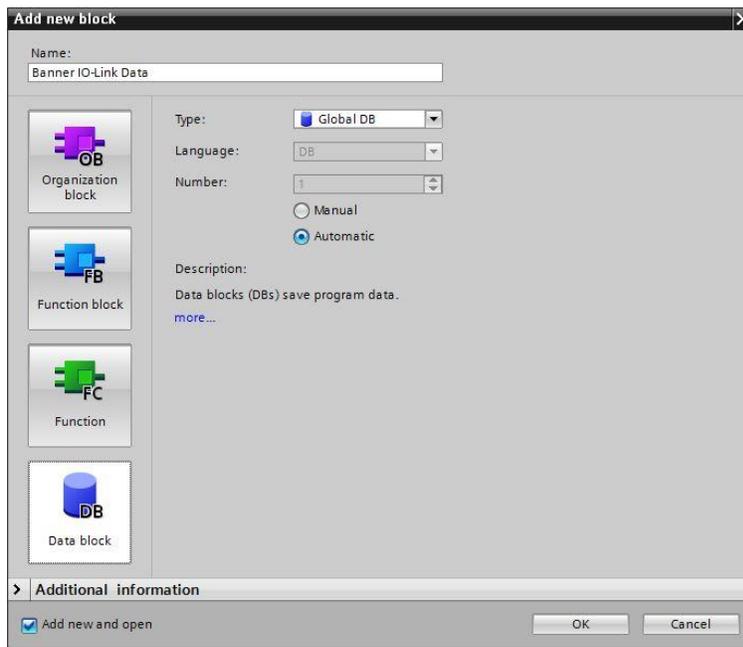
4. Go to Devices and networks to configure the system as necessary. Below is an example of what a configuration might look like. This example shows 5 different IO-Link Masters connected to the same PLC.



5. Click on the relevant device and configure the IO-Link Master as necessary. Refer to the documentation for the IO-Link Master. Recall that a K30 Pro Touch requires 9 bytes of space for the Process Data Out and 1 byte for the Process Data In.
6. Record the “I” and “Q” addresses where this K30 Pro Touch Process Data is to be stored, as these addresses will be required in the next step. In this example, 9 bytes of Process Data Out for port 2 on the IO-Link Master will be stored in Q68 through Q76 and the 2 bytes of Process Data In will be stored in I68 and I69.
7. Go to PLC Tags. Add a new tag table, then create a new tag to represent the raw Process Data Out to be sent from the IO-Link Master. In this example, Tag table_1 was created, then the tag “K30 IOLM1 01 PDO” was created using a Data Type of “Banner_K30Pro_PDORaw”. This naming convention calls out the type of sensor in question as well as the specific IO-Link Master and port number where the sensor is connected. A different IO-Link Master might be named IOLM2 or IOLM3, for instance, and other specific sensors may be connected to different port numbers. The “Q” address found in step 9 is tied to this new tag. Similarly, we need to make a tag for the Process Data In. Here the name “K30 IOLM1 01 PDI” was chosen, with a Data Type of Word. The “I” address from step 9 is used.

IOLM			
	Name	Data type	Address
1	K30 IOLM1 01 PDI	Word	%IW68
2	K30 IOLM1 01 PDO	*Banner_K30Pr...	%Q68.0

8. Go to Program blocks. Add a new Data block if necessary. In this example the new data block is named “Banner IO-Link Data”.



- In the new data block, create a new tag to represent the parsed Process Data In and Out for our K30 Pro Touch. The tag name again calls out the type of sensor, the IO-Link Master, and the port number. Use the data type "Banner_K30Pro_PDIO" for the new tag.

Banner IO-Link Data		
	Name	Data type
1	Static	
2	K30 IOLM1 01 PD	"Banner_K30Pro_PDIO"

- Add the "Banner_K30Pro_PD" function to an OB ladder. Link the "PDI" to the raw Process Data In variable from step 10. Link the "PDO" to the raw Process Data Out variable from step 10. Link "K30 Pro PD" to the parsed Process Data variable from step 12.

The last variable, "Operational Mode", allows the function to correctly interpret the Process Data Out. In the case of the K30 Pro Touch, there are five user-selected modes for the Process Data Out. This function needs to know what choice has been made in the K30 Pro Touch for this Operational Mode variable.

There are two ways to achieve this goal. We can simply type in the correct number for Operational Mode (see Fig. 1), or we can link this K30 Pro Touch Process Data Function to the K30 Pro Touch Parameter Data Function Block (see Fig. 2). See Appendix A for more information about K30 Pro Touch Process Data Out.

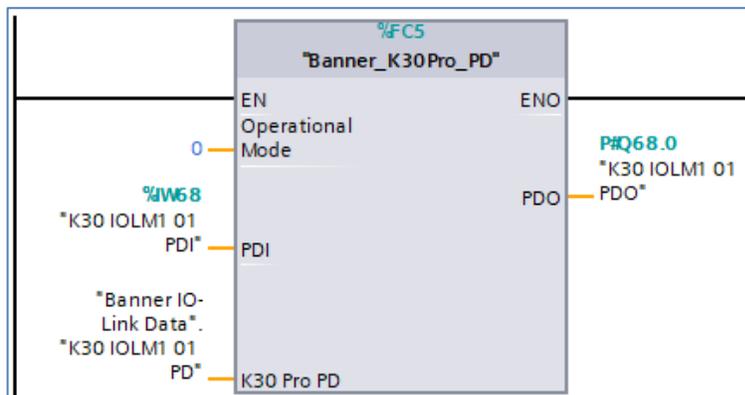


Figure 3: Hand type correct number for Operational Mode

NOTE: if you type in the incorrect number (i.e., it does not match the K30's current Operational Mode configuration) you will get incorrectly displayed Process Data Out information.

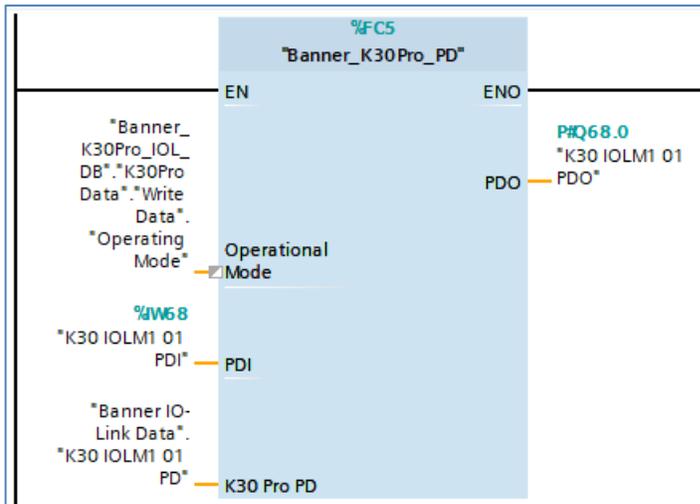


Figure 4: Linking Operational Mode variable to K30 Pro Touch Parameter Data Function Block

11. Process Data setup is complete.
12. Compile and download the configuration to the PLC, then go online. Open the “Banner IO-Link Data” data block and click Monitor all. You should see parsed K30 Pro Touch Process Data In.
13. Process Data is broken up into four different types. When Operational Modes controls which of four types is used to parse the raw byte data.

Banner IO-Link Data		
	Name	Data type
	Static	
	K30 IOLM1 01 PD	"Banner_K30Pro_PDIO"
	Multicolor	"Banner_K30Pro_Multi"
	Four State	"Banner_K30Pro_4State"
	Advanced	"Banner_K30Pro_Advanced"
	LED	"Banner_K30Pro_LED"

0: MultiColor
1: Four State
2: Advanced
3: LED

- a. MultiColor has three pieces of data. State Control is an output that controls the light. Touch State and Mode State are inputs giving the state of the light.

Multicolor	"Banner_K30Pro_Multi"
Touch State	USInt
Mode State	USInt
State Control	USInt

- b. Four State has three pieces of data. Job Control tells the light if a pick is being requested. Depending on the Touch State the light will be automatically set to one of four colors. Touch State and Mode State are inputs giving the state of the light.

▼ Four State	"Banner_K30Pro_4State"
■ Touch State	USInt
■ Mode State	USInt
■ Job Control	USInt

- c. Advanced allows for the complete control of the light. In MultiColor and Four State the light has a few preconfigured modes that can be activated depending on the State Control and Job Control values. Advanced mode the process data fully control the light. Nothing is preconfigured. Turning on the light requires a non-zero value to be entered into animation. Depending on the value entered multiple modes can be activated. Color 1 and Color 2 control the color the light will emit. Color 2 is only used in a few modes activated by Animation.

Advanced	"Banner_K30Pro_Advanced"
Touch State	USInt
▼ Light Control	"Banner_K30Pro_Adv"
■ Animation	USInt
■ Animation Direction	Bool
■ Animation Pattern	USInt
■ Animation Speed	USInt
■ Color 1	USInt
■ Color 1 Intensity	USInt
■ Color 2	USInt
■ Color 2 Intensity	USInt
Dynamic Sequence	USInt
Sequence Start Loc	USInt

- d. LED controls each LED individually. There process data breaks out each of the eight LEDs individually. When a non-zero value is entered the LED will light up with the color corresponding to that value.

▼ LED	"Banner_K30Pro_LED"
■ Touch State	USInt
■ LED 1 Color	USInt
■ LED 1 Intensity	USInt
■ LED 2 Color	USInt
■ LED 2 Intensity	USInt
■ LED 3 Color	USInt
■ LED 3 Intensity	USInt
■ LED 4 Color	USInt
■ LED 4 Intensity	USInt

Appendix A

K30 Pro Touch Process Data

The K30 Pro Touch has 2 bytes of Process Data In and 8 bytes of Process Data Out. There are five modes for displaying this data, as shown below. This Process Data is mapped to a specific group of PROFINET addresses. This function intelligently parses this Process Data into its component pieces.

The first is mode 0, "Multicolor".

ProcessDataIn "Process Data In" id=V_Pd_InMulticolor

bit length: 16
data type: 16-bit Record (subindex access not supported)

subindex	bit offset	data type	allowed values	default value	acc. restr.	mod. other var.	excl. from DS	name	description
1	0	Boolean	false = Inactive, true = Active					Output State	Output State. Related parameters defined in output and touch settings parameter data.
2	8	2-bit UInteger	0 = State 1, 1 = State 2, 2 = State 3, 3 = State 4					State	Animation State. Related parameters defined in Four State Full Logic/Multicolor parameter data.

ProcessDataOut "Process Data Out" id=V_Pd_OutMulticolor

bit length: 64
data type: 64-bit Record (subindex access not supported)

subindex	bit offset	data type	allowed values	default value	acc. restr.	mod. other var.	excl. from DS	name	description
1	0	2-bit UInteger	0 = State1, 1 = State2, 2 = State3, 3 = State4					State	Animation State. Related parameters defined in Four State Full Logic/Multicolor parameter data.

The next mode, "1", is "Four State Full Logic".

ProcessDataIn "Process Data In" id=V_Pd_InFourStateFullLogic

bit length: 16
data type: 16-bit Record (subindex access not supported)

subindex	bit offset	data type	allowed values	default value	acc. restr.	mod. other var.	excl. from DS	name	description
1	0	Boolean	false = Inactive, true = Active					Output State	Output State. Related parameters defined in output and touch settings parameter data.
2	8	2-bit UInteger	0 = State 1, 1 = State 2, 2 = State 3, 3 = State 4					State	Animation State. Related parameters defined in Four State Full Logic/Multicolor parameter data.

ProcessDataOut "Process Data Out" id=V_Pd_OutFourStateFullLogic

bit length: 64
data type: 64-bit Record (subindex access not supported)

subindex	bit offset	data type	allowed values	default value	acc. restr.	mod. other var.	excl. from DS	name	description
1	0	Boolean	false = Off, true = On					Job Input	Job Input for Four State Full Logic mode.
2	1	Boolean	false = Off, true = On					User Input (Indicator only)	User Input for Four State Full Logic mode (Indicator only).

Mode 2 is “Advanced”.

ProcessDataIn "Process Data In" id=V_Pd_InAdvanced

bit length: 16
data type: 16-bit Record (subindex access not supported)

subindex	bit offset	data type	allowed values	default value	acc. restr.	mod. other var.	excl. from DS	name	description
1	0	Boolean	false = Inactive, true = Active					Output State	Output State. Related parameters defined in output and touch settings parameter data.

ProcessDataOut "Process Data Out" id=V_Pd_OutAdvanced

bit length: 64
data type: 64-bit Record (subindex access not supported)

subindex	bit offset	data type	allowed values	default value	acc. restr.	mod. other var.	excl. from DS	name	description
1	0	4-bit Unsigned Integer	0 = Off, 1 = Steady, 2 = Flash, 3 = Two Color Flash, 4 = 50/50, 5 = 50/50 Rotate, 6 = Chase, 7 = Intensity Sweep, 8 = Color Sweep, 9 = Sequence, 10 = Wave, 11 = Double Wave					Animation Type	The Animation type
2	4	Boolean	false = CCW, true = CW					Animation Direction	The Direction of Animation rotation
3	5	3-bit Unsigned Integer	0 = Flash, 1 = Strobe, 2 = Three Pulse, 3 = SOS, 4 = Random					Animation Pattern	The pattern of Animation
4	8	2-bit Unsigned Integer	0 = Slow, 1 = Medium, 2 = Fast, 3 = Custom					Animation Speed	The speed of the Animation
5	10	2-bit Unsigned Integer	0					Reserved	Reserved
6	32	8-bit Unsigned Integer	0..255					Dynamic Sequence Value (0-255)	Value describing the LED position of the device. LED states defined in process data.
7	40	3-bit Unsigned Integer	0 = LED1, 1 = LED2, 2 = LED3, 3 = LED4					Sequence Start Location	Defines the LED location that the sequence animation is initiated at.
8	48	5-bit Unsigned Integer	0 = Green, 1 = Red, 2 = Orange, 3 = Amber, 4 = Yellow, 5 = Lime Green, 6 = Spring Green, 7 = Cyan, 8 = Sky Blue, 9 = Blue, 10 = Violet, 11 = Magenta, 12 = Rose, 13 = White, 14 = Custom1, 15 = Custom2					Color 1	The main color of the Animation, Custom Colors are defined in Parameter data
9	53	3-bit Unsigned Integer	0 = High, 1 = Medium, 2 = Low, 3 = Off, 4 = Custom					Color 1 Intensity	The Intensity of Color 1, Custom Intensity defined in Parameter Data
10	56	5-bit Unsigned Integer	0 = Green, 1 = Red, 2 = Orange, 3 = Amber, 4 = Yellow, 5 = Lime Green, 6 = Spring Green, 7 = Cyan, 8 = Sky Blue, 9 = Blue, 10 = Violet, 11 = Magenta, 12 = Rose, 13 = White, 14 = Custom1, 15 = Custom2					Color 2	The secondary color of the Animation, Custom Colors are defined in Parameter data
11	61	3-bit Unsigned Integer	0 = High, 1 = Medium, 2 = Low, 3 = Off, 4 = Custom					Color 2 Intensity	The Intensity of Color 2, Custom Intensity defined in Parameter Data

Mode 3 is "LED Control".

ProcessDataIn "Process Data In" id=V_Pd_InLedControl

bit length: 16
data type: 16-bit Record (subindex access not supported)

subindex	bit offset	data type	allowed values	default value	acc. restr.	mod. other var.	excl. from DS	name	description
1	0	Boolean	false = Inactive, true = Active					Output State	Output State. Related parameters defined in output and touch settings parameter data.

ProcessDataOut "Process Data Out" id=V_Pd_OutLedControl

bit length: 64
data type: 64-bit Record (subindex access not supported)

subindex	bit offset	data type	allowed values	default value	acc. restr.	mod. other var.	excl. from DS	name	description
1	0	4-bit UInteger	0 = Green, 1 = Red, 2 = Orange, 3 = Amber, 4 = Yellow, 5 = Lime Green, 6 = Spring Green, 7 = Cyan, 8 = Sky Blue, 9 = Blue, 10 = Violet, 11 = Magenta, 12 = Rose, 13 = White, 14 = Custom1, 15 = Custom2					LED 1 Color	Defines the color of the designated LED. LED 1 is oriented at the 12 O'clock position
2	4	4-bit UInteger	0..10					LED 1 Intensity (0-10)	Defines the intensity of the designated LED
3	8	4-bit UInteger	0 = Green, 1 = Red, 2 = Orange, 3 = Amber, 4 = Yellow, 5 = Lime Green, 6 = Spring Green, 7 = Cyan, 8 = Sky Blue, 9 = Blue, 10 = Violet, 11 = Magenta, 12 = Rose, 13 = White, 14 = Custom1, 15 = Custom2					LED 2 Color	Defines the color of the designated LED
4	12	4-bit UInteger	0..10					LED 2 Intensity (0-10)	Defines the intensity of the designated LED
5	16	4-bit UInteger	0 = Green, 1 = Red, 2 = Orange, 3 = Amber, 4 = Yellow, 5 = Lime Green, 6 = Spring Green, 7 = Cyan, 8 = Sky Blue, 9 = Blue, 10 = Violet, 11 = Magenta, 12 = Rose, 13 = White, 14 = Custom1, 15 = Custom2					LED 3 Color	Defines the color of the designated LED
6	20	4-bit UInteger	0..10					LED 3 Intensity (0-10)	Defines the intensity of the designated LED
7	24	4-bit UInteger	0 = Green, 1 = Red, 2 = Orange, 3 = Amber, 4 = Yellow, 5 = Lime Green, 6 = Spring Green, 7 = Cyan, 8 = Sky Blue, 9 = Blue, 10 = Violet, 11 = Magenta, 12 = Rose, 13 = White, 14 = Custom1, 15 = Custom2					LED 4 Color	Defines the color of the designated LED
8	28	4-bit UInteger	0..10					LED 4 Intensity (0-10)	Defines the intensity of the designated LED
9	32	2-bit UInteger	0					Reserved	
10	34	3-bit UInteger	0					Reserved	
11	37	2-bit UInteger	0					Reserved	