

# iVu Plus BCR

## Instruction Manual

Original Instructions  
B\_3084220 Rev. C  
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# Contents

1 Overview of the Sensor	4
1.1 Installation	4
1.1.1 Components	4
1.1.2 Installing and Connecting the Sensor	6
1.1.3 Cable Connections	8
1.1.4 iVu Trigger, Remote Teach, and I/O Waveforms	9
1.2 Live Mode Overview	11
1.2.1 Read/No Read, Pass/Fail, Match/No Match	11
1.2.2 Trigger Modes	11
1.2.3 Compare Data	12
1.2.4 Output 1, Output 2, and Output 3	12
1.2.5 Serial and Ethernet Output	12
1.2.6 Remote Teach	13
2 Home Screen	14
2.1 Display Modes	14
2.1.1 Display/Hide Annotations	14
2.1.2 Inspection Statistics	15
3 Main Menu Reference	18
3.1 Main Menu	18
3.2 System Menu	18
3.2.1 Mode	19
3.2.2 System Configuration	19
3.2.3 System Information	20
3.2.4 Lock device	21
3.2.5 Communications	21
3.2.6 Discrete I/O	26
3.2.7 Display Settings	28
3.2.8 Reboot Sensor	29
3.2.9 Firmware Update	29
3.3 Imager Menu	30
3.3.1 Auto Exposure	30
3.3.2 Exposure	30
3.3.3 Gain	31
3.3.4 Trigger	31
3.3.5 Focus	33
3.3.6 Strobe	34
3.3.7 FOV (Field of View)	35
3.4 Inspection Menu	36
3.4.1 Barcode Menu	36
3.4.2 Properties	42
3.4.3 Stored Inspections	42
3.5 Logs Menu	44
3.5.1 Inspection Logs	44
3.5.2 System Logs	45
3.5.3 Communication Logs	46
4 Setting up an Inspection	47
4.1 Acquiring a Good Image	47
4.2 Setting Up a Barcode Application	49
4.3 Setting up for Data Compare	50
5 Communications Guide	52
5.1 Introduction	52
5.2 iVu Plus Communication Summary of Ethernet and Serial	52
5.2.1 Communication Channels	52
5.2.2 Industrial Ethernet	52
5.2.3 Command Channel	53
5.2.4 Data Export	54
5.2.5 Image Export	54
5.3 Enabling Communications	55
5.3.1 Setting Up Ethernet Communications	55
5.3.2 Setting Up Serial Communications	59
5.4 Testing and Troubleshooting iVu Plus Communications	62
5.4.1 Understanding the Communication Log	62
5.4.2 Ethernet I/O	63
5.4.3 Serial I/O	63

5.5 Command Channel Primer .....	65
5.5.1 Command Channel Commands .....	65
5.5.2 Conventions Used for Examples .....	66
5.5.3 Examples .....	67
5.5.4 Command Channel Reference .....	68
5.5.5 Command Channel Command Status Register .....	73
5.5.6 Command Channel Error Codes .....	73
6 Industrial Ethernet Overview .....	75
6.1 Device Setup .....	75
6.1.1 Set IP Address .....	75
6.1.2 Set Industrial Ethernet Protocol (EIP/Modbus/TCP/PCCC) .....	75
6.1.3 Set Trigger Mode .....	75
6.2 Supported Functions .....	75
6.2.1 iVu Input Values .....	75
6.2.2 iVu Output Values .....	76
6.3 Sensor Operation .....	76
6.3.1 General Command Execution .....	77
6.4 EtherNet/IP .....	77
6.4.1 RSLogix5000 Configuration .....	77
6.4.2 Inputs to iVu (Outputs from PLC) .....	84
6.4.3 Outputs from the iVu (Inputs to the PLC) .....	85
6.4.4 Input and Output Flags Bits .....	87
6.4.5 Configuration Assembly Object .....	87
6.4.6 Data Formats .....	87
6.4.7 Minimum Requested Packet Interval (RPI) Value .....	88
6.5 Modbus/TCP .....	88
6.5.1 Holding Registers .....	88
6.5.2 Output Registers .....	89
6.5.3 Input and Output Coils .....	90
6.6 PLC5 and SLC 5 (PCCC) .....	91
6.6.1 Configuration .....	91
6.6.2 Inputs to iVu (Outputs from PLC) .....	94
6.6.3 Outputs from iVu (Inputs to PLC) .....	94
6.6.4 Input and Output Flags .....	96
6.7 Sample Timing Diagram .....	97
6.8 Command Channel Command Status Register .....	100
6.9 Diagnostic Guide .....	100
6.9.1 Ethernet Diagnostics .....	100
6.9.2 Networking and TCP/IP Diagnostics .....	101
6.9.3 Industrial Protocols Troubleshooting .....	103
6.10 Additional Information .....	105
6.10.1 iVu Command Channel Commands (iVu Command Channel over Industrial EtherNet) .....	105
7 Debugging Inspections .....	110
7.1 iVu Emulator .....	110
7.2 How to Round-Trip Debug Using the Emulator .....	110
7.2.1 How to Debug Using the Emulator from a PC .....	110
7.2.2 How to Debug Using the Emulator from the USB Flash Drive .....	111
8 Updating the Sensor .....	112
8.1 Update Process .....	112
8.2 How to Set or Modify a Device Name .....	112
8.3 How to Reset the Sensor Password .....	113
8.4 How to Use Bitmap Image Files with the iVu Emulator .....	113
9 LED Indicator Troubleshooting .....	115
9.1 Errors .....	115
9.2 Warnings .....	115
10 Product Support and Maintenance .....	116
10.1 Product Support .....	116
10.2 Maintenance .....	116
10.3 Banner Engineering Corp Limited Warranty .....	117

# 1 Overview of the Sensor

The iVu Plus BCR sensor reads a wide variety of barcodes. The package consists of sensor, lighting, lens, and display. Cables and mounting brackets can be ordered for each application. Additionally, other lenses, filters, and external lights are available. Installation, setup, and configuration can be done quickly without requiring a PC.

- No PC required to configure the sensor
- USB port for uploading and downloading of inspections and log files for easy updating and diagnostics
- Image processing expertise is not required
- Integrated or remote color touch screen display
- High speed processing

The iVu Plus BCR reads the following barcode types:

- DataMatrix (ECC 200) barcodes
- QR Code (QR and Micro QR)
- Linear barcodes: Code128, Code39, CODABAR, Interleaved 2 of 5, EAN13, EAN8, UPCE, Postnet, IMB, and Pharmacode

## 1.1 Installation

### 1.1.1 Components

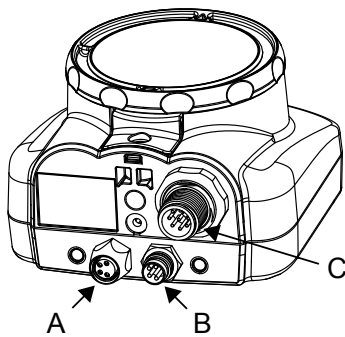
#### iVu with Integrated Display

The iVu Series sensor comes fully assembled with the lens and an integrated ring light if so ordered. The integrated touchscreen display has a plastic cover to protect the display. Remove this cover when setting up the sensor. When the display is not in use be sure to keep the display covered to protect it.

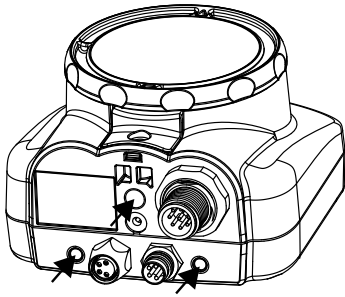
If an integrated ring light is not used, another light source is needed. Various lights are available from Banner. Operating in external trigger mode requires a triggering source (for example, the Banner WORLD-BEAM® QS18VN6D sensor).



- 1 LED - Green: Ready; Red: Error
- 2 LED - Green: Pass; Red: Fail
- 3 Ethernet I/O LED
- 4 Focusing Window
- 5 Focusing Window Locking Clip
- 6 Integrated Display



- A 8-pin Euro-style (M12) female USB Cable Connector
- B I/O Cable Connector
- C 12-pin Euro-style (M12) male Power and I/O Cable Connector



Mounting Bracket Mounting Holes (uses supplied three M4 x 4 mm screws)

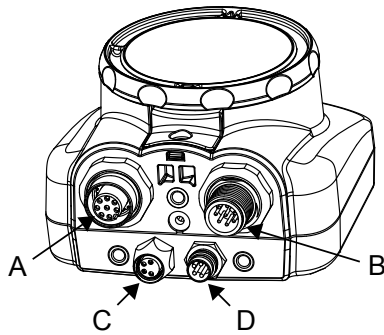
### iVu with Remote Display

The iVu sensor for use with a Remote Display comes fully assembled with the lens and an integrated ring light if so ordered. Although the Remote Display is not required for normal sensor operation, it is needed to set up the sensor and to monitor inspections.

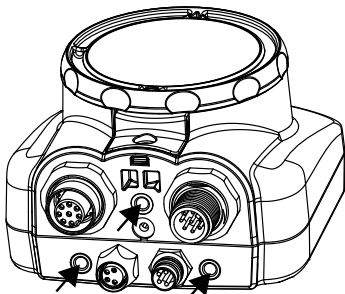
If an integrated ring light is not used, another light source is needed. Various lights are available from Banner. Operating in external trigger mode requires a triggering source (for example, the Banner WORLD-BEAM® QS18VN6D sensor).



- 1 LED - Green: Ready; Red: Error
- 2 LED - Green: Pass; Red: Fail
- 3 Ethernet I/O LED
- 4 Focusing Window
- 5 Focusing Window Locking Clip



- A Remote Display connector
- B Power and I/O Cable connector
- C USB connector
- D Ethernet connector



Mounting Bracket Mounting Holes (uses supplied three M4 x 4 mm screws)

## 1.1.2 Installing and Connecting the Sensor

The iVu Plus BCR sensor requires a bracket for mounting. Three brackets are available from Banner. The brackets allow the sensor to be mounted either perpendicular to the part or at an adjustable angle.

Thread three M4 x 4mm screws through the bracket into the mounting holes in the bottom of the sensor. Tighten all three screws.

Table 1: iVu Brackets

SMBIVURAL	SMBIVURAR	SMBIVUU
		


## Installing a Filter on iVu Series Sensors

### Installing a Filter on the Micro Video Lens Model

To install a filter on the iVu Series sensor with Micro Video Lens, use the illustration as a guide and follow the steps listed below.



**CAUTION:** Failure to follow these instructions may cause damage to your iVu Series sensor.

Micro Video Lens Models	
	A Lens
	B Focusing Window
	C Locking Clip
	D Locking Screw
	E Filter Cap
	F Filter

1. Remove the Focusing Window locking screw (D) using the 1/16 in. hex key.



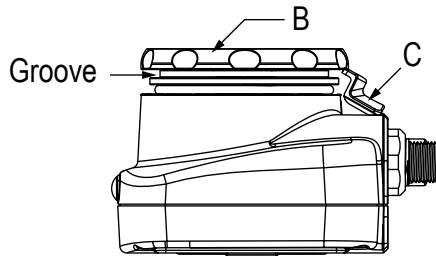
**NOTE:** The Locking Clip (C) inserts in a groove near the top of the Focusing Window (B). When removing the window, the Locking Clip will be loose. Be careful not to lose the clip while removing the window.

2. Unscrew the Focusing Window by turning it clockwise approximately 5 complete turns or until the Focusing Window disengages from the light/lens assembly.



NOTE: The light/lens assembly may include an integrated ring light or a blank disk if an integrated ring light is not used. Be careful that the light/lens assembly does not pull out when removing the Focusing Window. Give a slight tug on the Focusing Window when you think you've unscrewed it far enough. If the lens assembly moves with the window, continue to rotate the window clockwise until the lens assembly does not move.

3. Set the Focusing Window aside. Be careful not to get any debris on the window's O-ring.
4. If present, remove the protective covering on the filter.
5. Place the filter into the Filter Cap and press the cap onto the lens.
6. After the filter is installed, place the Focusing Window back into the housing while inserting the Locking Clip into the groove as shown.



7. Press the Focusing Window onto the housing to make sure that it seats correctly (no gap between the window and housing). Rotate the window counter-clockwise at least two turns.
8. Replace the locking tab screw but do not tighten until you have set up and focused the sensor again.

Installing a Filter on the C-Mount Lens Model

To install a filter on the iVu Series sensor with C-Mount Lens, use the illustration as a guide and follow the steps listed below.



CAUTION: Failure to follow these instructions may cause damage to your iVu Series sensor.

C-Mount Lens Models	
	A C-Mount Lens
	B Lens Enclosure
	C Retainer Ring (optional)
	D Filter (optional)
	E Filter Retainer Ring Tool
NOTE: Filter Kits are available separately.	

1. Remove the Lens Enclosure and Lens.
2. Install filter behind the retainer ring. Make sure it is fully seated.
3. Using the provided retainer ring tool, thread the retainer ring into the sensor until it firmly seats the filter.
4. Replace the Lens and Lens Enclosure on the camera.



**CAUTION: Electrostatic Discharge**

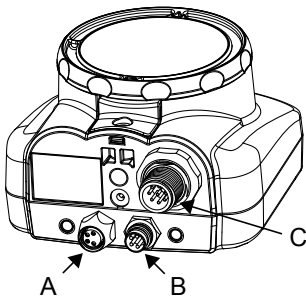
Avoid the damage that electrostatic discharge (ESD) can cause to the Sensor.

Always use a proven method for preventing electrostatic discharge when installing a lens or attaching a cable.

### 1.1.3 Cable Connections

#### Cable Connections for Integrated Display

The cable connections on the iVu Plus with integrated display are shown below, and power I/O connections (C) are defined in the Power I/O Connections table below.



- A USB Connector
- B Ethernet Connector
- C Power I/O Connector



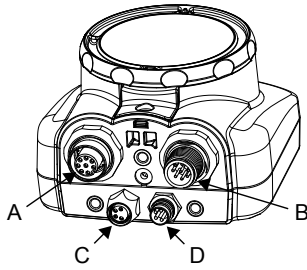
NOTE: Micro video lens model shown, C-Mount model connections are identical.

Power I/O Connections			
Pin #	Wire Color	Description	Direction
1	White	Output 1	Output
2	Brown	10-30V dc	Input
3	Green	Output 2	Output
4	Yellow	Strobe Out (5V dc only)	Output
5	Gray	Remote Teach	Input
6	Pink	External Trigger	Input
7	Blue	Common (Signal Ground)	Input
8	Red	Ready	Output
9	Orange	Output 3	Output
10	Light Blue	RS-232 TX	Output
11	Black	RS-232 Signal Ground	Output
12	Violet	RS-232 Rx	Input

#### Cable Connections for Remote Display

The cable connections on the iVu Plus with remote display are shown below, and power I/O connections (B) are defined in the Power I/O Connections table below.





- A Remote Display Connector
- B Power I/O Connector
- C USB Connector
- D Ethernet Connector



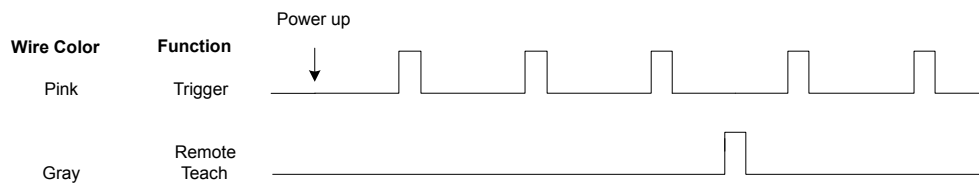
NOTE: Micro video lens model shown, C-Mount model connections are identical.

Power I/O Connections			
Pin #	Wire Color	Description	Direction
1	White	Output 1	Output
2	Brown	10-30V dc	Input
3	Green	Output 2	Output
4	Yellow	Strobe Out (5V dc only)	Output
5	Gray	Remote Teach	Input
6	Pink	External Trigger	Input
7	Blue	Common (Signal Ground)	Input
8	Red	Ready	Output
9	Orange	Output 3	Output
10	Light Blue	RS-232 TX	Output
11	Black	RS-232 Signal Ground	Output
12	Violet	RS-232 Rx	Input

### 1.1.4 iVu Trigger, Remote Teach, and I/O Waveforms

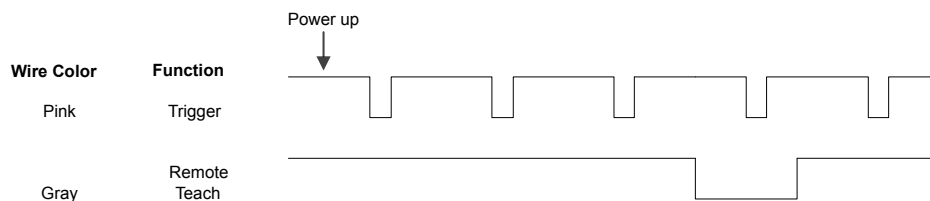
The iVu has two input signals—Trigger and Remote Teach. The default setting is to detect the low to high transition. This setting can be changed in the Main Menu > System > Discrete I/O > Input Polarity screen on the sensor.

#### PNP (Low-to-High) Trigger and Remote Teach Input Waveforms



The sensor triggers from low to high, and Remote Teach behaves electrically like trigger.

#### NPN (High-to-Low) Trigger and Remote Teach Input Waveforms

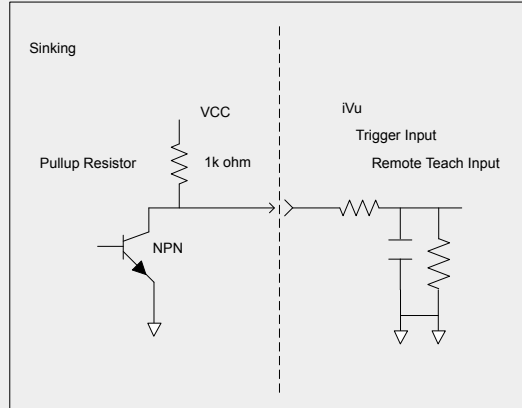


The sensor triggers from high to low, and Remote Teach behaves electrically like trigger.



**NOTE:** If the device used to trigger or remote teach the iVu Plus BCR is a sinking device, these are the options regarding the use of a pull-up resistor:

Option 1: Put a pull-up resistor, rated approximately 1k ohm, between the sensor's positive (+) voltage and the sensor's input as shown below.



Option 2: Enable the Input Pullup in the iVu Plus BCR software (Main Menu > System > Discrete I/O > Input Pullup).

### iVu Output Waveforms

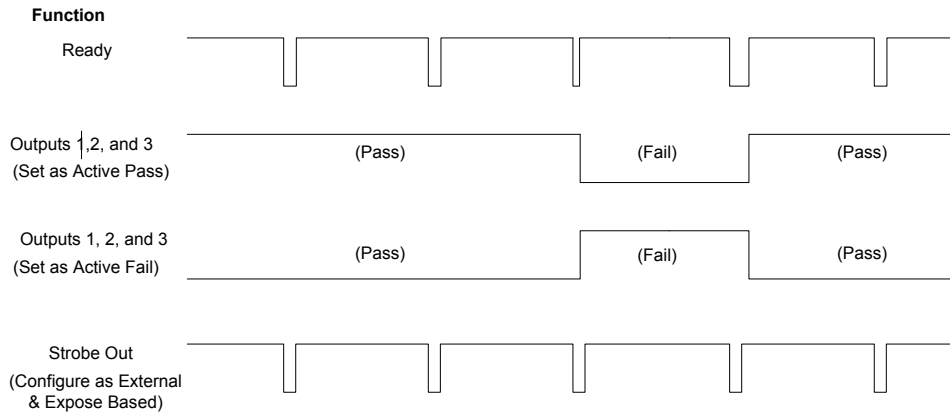


Figure 1. PNP Outputs

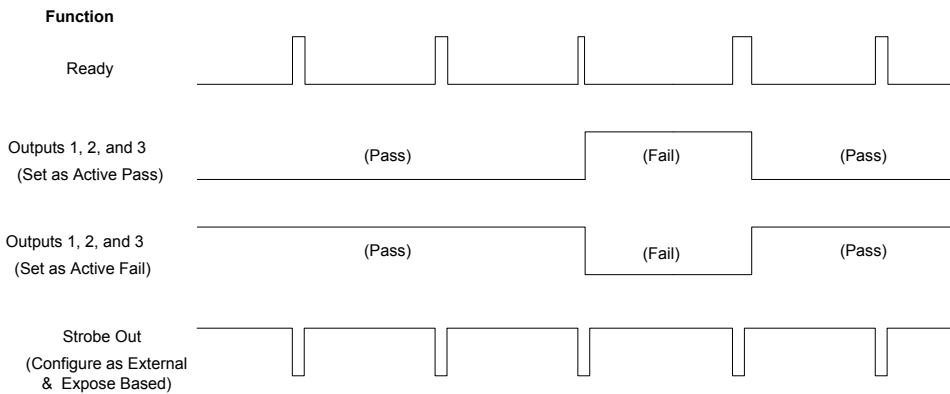
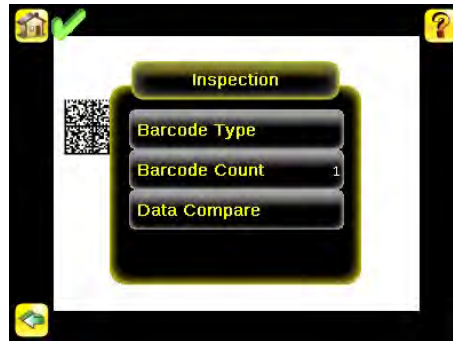


Figure 2. NPN Outputs

## 1.2 Live Mode Overview

The iVu Plus BCR can be configured to evaluate one or more of the supported barcode types and can look for a specific number of barcodes from 1 to 10. The barcode types are selected on the integrated touch screen by accessing Main Menu > Inspection > Barcode > Barcode Type. The barcode count is selected on the touch screen by going to Main Menu > Inspection > Barcode > Barcode Count.



### 1.2.1 Read/No Read, Pass/Fail, Match/No Match

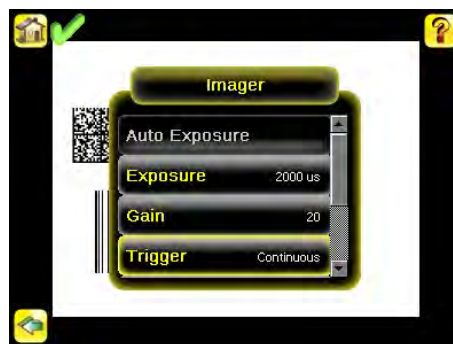
- A Read condition occurs when the configured number of barcodes are found in a scan. These barcodes must be error-free.
- A No Read condition occurs when the configured number of barcodes are not found in a scan.
- If the sensor is configured where Data Compare is disabled, Pass and Fail are the same as Read and No Read.
- If the sensor is using the Data Compare feature, Pass indicates that a good barcode was found and the data compared.
- If the sensor is using the Data Compare feature, Fail indicates that either no good barcode was found or the data did not compare.
- A Match condition occurs when the required number of barcodes are found and the compare is successful.
- A No Match condition occurs when the required number of barcodes are found, but the compare is not successful.

### 1.2.2 Trigger Modes

The iVu Plus BCR has five trigger modes that determine how the sensor captures and processes images:

- External - Single
- Continuous
- External - Gated
- Command
- Industrial Ethernet Only

You can select one of the trigger modes by accessing Main Menu > Imager > Trigger on the iVu touch screen display. [Trigger](#) on page 31 describes these trigger modes in more detail.



### 1.2.3 Compare Data

The iVu Plus BCR has a data compare feature for comparing read barcode data against reference data. Data can be manually entered by navigating to the Main Menu > Inspection > Barcode > Data Compare > Set Data screen. Data of up to 3200 characters can be entered. Additionally, the data compare feature provides for masking characters within the data.

There are two other ways to enter compare data:

- Importing the last read data while viewing the Set Data screen. The new data is effective on the first trigger that occurs after this action.
- Using Remote Teach.

When a Remote Teach occurs, the data of the first read barcode is saved as Data Compare input. Inspections executed on the next trigger uses the new data for comparison with subsequently read barcodes. If the previous input data contained any masked characters, Remote Teach retains the masked characters only if the new data is of the same length as the previous input data. If the length does not match, masking is removed.

The sensor tries to compare full length of this string with the data read from the barcode. If not equal, the inspection is marked as Fail.



NOTE: If the sensor reads more than one barcode in the field of view, only the first barcode data that the sensor reads can be compared.

### 1.2.4 Output 1, Output 2, and Output 3

The sensor has three output signals that you can configure for Pass, Fail, Read, No Read, Match, No Match, System Error, and Missed Trigger. The default settings are Pass for Output 1, Fail for Output 2, and Pass for Output 3.



NOTE: For all outputs, the default setting is Latched, which means that the signal is active until the results of an inspection cause a change in the signal output. If Pulsed is selected, the default pulse width is 50 ms.

### 1.2.5 Serial and Ethernet Output

The iVu Plus communicates with other devices via Ethernet or a UART serial communications port (RS-232). In order to establish an Ethernet connection to the sensor, the external device must be configured with the correct IP address and TCP port to communicate. To use the serial communications connection, port settings for baud rate, data bits, parity, and stop bits must be configured on the iVu Plus to match the settings of the external device.

The iVu Plus BCR RS-232 port or ethernet port can be used to output barcode data to other applications. To access the Data Export screen, go to Main Menu > System > Communications > Data Export. The user can enable or disable this feature. When enabled:

- if the sensor is configured for either External-Single or External-Gated trigger modes, every trigger results in the transmission of output data (if the sensor does not successfully read a barcode, the output will be NO\_READ).
- if the sensor is configured for Continuous trigger mode, the sensor transmits output barcode data only upon a successful read.

To access the Serial Output screen, go to Main Menu > System > Communications > Serial I/O.

When RS-232 serial output is enabled, the user can configure:

- Serial Port Settings (listed below)
- Type of Data to Export (listed below)
- Output Format (listed below)

To access the Ethernet Output screen, go to Main Menu > System > Communications > Ethernet I/O.

When ethernet output is enabled, the user can configure:

- IP Address, Port number, Subnet Mask, and Gateway
- Type of Data to Export (listed below)
- Output Format (listed below)

## Type of Data to Export:

- Pass/Fail Output
- Inspection Name
- Barcode Count
- Data Length
- Symbol Type
- Barcode Data
- Frame Number
- Inspection Time (ms)

## Serial Port Settings:

- Baud Rates
- Start Bits
- Stop Bits
- Data Bits
- Parity Control

## Output Format:

- Start String
- Delimiter
- End String

## 1.2.6 Remote Teach

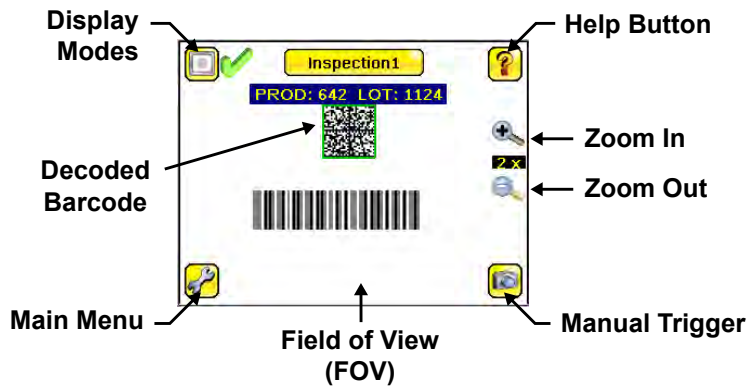
The Remote Teach function is a method of remotely updating inspection parameters while the iVu sensor is running. The sequence of events for executing a Remote Teach are:

1. With the sensor Ready (see [Installation](#) on page 4), pulse the Remote Teach line.
2. The sensor recognizes that the Remote Teach line has been pulsed and waits for the next valid trigger.
3. At the next valid trigger, Ready goes inactive (the Green Ready LED shuts OFF), and the sensor acquires a new image.

When a Remote Teach occurs, the data of the first read barcode is saved as Data Compare input. Inspections executed on the next trigger uses the new data for comparison with subsequently read barcodes. If the previous input data contained any masked characters, Remote Teach retains the masked characters only if the new data is of the same length as the previous input data. If the length does not match, masking is removed.

## 2 Home Screen

The Home screen on the iVu Series sensor display is used to monitor inspections and to configure the sensor. Normally, the part being inspected is centered on the screen.



### 2.1 Display Modes

In the upper left of the screen is an icon for accessing different Display Modes:

- Display Annotations
- Hide Annotations
- Display Statistics.

#### 2.1.1 Display/Hide Annotations

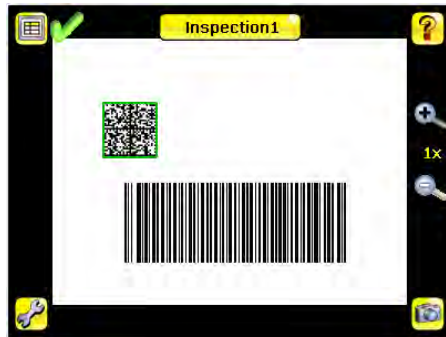
Click the icon in the upper-left of the screen to display annotations. When annotations are on, the display shows the data the sensor has read.




If the sensor reads more than one barcode in the field of view (FOV), in addition to the read data, the display indicates the index of each read barcode. In the example below, the top barcode is 1 and the bottom barcode is 2. It is important to note that, if the sensor reads more than one barcode, only the first barcode data (index #1) can be compared or used in a remote teach operation.



Click the icon in the upper-left of the screen to hide annotations.



## 2.1.2 Inspection Statistics

To access the Inspection Statistics, click the Display mode icon .

The Inspection Statistic mode has three pages:

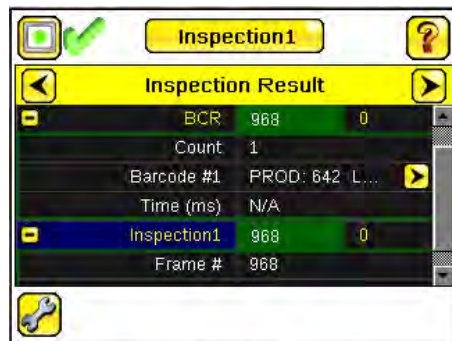
- History
- Inspection Result
- Inspection Inputs

Click the arrows to access the other pages.

### Inspection Results

The Inspection Result screen shows data about the current inspection being viewed, including the

- Barcode (BCR) Pass and Fail count
- Count of barcodes found in current image
- Data for each barcode found
- Execution time of Barcode sensor
- Frame Number (total number of objects since bootup)
- Execution time of entire inspection



### Barcode Viewer

To view detailed information about a particular barcode, click the arrow next to the Barcode # to access the Barcode Viewer screen.

If Data Compare is disabled, The Barcode Viewer screen shows a single text box indicating the index number of the barcode and the data the sensor is reading. The data is displayed in yellow.



If Data Compare is enabled and the barcode is the first one, there are two text boxes. The upper one displays the data read from the barcode, and the lower text box shows the data from the Data Compare screen. The sensor does a position-by-position match and the characters that match are in yellow and mismatches are in red.



### History

The History screen shows inspection history from sensor reboot, or the last time the statistics were reset, including:

- Total count barcode (BCR) sensor Passed and Failed
- Count Range for barcodes found when running this inspection
- Execution Time Range for Barcode sensor
- Pass and Fail count for this inspection (for example, Inspection1)
- Total Frames (images) captured for this inspection
- Missed triggers

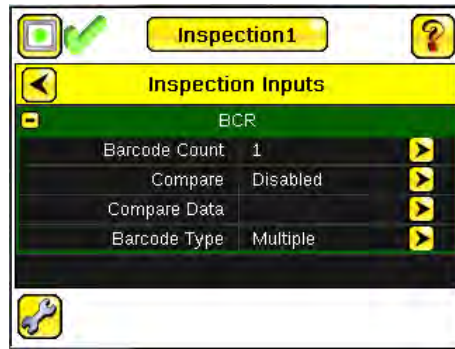
Click the Reset button to reset statistics.

The table contains history of each sensor in the inspection. Data of each sensor can be expanded or collapsed as required using the +/- . The green area indicates the sensor passed, red indicates fail. If a sensor fails, an icon besides the sensor name will indicate the reason of failure.

### Inspection Inputs

The Inspection Input page has the sensor settings. Use this page to verify what inspection input settings were used on the latest inspection. Click + to expand the inspection information, or – to collapse the inspection information. Use the right arrows as a shortcut go to a sensor setting screen.

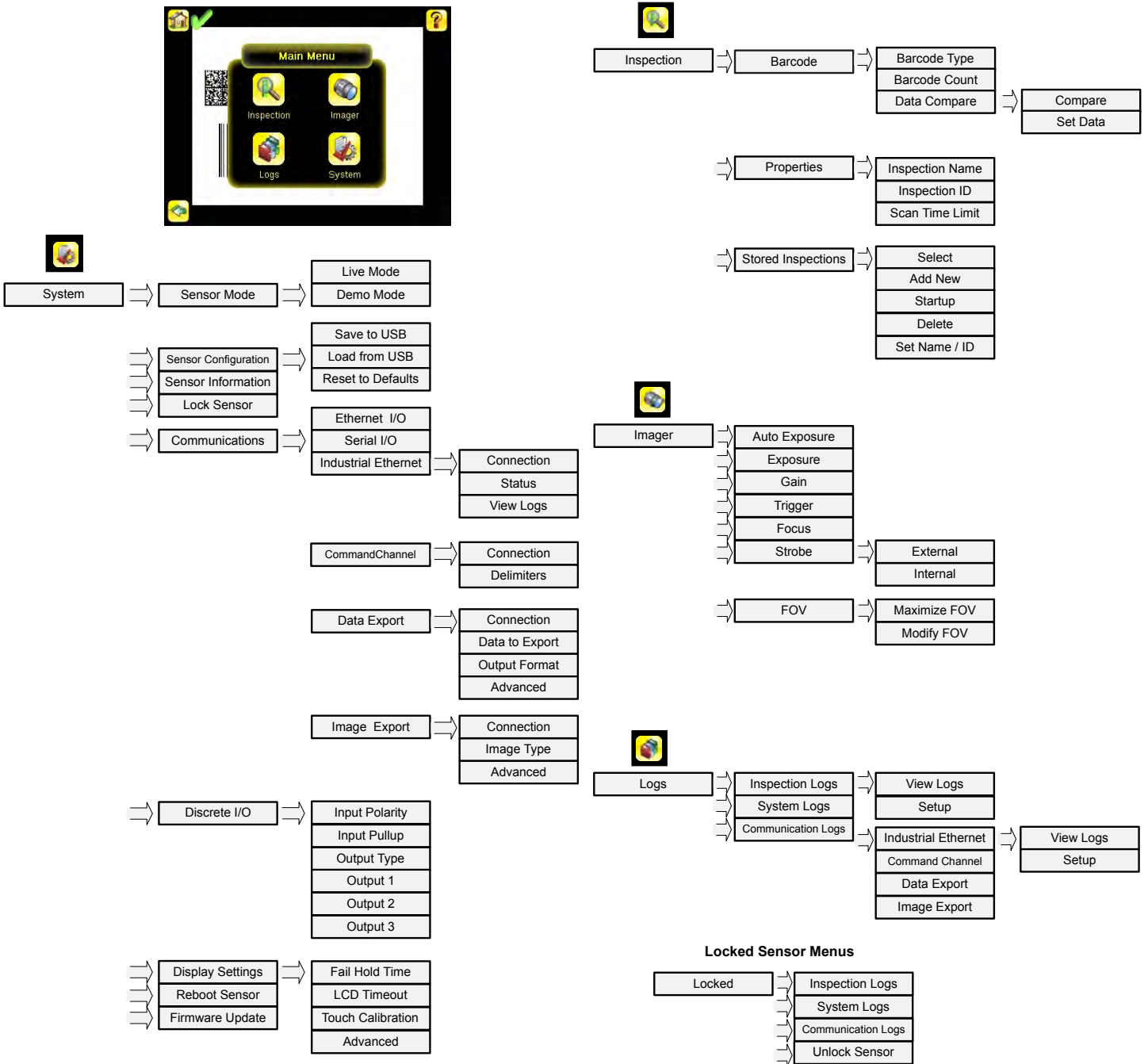




# 3 Main Menu Reference

## 3.1 Main Menu

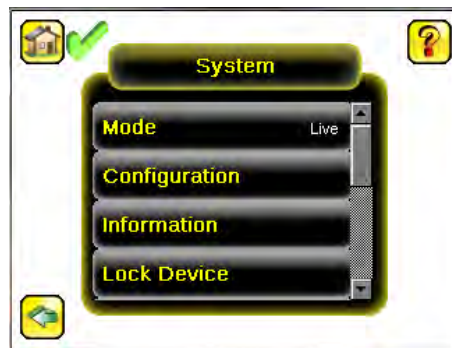
The Main Menu has four sections. Inspection—to modify inspection settings. Imager—to run the Auto Exposure routine and to make adjustments to functions like exposure, gain, and strobe. System—to set output signals, communication channel parameters and to manage the device. Logs—to configure and view System and Inspection Logs.



## 3.2 System Menu

Main Menu > System

The System menu icon is on the Main Menu, and is used to manage the sensor. The System menu provides for selecting Sensor Mode, updating sensor firmware, backing up and restoring sensor Configuration, and other general system-level operations.



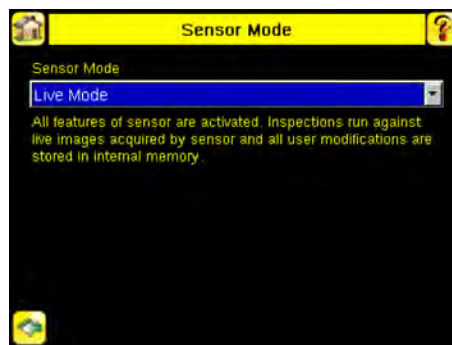
### 3.2.1 Mode

Main Menu > System > Mode

The sensor has two operating modes:

- Live Mode, which is the normal operating mode where the sensor captures live images, scans, and verifies barcodes
- Demo Mode, where inspections are run on stored images and inspection parameters.

The first time the device is powered up it starts in Demo Mode. Demo Mode uses stored images and inspection parameters that demonstrate how the sensor is set up without having to worry about focus, lighting, or triggers. In this mode, practice making adjustments while observing how the adjustments affect the results. To exit Demo Mode go to Main Menu > System > Mode and select Exit Demo Mode. Upon exit, the sensor reboots into its normal operating mode with default settings.



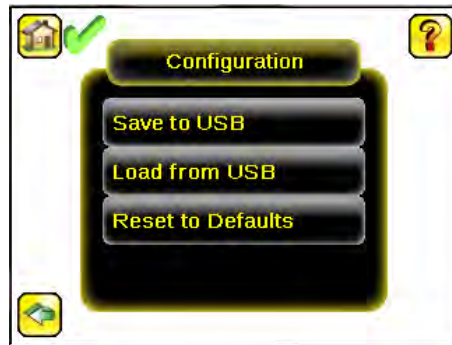
NOTE: Switch between Live Mode and Demo Mode any time by going to Main Menu > System > Mode.

### 3.2.2 System Configuration

Main Menu > System > Configuration

The Sensor Configuration menu options are:

- Save sensor Configuration to the USB flash drive
- Load sensor Configuration from the USB flash drive
- Reset the sensor Configuration to defaults



### Save to USB

Main Menu > System > Configuration > Save to USB

The Save to USB screen allows the sensor Configuration to be saved to a USB flash drive. The saved configuration information can be used as a backup or as a way to clone configuration information for other sensors.



NOTE: On the Emulator, this option is Save Configuration.

### Load from USB

Main Menu > System > Configuration > Load from USB

The Load from USB screen allows the sensor Configuration to be restored from a USB flash drive. This operation removes all existing inspections and replaces them with inspections contained in the configuration file on the USB flash drive.

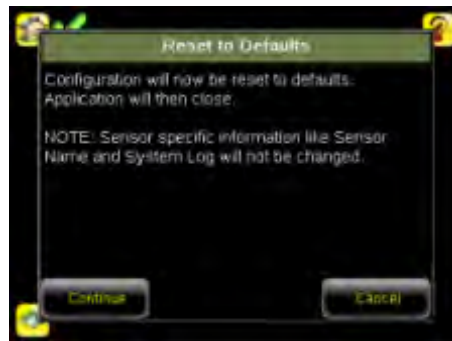


NOTE: On the Emulator, this option is Load Configuration.

### Reset to Defaults

Main Menu > System > Configuration > Reset to Defaults

Resets all sensor configurations to the factory defaults. This operation will remove all existing inspections and replace them with factory default settings.



## 3.2.3 System Information

Main Menu > System > Information

The Information screen displays the following sensor information:

- Serial Number
- Firmware Version
- Boot Number
- Up Timer—the time elapsed since last boot of the sensor
- Hour Count—the total hours of operation in the sensor's lifetime

- Model Number
- Device Name

Click the right-arrow next to the Sensor Name field to display a software keyboard that allows you to change the Sensor Name.

### 3.2.4 Lock device

Main Menu > System > Lock device

This option provides for locking the sensor to prevent accidental modification of settings. When locked, the sensor only provides access to pass/fail statistics, as well as the ability to view logs and to save them to a USB device. A lock icon in the upper left corner of the sensor display indicates that the sensor is locked. Note that the sensor can be locked with or without a password. If a password is not used, unlock the sensor by clicking on the Unlock device menu. When a password is used, it must be 4 digits entered using the software keypad. If the password is lost, use the Password Reset Utility software provided on the CD to obtain a Reset Key.



NOTE: This menu option is not available in the Emulator.

### 3.2.5 Communications

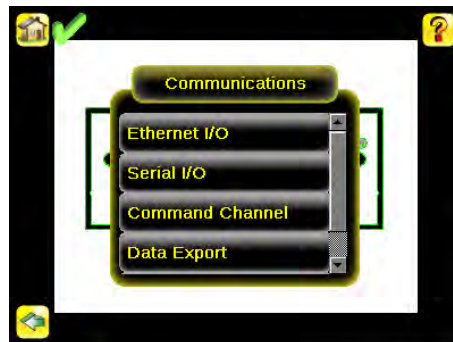
Main Menu > System > Communications

The Communications menu is used to configure the serial and ethernet I/O channel. There are six menu options:

- Ethernet I/O for configuring the Ethernet port
- Serial I/O for configuring the Serial port
- Industrial Ethernet settings
- Command Channel for sending commands to get specific data through Serial or Ethernet channels.
- Data Export Channel for enabling or disabling the channel for data export only
- Image Export Channel for enabling or disabling the channel for image export only



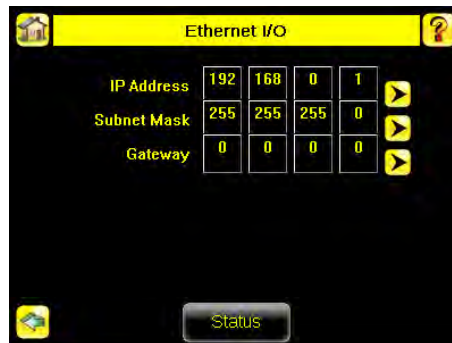
NOTE: Serial I/O can be configured either for Data Export or Command Channel. Image Export is only available on Ethernet.



### Ethernet I/O

Main Menu > System > Communications > Ethernet I/O

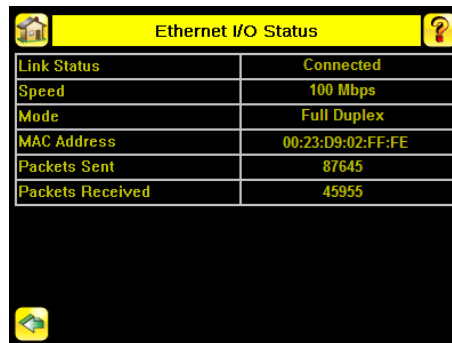
The sensor's Ethernet communications can be used to send data out the Ethernet port as part of an inspection, and remote devices can communicate with the sensor. The Ethernet I/O screen is where IP Address, Subnet Mask, and Gateway settings are configured. Use the expand arrow next to each field to display a software keypad to enter values for each field. Click Status at the bottom of the screen to verify communications as you connect to remote devices.



### Ethernet I/O Status

Main Menu > System > Communications > Ethernet I/O > Status

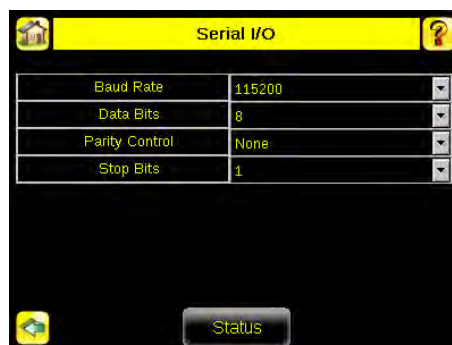
The Ethernet I/O Status screen can be used to verify that the Ethernet wiring has been correctly set up. In addition to determining if the link has been established, incoming and outgoing traffic can be monitored.



### Serial I/O

Main Menu > System > Communications > Serial I/O

Set Serial I/O settings for Baud Rate, Data Bits, Parity Control and Stop Bits on this screen. Clicking Status displays recent bytes transmitted through this channel.



### Port Status

Main Menu > System > Communications > Serial I/O > Status

The Port Status screen can be used to ensure data is entering and exiting the sensor. This can be useful for debugging issues such as improper wiring, mismatched baud rates, or other serial I/O issues.



## Industrial Ethernet

Main Menu > System > Communications > Industrial Ethernet

The iVuPlus device can be controlled or monitored over Industrial Ethernet using Ethernet/IP, Modbus/TCP or PCCC protocols. This document will help you to set up the iVu Plus in the desired configuration and provide you with information you will need to connect to the master device (PLC, HMI, etc.).

### Connection

Main Menu > System > Communications > Industrial Ethernet > Connection

The Connection screen is used to enable either Modbus or EIP/PCCC protocols on Industrial Ethernet channel. Select 'Disable' to completely disable Industrial Ethernet channel.

### Status

Main Menu > System > Communications > Industrial Ethernet > Status

The status screen displays information about the current connection. This information is protocol specific.

### View Logs

Main Menu > System > Communications > Industrial Ethernet > View Logs

This screen displays the list of recent events on Industrial Ethernet channel. Detailed logging can be selected under Setup when troubleshooting.

## Command Channel

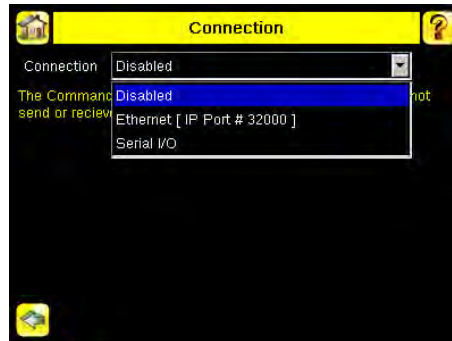
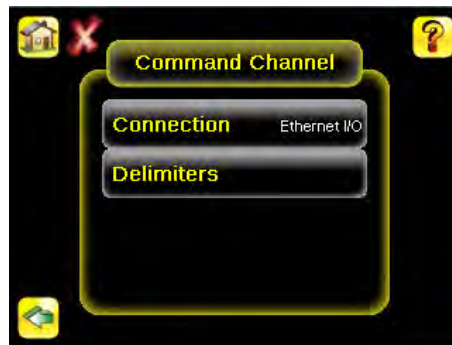
Main Menu > System > Communications > Command Channel

The iVu command channel is a bi-directional communication protocol that currently supports ASCII via the RS-232 serial interface or ethernet interface, and enables other devices to remotely control the iVu sensor and to access sensor results.

### Connection

Main Menu > System > Communications > Command Channel > Connection

The Connection screen is used to enable or disable the Command Channel.



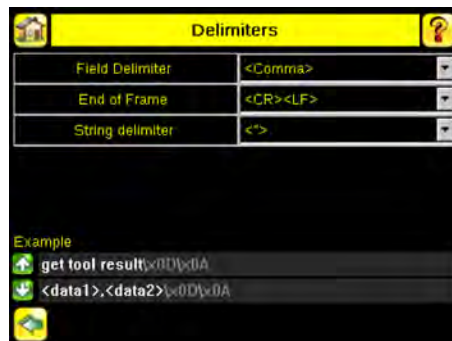
### Delimiters

Main Menu > System > Communications > Command Channel > Delimiters

In the Delimiters screen, there are three delimiter options that you can set:

- Field Delimiter, which determines what is used to separate data that the sensor is sending out to a remote device.
- End of Frame, which determines the delimiter used to indicate the end of a frame.
- String Delimiter, which determines what is used to enclose a string field during both input and output operations.

Use the drop-down lists to select the appropriate delimiter. The example at the lower part of the screen displays how the data will look in the output or input streams.



### Data Export

Main Menu > System > Communications > Data Export

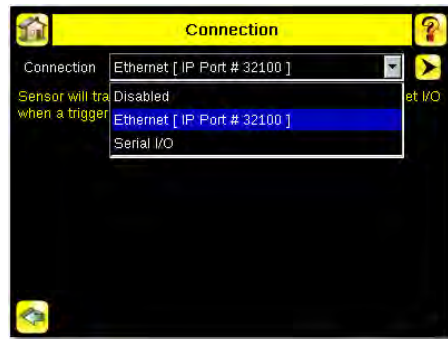
When the Data Export is enabled, the sensor will transmit selected inspection data when triggered.

#### Connection

Main Menu > System > Communications > Data Export > Connection

The Connection screen is used to enable or disable the Data Export Channel.





### Data To Export

Main Menu > System > Communications > Data Export > Data To Export

The options in the Data To Export screen are used to determine what barcode data is exported via the serial port.



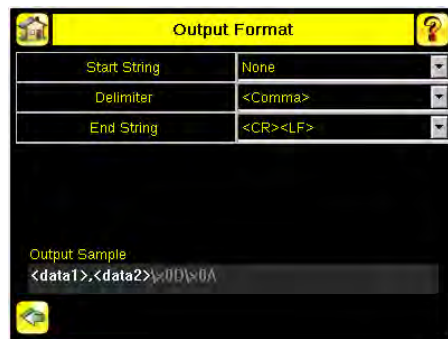
NOTE: Grab the edge of the Data to Export menu and pull down to allow all information to show.



### Output Format

Main Menu > System > Communications > Data Export > Output Format

In the Output Format screen, use the drop-down lists to select Start and End Strings as well as a Delimiter. In the field at the bottom of the screen is an example of how the data will look when it is output.



### Data Export Advanced

Main Menu > System > Communications > Data Export > Advanced

During the Data and Image export operation, the sensor's output channels might become full. This can occur if the sensor is producing export data (frames) faster than the data can be exported from the device or faster than the client is reading the channel export data (due to bandwidth limitations).

This setting affects how the sensor will behave in this situation.

Select 'Hold READY' to ensure that all frames are transmitted. In this case, the READY signal will remain inactive (sensor is busy) until the new frame has been added to the channel for transmission. Triggers might be missed during this time.

Select 'Do not hold READY' to cause the sensor to discard the new frame if the channel is full and thus activate the READY signal immediately after the current inspection is complete. In this case, the discarded frames will not be transmitted.



NOTE: This setting affects both the Data Export Channel and Image Export Channel.

## Image Export

Main Menu > System > Communications > Image Export

When the Image Export Channel is enabled, the sensor will transmit the acquired image on every trigger. The image is transmitted as a bitmap (BMP) file. This operation is only available over Ethernet I/O.

### Connection

Main Menu > Communications > Image Export > Connection

The Connection screen is used to enable or disable the Image Export.

### Image Type

Main Menu > System > Image Export > Image Type

Choose between JPEG or BMP format for the exporting image file.

### Image Export Advanced

Main Menu > System > Communications > Image Export > Advanced

During the Data and Image Export operation, the sensor's output channels might become full. This can occur if the sensor is producing export data (frames) faster than the data can be exported from the device or faster than the client is reading the channel export data (due to bandwidth limitations).

This setting affects how the sensor will behave in this situation.

Select 'Hold READY' to ensure that all frames are transmitted. In this case, the READY signal will remain inactive (sensor is busy) until the new frame has been added to the channel for transmission. Triggers might be missed during this time.

Select 'Do not hold READY' to cause the sensor to discard the new frame if the channel is full and thus activate the READY signal immediately after the current inspection is complete. In this case, the discarded frames will not be transmitted.

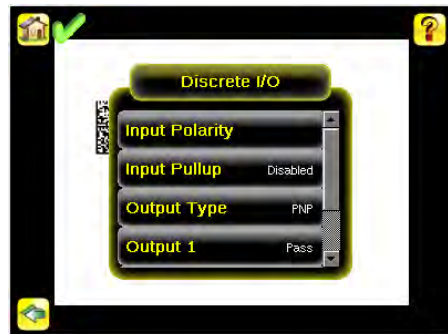


NOTE: This setting affects both the Data Export Channel and Image Export Channel.

## 3.2.6 Discrete I/O

Main Menu > System > Discrete I/O

The Discrete I/O options are used to adjust iVu input and output settings.



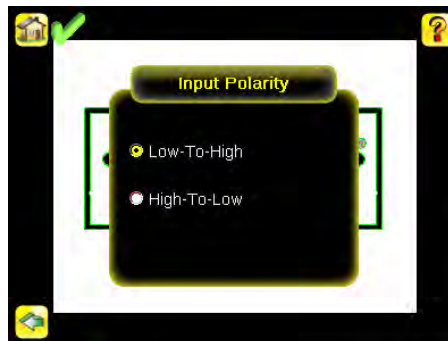
## Input Polarity

Main Menu > System > Discrete I/O > Input Polarity

The iVu has two input signals—Trigger and Remote Teach. Both of these signals are edge sensitive. The operation of these signals is dependent on the Input Polarity setting.

- Low To High - The Trigger and Remote Teach are detected on a low to high transition of the signal.
- High To Low - The Trigger and Remote Teach are detected on a high to low transition of the signal.

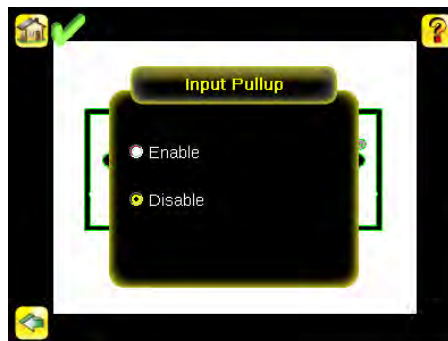
The default setting for a PNP sensor is Low To High, and for an NPN sensor it is High To Low. The user can change the setting on the Input Polarity screen.



## Input Pullup

Main Menu > System > Discrete I/O > Input Pullup

By default, the Input Pullup is disabled. If the device used to trigger and remote teach the iVu sensor is a Sinking device (NPN) then you will only need to enable Input Pullup here if that device does not have its own pullup resistor. Otherwise, this should be disabled.



## Output 1

Main Menu > System > Discrete I/O > Output 1

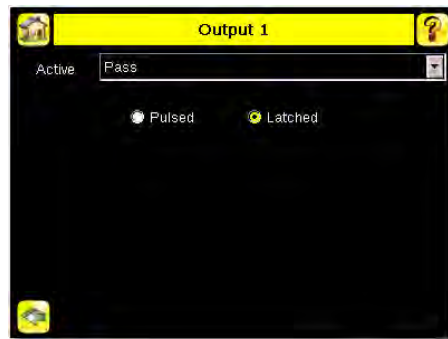
Output 1 can be configured for Pass, Fail, Read, No Read, Match, No Match, Missed Trigger, or System Error.

- A Read condition is when the configured number of barcodes are found in a scan. These barcodes must be error-free.
- A No Read condition is when the configured number of barcodes are not found in a scan sequence. This will not occur in Continuous Scan mode.
- If Data Compare is disabled, Pass and Fail are the same as Read and No Read.
- If the sensor is using Data Compare, Pass indicates that a good barcode was found, and the data compared.
- If the sensor is using Data Compare, Fail indicates that either no good barcode was found, or the data did not compare.
- A Match condition occurs when the required number of barcodes are found and the compare is successful.
- A No Match condition occurs when the required number of barcodes are found, but the compare is not successful.
- A Missed Trigger condition occurs when a trigger is received while sensor is busy inspecting the previous image. This output signal will be set to active state. This signal will be reset up on resetting the 'History' on the statistics page.
- A System Error condition occurs when a fatal error is detected on the sensor. This output signal will be set to active state. This signal can be reset upon resetting the 'History' on the statistics page, or executing a 'ClearSystemError' command through command channel.

The default setting is Pass and Latched for Output 1. If Pulsed is selected, the default Pulse width is 50 ms.



NOTE: For Latched the signal is active until the results of an inspection cause a change in the signal output.



## Output2 and Output3

Main Menu > System > Discrete I/O > Output 2

Main Menu > System > Discrete I/O > Output 3

Output 2 and Output 3 can be configured in a similar way as Output 1.

The default setting for Output 2 is Fail and Latched. The default setting for Output 3 is Pass and Latched.

## Output Type

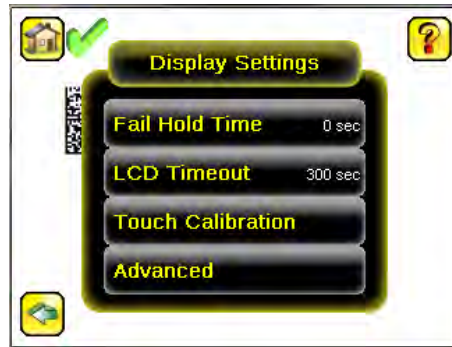
Main Menu > System > Discrete I/O > Output Type

Select NPN to configure the sensor's outputs to sink current. Select PNP to configure the sensor's output for source current.

## 3.2.7 Display Settings

Main Menu > System > Display Settings

The Display Settings menu is for setting the Fail Hold Time, LCD Timeout, and doing a Touch Screen Calibration. Display optimization can be enabled in the Advanced menu.



## Fail Hold Time

Main Menu > System > Display Settings > Fail Hold Time

The Fail Hold Time determines how long a failed image is displayed on the LCD so that you can see what failed. The sensor will continue to process any triggers and the inspection will continue normally. This time delay is just for the screen. You can set this parameter from 0 to 3600 seconds using the slider at the bottom of the screen.

## LCD Timeout

Main Menu > System > Display Settings > LCD Timeout

The LCD screen dims after a user-selectable period when the device is not being used. Use the arrow keys or slide the bar at the bottom of the screen to set the LCD screen time out.



NOTE: This screen is not available in the Emulator.

## Touch Calibration

Main Menu > System > Display Settings > Touch Calibration

Touchscreen Calibration may be necessary if the software does not correctly respond when an icon on the screen is pressed. The calibration routine aligns the touch screen's coordinates to the display behind it. Be sure to follow the prompts on the screen when executing the Touchscreen Calibration function.



NOTE: This screen is not available in the Emulator.

## Advanced

Main Menu > System > Display Settings > Advanced

The Advanced Display screen allows you to enable the Optimize Display Response option. This feature helps to make the display more responsive when the sensor is busy (either inspection times are long and/or no idle time exists between inspections). Disable this feature if Missed Triggers occur due to touchscreen presses. With this setting disabled, the display may become sluggish when the sensor is busy.

### 3.2.8 Reboot Sensor

Main Menu > System > Reboot Sensor

The Reboot Sensor screen allows you to force a reboot of the sensor.



NOTE: This option is not available on the Emulator.

### 3.2.9 Firmware Update

Main Menu > System > Firmware Update

The Firmware Update screen is used to load the latest sensor firmware. The Firmware Update screen lists the firmware versions it finds in the BANNER\FIRMWARE folder on the USB flash drive. When you receive a firmware update from Banner Engineering, be sure to put it in the BANNER\FIRMWARE folder on the USB flash drive.

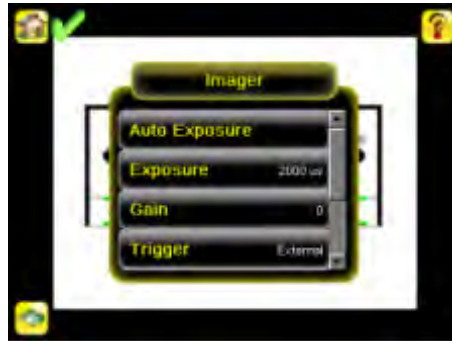


NOTE: The Firmware Update menu is not available in the Emulator.

### 3.3 Imager Menu

Main Menu > Imager

The Imager menu icon is on the Main Menu, and lists parameters that affect the characteristics of the captured image. The Imager menu is used to access the Auto Exposure routine, manually adjust Exposure and Gain, set Trigger and Strobe options as well as the size of the field of view (FOV).



#### 3.3.1 Auto Exposure

Main Menu > Imager > Auto Exposure

Auto Exposure optimizes the exposure time and gain for the current lighting conditions. Multiple triggers are required to complete this function.



NOTE: The Auto Exposure option is not available on the Emulator.

#### 3.3.2 Exposure

Main Menu > Imager > Exposure

Exposure is the amount of time the sensor allows light to energize the imager. Increasing the exposure time by moving the slider to the right allows more light to energize the imager, which brightens the image.



NOTE: This feature is not effective on the emulator.

### 3.3.3 Gain

Main Menu > Imager > Gain

Gain is an electronic boost to the image signal. Increasing Gain by using the '-' and '+' keys or moving the slider to the right increases image brightness without increasing exposure time. Note that Gain brightens both the light pixels and dark pixels and may reduce the image quality.

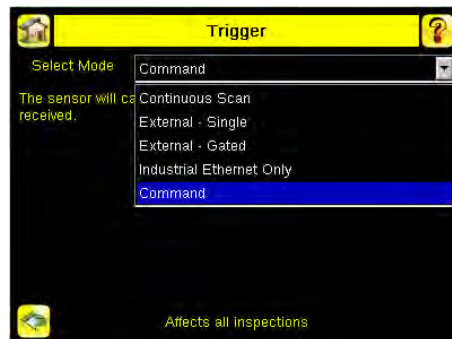


NOTE: This feature is not effective on the emulator.

### 3.3.4 Trigger

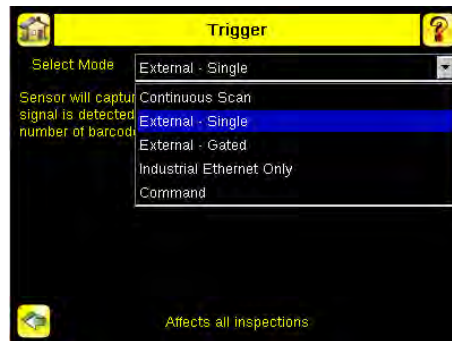
Main Menu > Imager > Trigger

A Trigger is a signal that makes the sensor capture a barcode image and decode it. From the drop-down list, select either Continuous Scan, External - Single, External - Gated, Industrial Ethernet Only, or Command.



### External-Single Mode

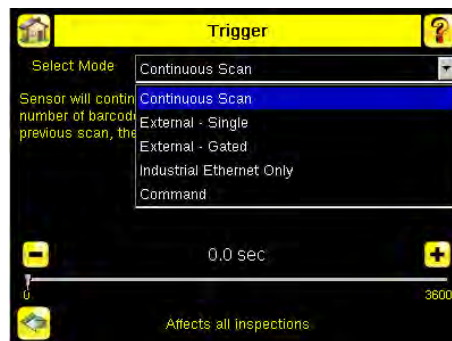
In External-Single mode, the sensor depends on an external trigger. For each trigger, the sensor captures an image and executes one scan through the configured barcode types looking for the specified number of barcodes. This trigger mode uses the Scan Time Limit parameter (Main Menu > Inspection > Properties > Scan Time Limit) to limit the amount of time the sensor will attempt to scan for barcodes on an image.



## Continuous Mode

In Continuous mode, the sensor uses internal timing to continuously capture images. For each captured image, the sensor scans through the configured barcode types looking for the specified number of barcodes. If the specified number of barcodes is found, a Read event occurs. If the specified number of barcodes is not found, the sensor captures another image and repeats the scan. There are two parameters that are used to fine-tune how Continuous Scan mode operates:

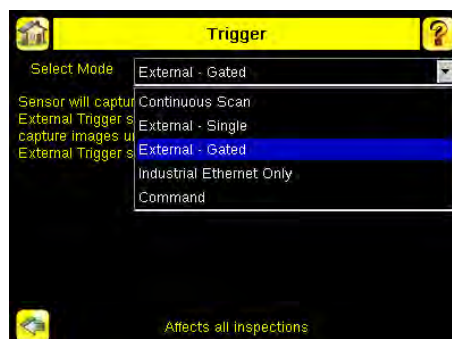
- Same Code Reject Time (set at the bottom of Main Menu > Imager > Trigger )—time in seconds that must elapse before the scanner will report a previously scanned symbol again. A different symbol will be read immediately.
- Scan Time Limit ( Main Menu > Inspection > Properties > Scan Time Limit )—limits the amount of time the sensor will attempt to scan for barcodes on an image.



NOTE: A No Read condition will not occur in Continuous mode as another image capture and scan automatically follows.

## External-Gated Mode

External-Gated mode is similar to Continuous mode. While an external trigger input signal is active, the sensor continues to capture images and run barcode scans until a successful Read occurs or the External Trigger input signal becomes inactive. The External - Gated mode uses the Scan Time Limit parameter (Main Menu > Inspection > Properties > Scan Time Limit) to limit the amount of time the sensor will attempt to decode barcodes on an image.



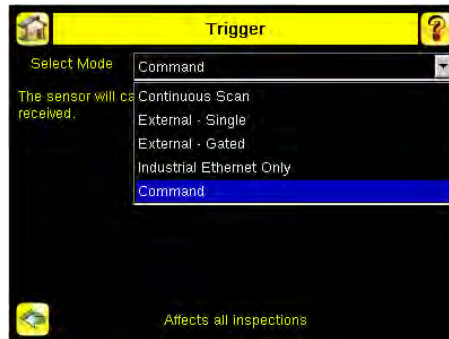




NOTE: A No Read condition will not occur in External - Gated mode while the external trigger is active.

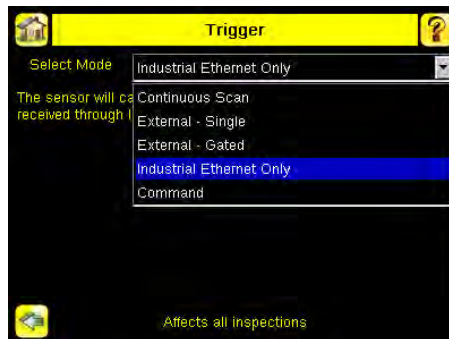
## Command Mode

In Command mode, the sensor captures images when Trigger commands are received. The various trigger command modes described above can also be set through a command channel. Refer to the Communications guide for specific commands. The commands can come from either Serial I/O or Ethernet I/O.



## Industrial Ethernet Only

When Industrial Ethernet communication channel is enabled, triggers can be received from the modes mentioned above. Triggers through Industrial Ethernet will not be executed if selected Trigger Mode is 'Continuous Scan'. If it is desired to receive triggers only through Industrial Ethernet channel, select 'Industrial Ethernet Only'.



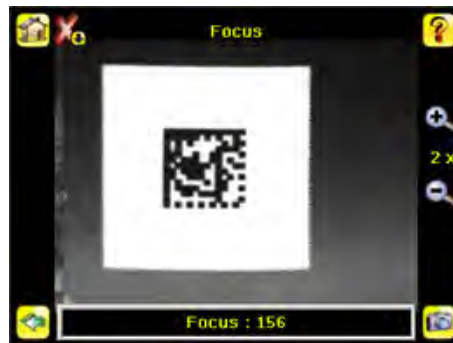
### 3.3.5 Focus

Main Menu > Imager > Focus

The Focus Number displayed at the bottom of this screen is used to fine-tune image focus. Loosen the lock on the lens cover, turn the focus ring on the sensor until the Focus Number peaks (or the image appears sharp), then lock the focus ring.



NOTE: For the Focus Number to work, the sensor must be triggering and the images must be similar over time.



### 3.3.6 Strobe

Main Menu > Imager > Strobe

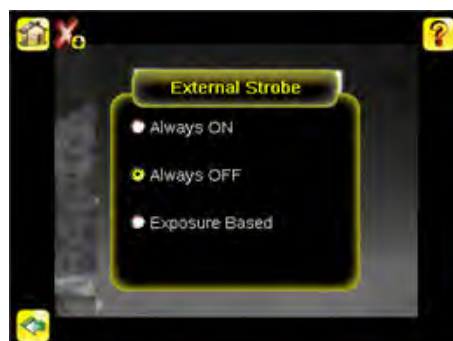
The Internal Strobe configures the operation of the integrated ring light. The External Strobe configures the operation of an external light.



#### External

Main Menu > Imager > Strobe > External

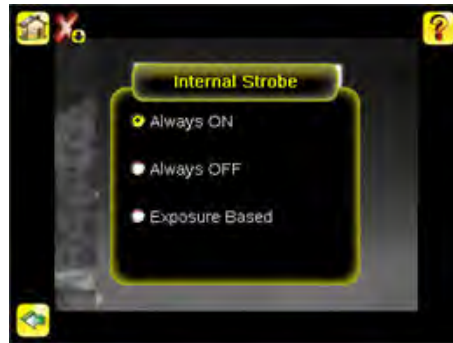
The External Strobe is a 5V output that can be used for an external light. Setting options are Always ON, Always OFF, or Exposure Based. If Exposure Based is selected, then the external light is on during the time the sensor is capturing an image.



#### Internal

Main Menu > Imager > Strobe > Internal

The Internal Strobe setting configures the operation of the integrated ring light. Strobe options are Always ON, Always OFF, or Exposure Based. If Exposure Based is selected, then the ring light is on during the time the sensor is capturing an image. For UV models, the Always ON option is not available.



### 3.3.7 FOV (Field of View)

Main Menu > Imager > FOV

The field of view (FOV) is the area that the sensor can see at a given working distance. The working distance is the distance from the sensor's lens cover to the part being inspected. By default, the sensor uses the entire FOV in its operation. The effective FOV can be reduced in order to speed up the processing time of an inspection or to decrease background noise.



#### Maximize FOV

Main Menu > Imager > FOV > Maximize FOV

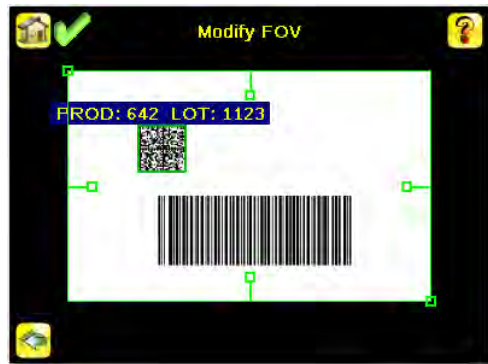
If the FOV has been modified and you want to quickly get back to the default, click the Maximize FOV menu option to restore the FOV to the entire sensor display.



## Modify FOV

Main Menu > Imager > FOV > Modify FOV

Use this option to reduce or alter the size of the FOV.



## 3.4 Inspection Menu

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Main Menu > Inspection

The Inspection menu icon is located on the Main Menu. The Inspection Menu provides options to set inspection parameters on currently running inspection and manage stored inspections.



### 3.4.1 Barcode Menu

Main Menu > Inspection > Barcode

The Barcode Menu is the location for Barcode Type, Barcode Count, and Data Compare screens.

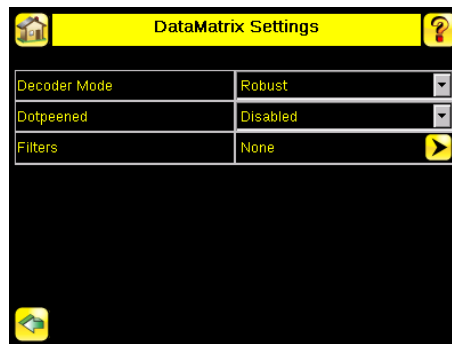
#### Barcode Type

Main Menu > Inspection > Barcode > Barcode Type

The first time the sensor is powered up, the selection checkboxes for DataMatrix and All Linear barcode types are checked. The best practice is to check only the barcode type(s) applicable for your particular application. Note that, if All Linear is unchecked, a single linear barcode type can be selected instead.



### DataMatrix Settings



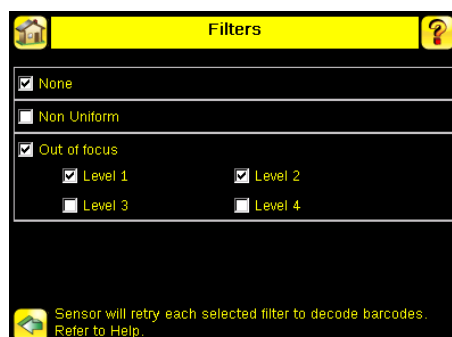
#### Decoder Mode

The Decoder Mode determines which decode algorithm to use and how imperfections in barcode images are handled. When you select Fast from the drop-down list, the sensor uses an algorithm that is tailored for speed. The algorithm does NOT correct for barcode image imperfections. The Fast setting has the best results on high-contrast images that contain high-quality barcodes. When you select Robust, the sensor uses an algorithm that performs routines to correct for imperfections of the barcode image. When Equalization is selected, the sensor tries to improve the contrast within the symbol to improve readability.

#### Dotpeened

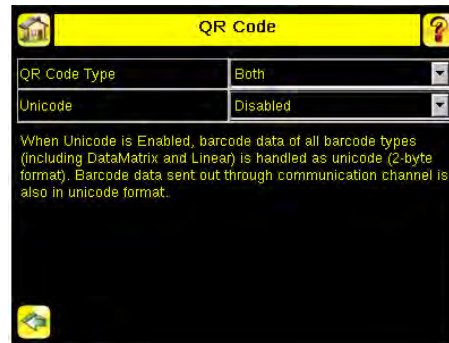
Enabling Dotpeened causes the decoder to be run in a method that is optimized for dot peened data matrix barcodes.

#### Filters



Use filters to improve decode rates in conditions in which the barcodes are blurred or have nonuniform module sizes. Select one or more Out-of-focus filters to improve the decode rate of out-of-focus barcodes. Select the Non Uniform filter to improve the decode rate of barcodes with non-uniformly sized data modules. The time required to read the barcode data may increase with the number of selected filters. The sensor will run the most successful filter (since boot-up) first before trying other filters. Select None to force the sensor to first try to decode barcodes without applying any filters.

### QR Code Settings



#### QR Code Type

The QR Code Type determines whether the device should decode a QR Code, Micro QR code, or both.

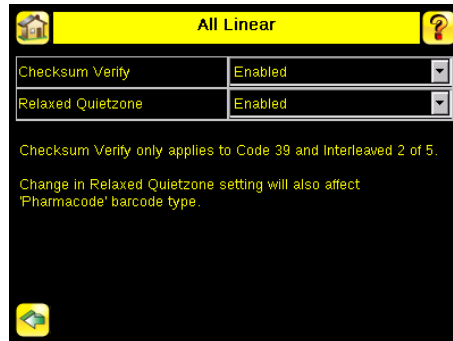
#### Unicode

The device is capable of decoding Kanji characters embedded in a QR Code. In order for the device to display the decoded data correctly, and be able to export the decoded data in Unicode format (2 byte), this setting should be enabled. Decoded data sent out on Communication Channels will also be in unicode format. The Compare Data will also be stored in unicode format. Enabling this feature affects data decoded from all barcodes in the inspection, irrespective to their symbology.

### All Linear Settings

The All Linear settings described below apply to the following barcode types:

- Code 128
- Code 39
- CODABAR
- Interleaved 2 of 5
- EAN13
- EAN8
- UPCE
- Postnet
- IMB



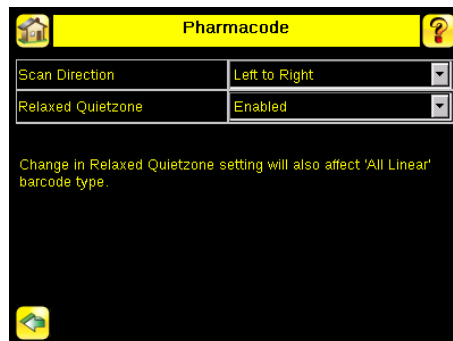
### Checksum Verify

When checksum is enabled, the sensor uses a checksum to verify the integrity of the barcode being read.

### Relaxed Quietzone

The Quietzone is a blank margin on either side of a barcode that indicates where the barcode begins and ends. If this Quietzone isn't big enough, the sensor can have trouble decoding the barcode. By enabling Relaxed Quietzone there is a greater tolerance with respect to the quiet zone required before and after the barcode.

### *Pharmacode Settings*



### Scan Direction

For Pharmacode, select one of the following for Line Scanning:

- Left to Right
- Right to Left
- Top to Bottom
- Bottom to Top
- Omnidirectional

Use Omnidirectional scanning if barcode can appear inverted on part being inspected. If 'Compare' is enabled, the sensor attempts to compare that string to decoded data in both scan directions. Inspection is marked as PASS if at least one string matches. The data that successfully matched is displayed on the screen and is exported through communication channels as requested.

If Omnidirectional scan is selected, but 'Compare' is disabled, the data decoded from left-to-right scan is reported.

## Relaxed Quietzone

The Quietzone is a blank margin on either side of a barcode that indicates where the barcode begins and ends. If this Quietzone isn't big enough, the sensor can have trouble decoding the barcode. Enabling Relaxed Quietzone creates a greater tolerance with respect to the quiet zone required before and after the barcode.

## Barcode Count

Main Menu > Inspection > Barcode > Barcode Count

In the Barcode Count screen, select the number of barcodes you want to decode. You can select from 1 to 10.



NOTE: For IMB, Postnet and Pharmacode barcode types, the sensor will decode only one barcode for each of these types regardless of the Barcode Count setting. This means that if there is one of each of these types in an image, and the Barcode Count is set to 3, the sensor will decode all three; however, if there are three IMB barcodes, for example, the sensor will always only decode one IMB barcode.



## Data Compare

Main Menu > Inspection > Barcode > Data Compare

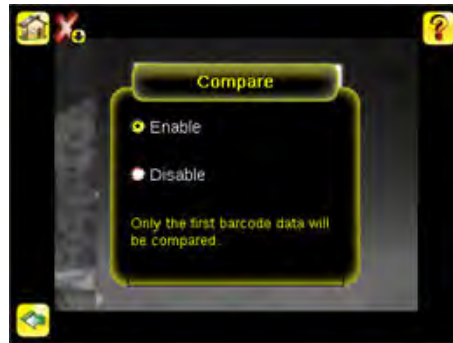
The menu options here are used to set up the sensor for Data Compare. Note that, if the Barcode Count is greater than 1, only the first barcode data can be compared or used in a remote teach operation. Turn on annotations to see which barcode is first.



## Compare

Use this menu to enable or disable Data Compare. If Data Compare is enabled, data can be defined in the Compare Data screen. The data can be retrieved from a previously scanned barcode, or it can be entered using the software keyboard on the touch screen, and insignificant characters can be masked within the data.

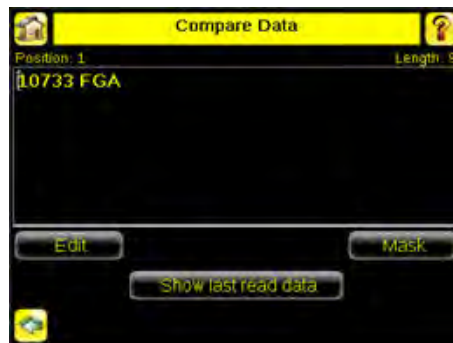




### Compare Data

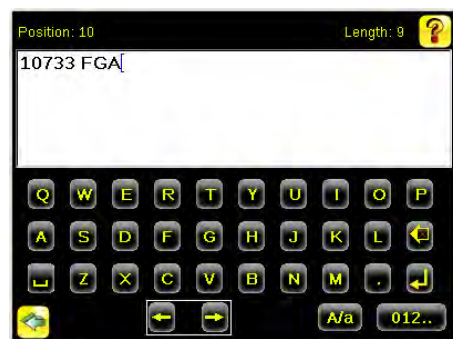
The Compare Data screen allows you to specify data against which you can compare a read barcode. Note that, if the Barcode Count is greater than 1, only the first barcode data can be compared or used in a remote teach operation. To see which barcode is the first one, turn on annotations.

- Click the Show last read data button to use the last read barcode data for the data compare.
- Click the Edit button to enter data using a software keyboard on the touch screen.
- Click the Mask button to select characters in the data to mask from the data compare. To mask a character, use the arrows at the bottom of the screen to move the cursor (|). When the cursor is to the left of a character you want to mask, click the Mask button. The character will change to green with a slash through it. If you want to unmask a character, make sure that the cursor is to the left of the masked character, and click the Unmask button.



### Edit Compare Data

The Edit screen displays data that was previously read or entered in the text field. The Position of the cursor within the characters displayed (|) in the text field is indicated at the top of the screen. Additionally, the number of characters is indicated by Length. Use the left and right arrows below the software keyboard to move the cursor between the displayed characters. Place the cursor to the right of any character and use the back-arrow at the top of the screen to delete that character. Use the button at the bottom right of the screen to cycle through different character entry keyboards: text entry (with a button to toggle between upper- and lower-case characters), numeric entry, special character entry, and hex character entry.



### Last Read Data

Click the Show last read data button to use the last read barcode data for the data compare.

### Mask Data

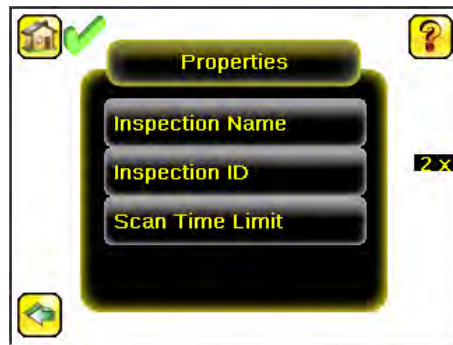
To mask characters in the data, move the cursor to the left of the character(s) to be masked, and click the Mask button. A masked character will appear gray with a strikethrough (\) indicator. To unmask a previously masked character, click the UnMask button. Note that, when using Remote Teach to set new barcode data, if the previous input data contained any masked characters, Remote Teach will retain the masked characters only if the new data is of the same length as the previous input data. If the length does not match, masking is removed.



### 3.4.2 Properties

Main Menu > Inspection > Properties

The Properties menu is used to edit an Inspection Name or set the Scan Time Limit.



### 3.4.3 Stored Inspections

Main Menu > Inspection > Stored Inspections

Stored Inspections is used to manage stored inspections. Management of stored inspections includes adding, deleting, and specifying which inspection should be defined as the Startup inspection.



From the Stored Inspections menu click Select, Add New, Startup, Delete, or Set Name/ID

### Select

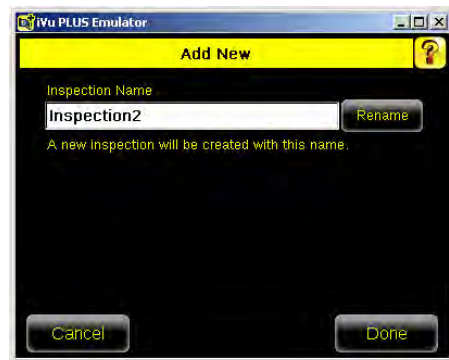
Main Menu > Inspection > Stored Inspections > Select

This screen is used to select a new running inspection. Select the name of the inspection to start, and click the Start Running button that displays.

### Add New

Main Menu > Inspection > Stored Inspections > Add New

The Add New button is to add a new inspection. The sensor can store up to 30 inspections. When you add a new inspection, it will begin running. When adding a new inspection, you can specify the name for the new inspection.



### Startup

Main Menu > Inspection > Stored Inspections > Startup

The Startup button allows you to select the inspection to use as the startup inspection. The selected inspection will automatically start after power up.

### Delete Inspections

Main Menu > Inspection > Stored Inspections > Delete

The Delete button is used to delete stored inspections. Note that any running inspection, or the inspection marked as the Startup inspection, cannot be deleted.

### Set Name/ID

Main Menu > Inspection > Stored Inspections > Set Name/ID

The Set Name/ID button is used to change the name or ID of an inspection. You can sort the inspections in numeric or alphabetical order by clicking on the icon beside the Help icon. Click on Name to edit the name of the inspection. Click on ID to change the ID of the inspection.

## 3.5 Logs Menu

---

Main Menu > Logs

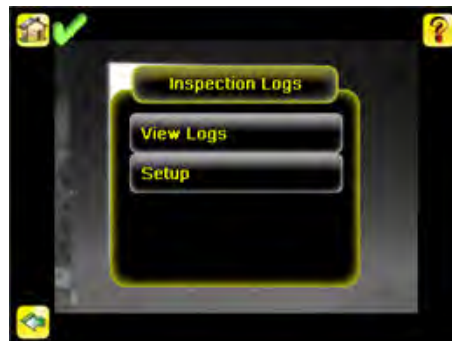
The Logs menu icon is on the Main Menu, and is used to set up, view, and save Inspection, Communication, and System Logs.



### 3.5.1 Inspection Logs

Main Menu > Logs > Inspection Logs

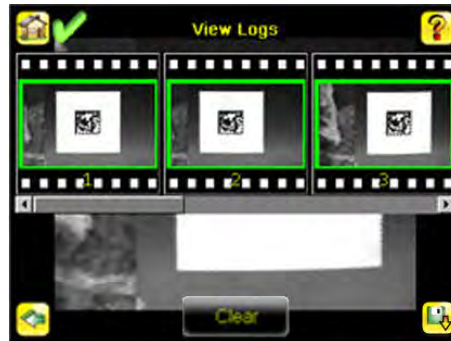
This menu provides for configuring and viewing Inspection Logs. Inspection Logs are stored inspection records that include a captured image, the parameters used to inspect it, and the results of that inspection. Up to ten Inspection Logs can be held in memory on the sensor. The next ten overwrite the previous. Inspection Logs can be saved to the USB flash drive so that the logs can be imported to the emulator.



### View Logs

Main Menu > Logs > Inspection Logs > View Logs

Inspection Logs appear as a strip of film. You can select a frame to view a specific image. Use the icon in the lower right of the screen to save the logs to the USB flash drive. Logs saved to the USB flash drive can be imported into the emulator. Click the Clear button to clear Inspection Logs.



The View Inspection Log screen is used to debug an inspection, and shows one inspection in read-only mode. Click the upper-left icon to cycle through views. When in Statistics view, the table title has arrows to switch between Inputs and Results of the Inspection.

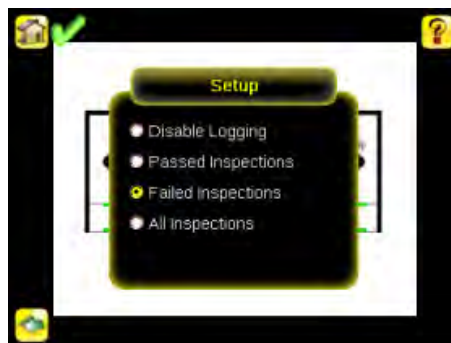
Use the left and right arrow keys at the bottom of the screen to navigate through the all stored Inspection Logs.



## Setup

Main Menu > Logs > Inspection Logs > Setup

Use the radio buttons to Disable Logging, to log Passed Inspections, Failed Inspections, or All Inspections.



## 3.5.2 System Logs

Main Menu > Logs > System Logs

The System Log contains configuration change information, other notifications, and any errors or warnings that may be encountered.

- Click the icon in the upper left corner of the screen to show/hide the time column

- Click Clear Log button at the bottom of the screen to clear the System Log
- Click the icon at the lower-right of the screen to save the System Log to the USB flash drive



NOTE: System log will not log changes while in Demo mode. Additionally, the Emulator does not log changes.

### 3.5.3 Communication Logs

Main Menu > Logs > Communication Logs

The Communication Log contains logs for the four communications channels; Industrial Ethernet, Command Channel, Data Export, and Image Export. The features below are available for each of the logs:

- Click the icon in the upper left corner of the screen to show/hide the time column.
- Click Clear Log button at the bottom of the screen to clear the log.
- Click the icon at the lower-right of the screen to save the Log to the USB flash drive.



NOTE: Communication log will not log changes while in Demo mode. Additionally, the Emulator does not log changes.

## 4 Setting up an Inspection

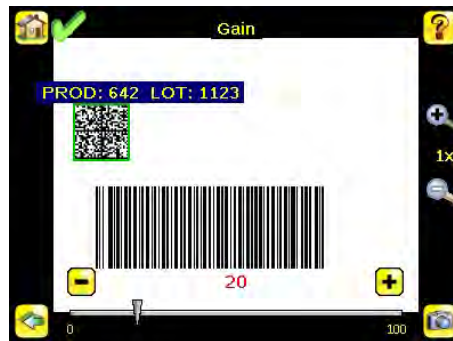
To set up for an inspection:

1. Acquire a good image.
2. Set up a barcode application.
3. Set data compare parameters.

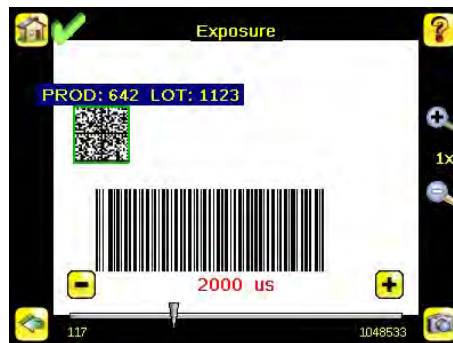
### 4.1 Acquiring a Good Image

The iVu Series sensor needs to capture a good image to ensure that it can read the barcode(s) correctly.

1. Go to Main Menu > Imager > Auto Exposure to run the Auto Exposure routine.
2. Check the lighting.
  - Make sure that the lighting is constant and consistent (unchanging over time, no shadows or hot spots).
  - Capture the barcode with lighting that optimizes its contrast and separates it from the background. Depending on the target, this may mean the integral ring light is not the best choice and other Banner lights should be considered.
  - Adjust the mounting angle to provide the clearest image of the barcode. The mounting bracket lets you easily position and adjust the sensor on your line. Typically, a slight angle will help with read robustness.
3. If needed, go to Main Menu > Imager > Auto Exposure to run the Auto Exposure routine a second time or adjust Gain and Exposure manually:
  - Main Menu > Imager > Gain



- Main Menu > Imager > Exposure



4. Go to Main Menu > Imager > Focus to adjust the focus while monitoring the Focus Number:



For Micro Video Lens Models Only:

1. Use the supplied 1/16 in. hex key to loosen the Focusing Window locking screw (D), then adjust focus on the iVu Series sensor using the clear Focusing Window (B).
2. Adjust focus while monitoring the focus number. To ensure the best image, adjust the focus until the Focus Number peaks.



NOTE: Turning the Focusing Window counter-clockwise focuses on closer objects, while turning the Focusing Window clockwise focuses on more distant objects.



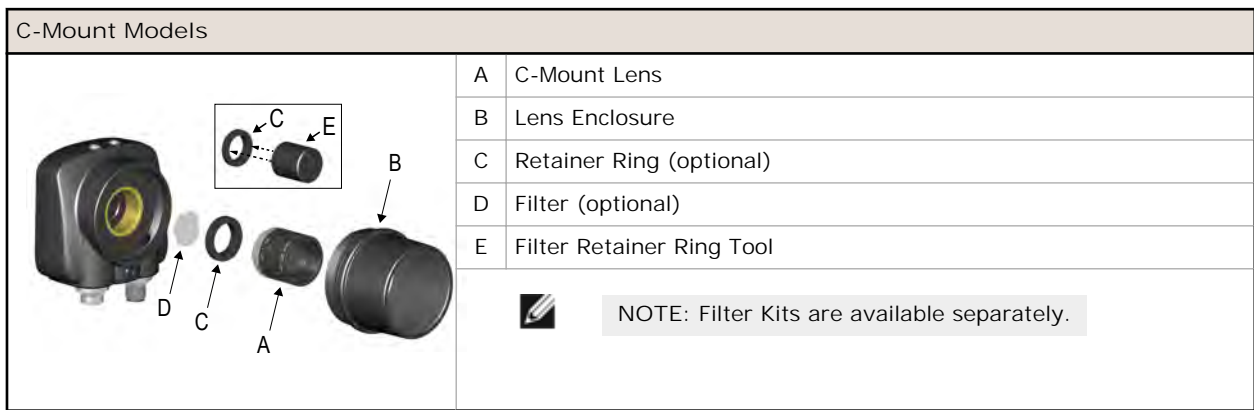
3. After the best image has been acquired, lock the focusing window.

Micro Video Lens Models	
	A Lens
	B Focusing Window
	C Locking Clip
	D Locking Screw
	E Filter Cap (optional)
	F Filter (optional)
	NOTE: Filter Kits are available separately.

For C-Mount Models Only:

1. Remove the Lens Enclosure.
2. Adjust focus while monitoring the focus number. To ensure the best image, adjust the focus until the Focus Number peaks.
3. Replace the Lens Enclosure on the camera.

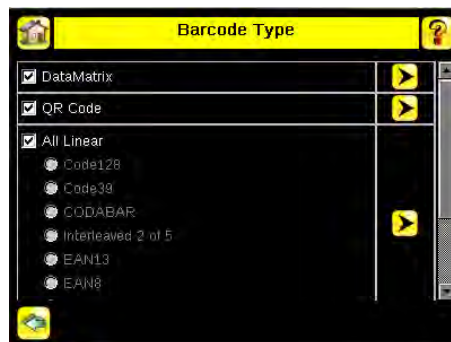




## 4.2 Setting Up a Barcode Application

This section describes how to set up the iVu Plus BCR sensor.

1. Go to Main Menu > Inspection > Barcode > Barcode Type to select one or more Barcode Types from the list.



NOTE: To ensure optimal performance, select only the barcode types for your application. For example, if you use only one of the of the barcode types listed for All Linear, uncheck the box next to All Linear, and select a radio button next to the desired linear barcode type. If you use only DataMatrix, uncheck all the boxes except the one next to DataMatrix.

2. Go to Main Menu > Inspection > Barcode > Barcode Count to select the number of barcodes (1 to 10) to be read at one time.



After the sensor has been set up as described:

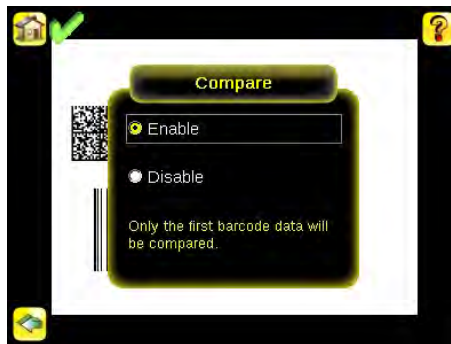
- Each successfully read barcode is marked by a green bounding box. If annotations are on, the barcode data is also displayed.
- Any case where data does not compare is marked with a solid red bounding box. If the barcode is marked with a dotted red bounding box, this indicates a checksum error or quiet zone violation.

- Any barcodes in the field of view that the sensor does not detect (for example, because they are not one of the barcode types selected), are unmarked.

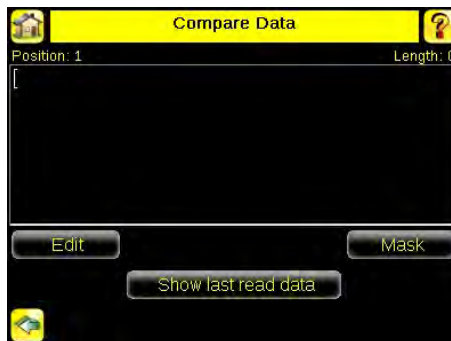
## 4.3 Setting up for Data Compare

This section describes how to set up the data compare feature. For this example, the reference data will be from a previously decoded barcode.

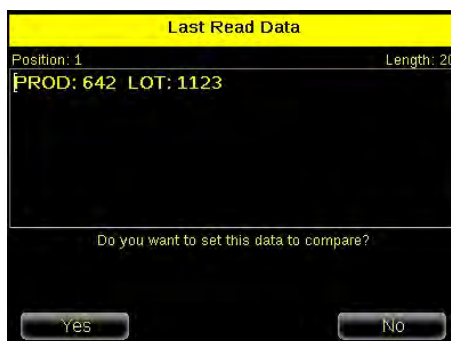
1. Go to the Main Menu > Inspection > Barcode > Data Compare > Compare to Enable data compare.



2. Go to the Main Menu > Inspection > Barcode > Data Compare > Set Data, and click the Show last read data button.



3. Press the Yes button.



4. Press the Home icon to return to the main screen.



For all subsequent triggers, when the sensor reads the barcode data, it will compare it against this reference data.

## 5 Communications Guide

### 5.1 Introduction

The iVuPlus device can be controlled or monitored over Industrial Ethernet using Ethernet/IP, Modbus/TCP or PCCC protocols. This document will help you to set up the iVu Plus in the desired configuration and provide you with information you will need to connect to the master device (PLC, HMI, etc.).

### 5.2 iVu Plus Communication Summary of Ethernet and Serial

The iVu Plus communicates with other devices via Ethernet or a UART serial communications port (RS-232). In order to establish an Ethernet connection to the sensor, the external device must be configured with the correct IP address and TCP port to communicate. To use the serial communications connection, port settings for baud rate, data bits, parity, and stop bits must be configured on the iVu Plus to match the settings of the external device.

#### 5.2.1 Communication Channels

The iVu Plus BCR supports up to four communications channels. To access the channels, go to Main Menu > System > Communications.



- Command Channel—a bi-directional communication protocol that currently supports ASCII and enables other devices to remotely control the iVu Plus sensor and access sensor results
- Industrial Ethernet—a bi-directional communication channel that allows the user to control the sensor and access sensor results using Ethernet/IP, Modbus/TCP, or PCCC protocol
- Data Export—used to export selected inspection data to a remote device
- Image Export—used to export inspection images to a remote device

Data export and command channel can be configured for either Ethernet or Serial I/O (but not both); image export is only available over Ethernet. The table below briefly summarizes valid communication channel configuration options.

Command Channels	Scenario #1		Scenario #2		Scenario #3	
	Ethernet	Serial I/O	Ethernet	Serial I/O	Ethernet	Serial I/O
Command Channel	Yes	No	No	Yes	Yes	No
Industrial Ethernet	Yes	No	Yes	No	Yes	No
Data Export	Yes	No	Yes	No	No	Yes
Image Export	Yes	No	Yes	No	Yes	No

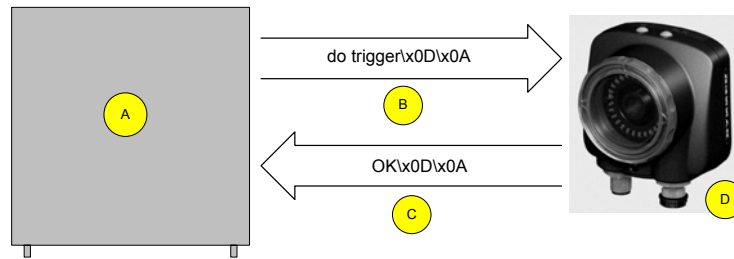
#### 5.2.2 Industrial Ethernet

Main Menu > System > Communications > Industrial Ethernet

The iVuPlus device can be controlled or monitored over Industrial Ethernet using Ethernet/IP, Modbus/TCP or PCCC protocols. This document will help you to set up the iVu Plus in the desired configuration and provide you with information you will need to connect to the master device (PLC, HMI, etc.).

### 5.2.3 Command Channel

The iVu Plus BCR command channel is a bi-directional communication protocol that currently supports ASCII via either Ethernet or the RS-232 serial interface, and enables other devices to remotely control the iVu sensor and access sensor results.



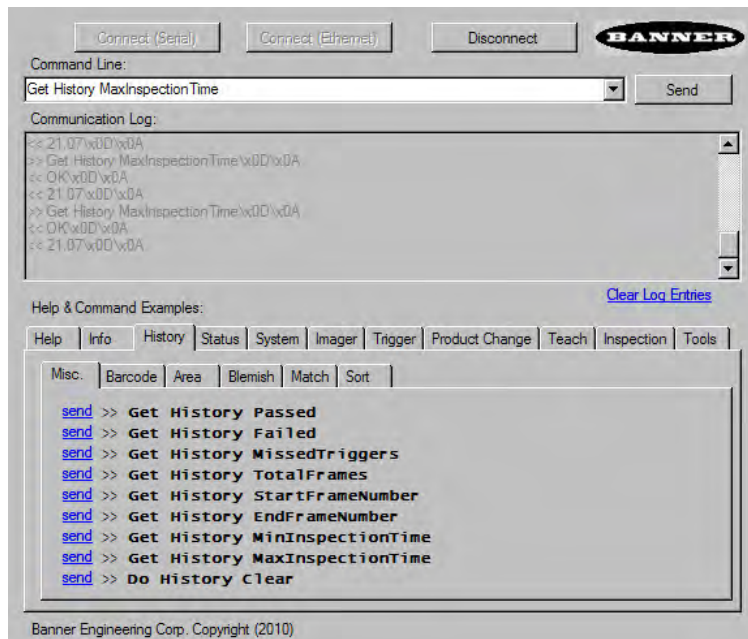
- A Control Device, which can be a PLC, PC program, or a terminal
- B Request Frame
- C Response Frame
- D iVu Plus BCR Sensor

The following are some of the functionality available via the command channel:

- Get sensor information (such as version and sensor name)
- Control "discrete" I/O (such as trigger and teach)
- Get sensor results (such as sensor status)
- Change the running inspection

#### Command Channel Sample Application

The iVu Plus BCR installation CD has a Command Channel sample application that provides an easy interface to execute commands. In a production environment, you will need to create your own application for bi-directional communication with the sensor.



## 5.2.4 Data Export

The iVu Plus sensor provides for exporting user-selected inspection data via either Ethernet or the RS-232 serial interface. Inspection data that can be exported includes:

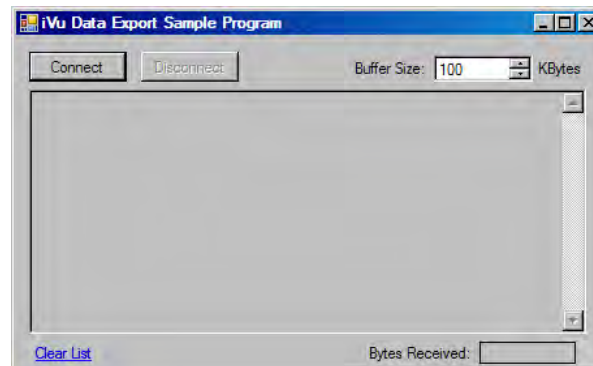
- Pass/Fail Output
- Inspection Name
- Sensor Result
  - Pass/Fail
  - Sensor Result (see [Table 2](#) on page 54 for additional information)
- Frame #
- Inspection Time (ms)

*Table 2: Sensor Results*

Sensor Type	Data to Export
Barcode	Barcode Count
	Data Length
	Symbol Type
	Barcode Data

### Sample Application

The iVu Plus BCR installation CD has a Data Export sample application that provides for viewing exported data while setting up the sensor, etc. In a production environment, you will need to create your own application to process data exported from the sensor.



## 5.2.5 Image Export

Image export is only supported on Ethernet ports. Inspection images are a maximum 752×480 8-bits per pixel grayscale images in Windows BMP format that represent all the data in a full Field of View (FOV).

Each exported image is comprised of a header (64 bytes) followed by the image data (approximately 361K). All 16- and 32-bit numeric entries are little endian.

The header includes the following information:

Byte Offset	Field ID	Size in Bytes	Data Type	Description
0-15	Header Prefix	16	char	"IVU PLUS IMAGE"
16-19	Header Version	4	UInt32	1
20-23	Image Size	4	UInt32	Number of bytes (Windows BMP image)
24-27	Image Frame Number	4	UInt32	Most recently snapped image frame number
28-29	Image Width	2	UInt16	752 (max)

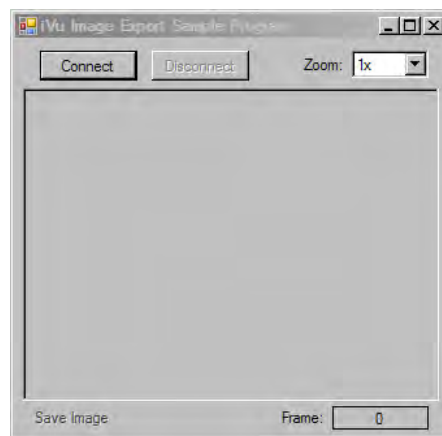
Byte Offset	Field ID	Size in Bytes	Data Type	Description
30-31	Image Height	2	UInt16	480 (max)
32-33	Image Format	2	UInt16	0: Bitmap, 1: JPEG
34-63	Reserved	32	byte	Reserved for future use



NOTE: If FOV's are adjusted so that they are smaller, the bitmaps will also be smaller.

### Image Export Sample Application

The iVu Plus BCR installation CD has a Image Export sample application that provides a way to save exported images. In a production environment, you will need to write your own application to process exported images, for example to display them on an HMI or to save them to disk.



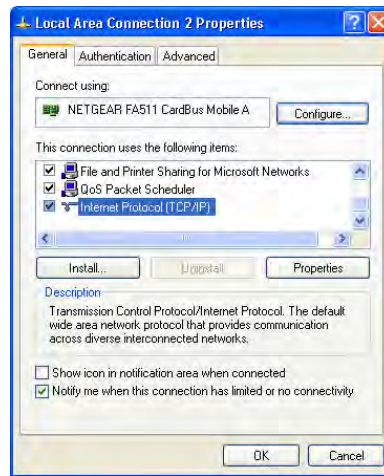
## 5.3 Enabling Communications

### 5.3.1 Setting Up Ethernet Communications

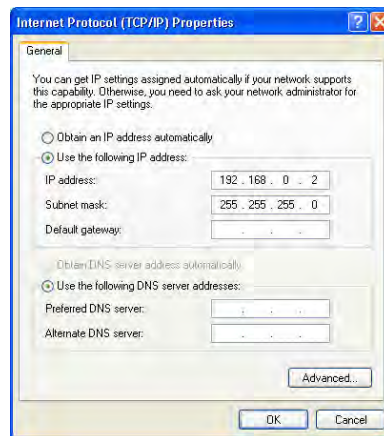
Configure both the PC and the sensor using the following instructions.

#### Windows XP

1. Open Network Properties on the PC (right-click on the Network Neighborhood icon).
2. On the Local Area Connection, right-click on Properties.
3. In the dialog, click on Internet Protocol (TCP/IP) and click the Properties button.

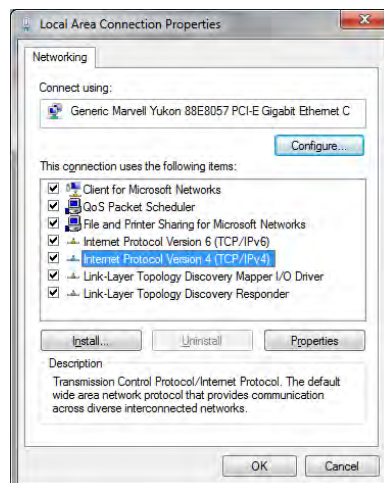


4. In the Internet Protocol (TCP/IP) Properties dialog, select Use the following IP address and make sure that the IP address is 192.168.0.2, and the subnet mask is 255.255.255.0.



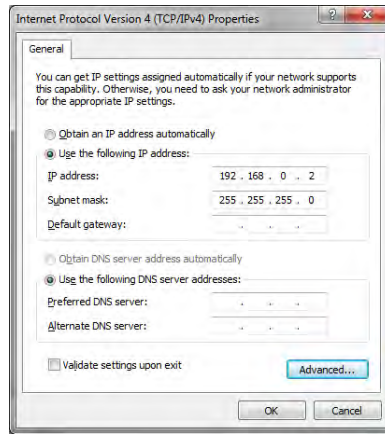
## Windows 7

1. Open Network Connections by clicking on the Start button, then selecting the Control Panel followed by Network and Internet, and clicking Manage network connections.
2. Right-click the connection you want to change, then click Properties. If you are prompted for an administrator password or confirmation, type the password or provide confirmation.
3. In the Networking dialog, click on Internet Protocol Version 4 (TCP/IPv4) and click the Properties button.



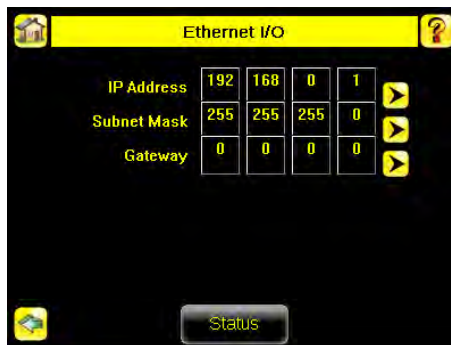


4. In the Internet Protocol (TCP/IPv4) Properties dialog, select Use the following IP address and make sure that the IP address is 192.168.0.2, and the subnet mask is 255.255.255.0.

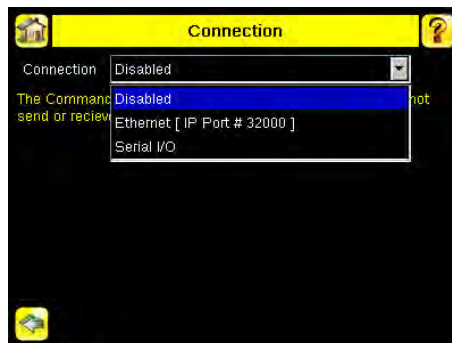


### Sensor Setup for Ethernet Communications

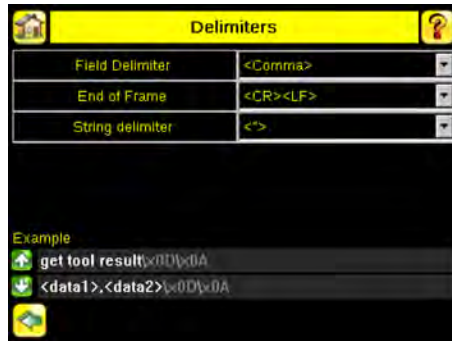
1. Go to Main Menu > System > Communications > Ethernet I/O and make sure that the sensor is configured as shown below.



2. To enable the command channel over Ethernet:
  - a. Go to Main Menu > System > Communications > Command Channel > Connection, and select Ethernet [IP Port # 32000].

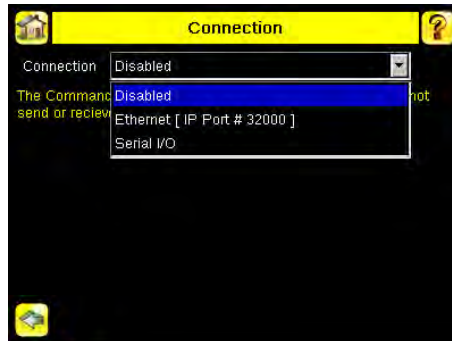


- b. Configure the field and end-of-frame delimiters. Go to Main Menu > System > Communications > Command Channel > Delimiters.

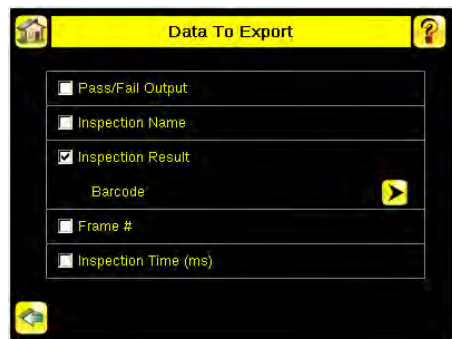


Valid end-of-frame delimiters are: <comma>, <colon>, <semicolon>, <CR>, <CR><LF>, <LF><CR>, or <ETX>.

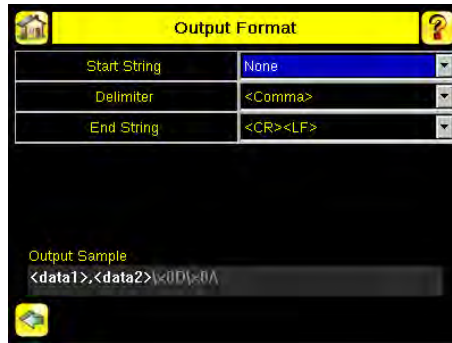
- c. Verify that the iVu receives and transmits data correctly.
- 3. To enable Data Export over Ethernet:
  - a. Go to Main Menu > System > Communications > Data Export > Connection and select Serial I/O from the drop-down.



- b. Go to Main Menu > System > Communications > Data Export > Data To Export and select the inspection data to export.



- c. Go to Main Menu > System > Communications > Data Export > Output Format and select the Start String, Delimiter, and End String.



d. Go to Main Menu > System > Communications > Data Export > Advanced.



During the Data and Image export operation the sensor's output channels might become full. This can occur if the sensor is producing export data (frames) faster than the data can be exported from the device (due to bandwidth limitations) or faster than the client is reading the channel export data.

This setting affects how the sensor will behave in this situation.

- Select Hold READY to ensure that all frames are transmitted. In this case, the READY signal will remain inactive (sensor is busy) until the new frame has been added to the channel for transmission. Triggers might be missed during this time.
- Select Do not hold READY to cause the sensor to discard the new frame if the channel is full and thus activate the READY signal immediately after the current inspection is complete. In this case, the discarded frames will not be transmitted.

### Communications Channel Ports

The following are the default Ethernet port settings for the communications channels:

- Command Channel — 32200
- Data Export — 32100
- Image Export — 32000

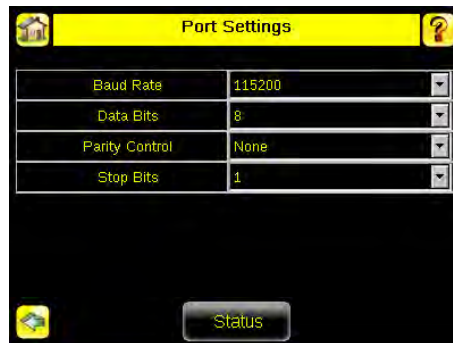
### 5.3.2 Setting Up Serial Communications

1. Electrically connect the control device and the iVu sensor. On the iVu, the pins/wire colors used for serial communications via RS-232 are shown in the table below.

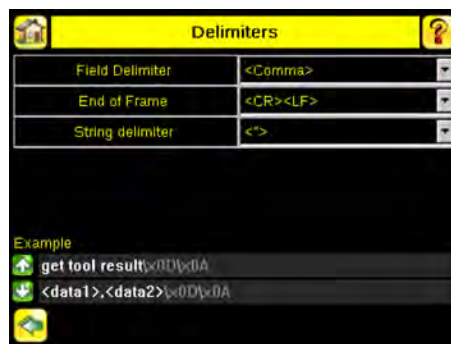
Table 3: iVu RS-232 Connections

Pin #	Wire Color	Description
10	Light-Blue	TX
11	Black	Signal Ground
12	Violet	RX

2. Configure port settings (baud rate, data bits, parity, and stop bits) on the iVu to match the settings on the control device. Go to Main Menu > System > Communications > Serial I/O.

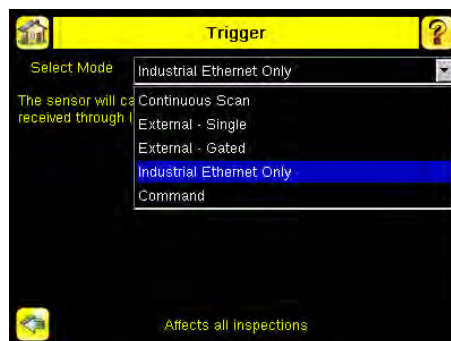


3. To enable the command channel over the serial connection:
  - a. Go to Main Menu > System > Communications > Command Channel > Connection and select Serial I/O.
  - b. Configure the field and end-of-frame delimiters. Go to Main Menu > System > Communications > Command Channel > Delimiters.

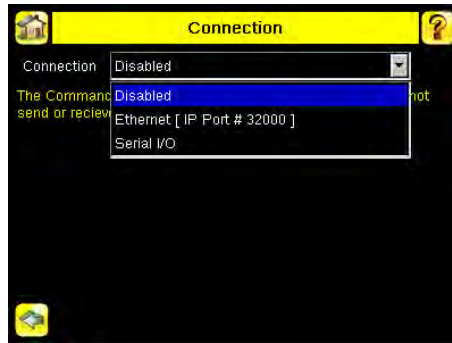


Valid end-of-frame delimiters are: <comma>, <colon>, <semicolon>, <CR>, <CR><LF>, <LF><CR>, or <ETX>.

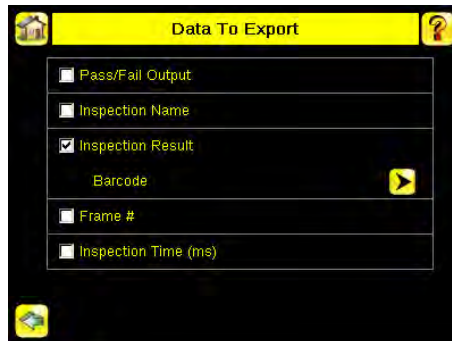
- c. Optionally, if you want to trigger the iVu from the control device, set the trigger mode to Command (go to Main Menu > Imager > Trigger and select Command from the drop-down).



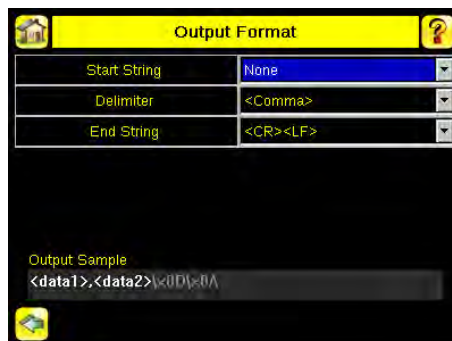
- d. Verify that the iVu receives and transmits data correctly.
4. To enable Data Export over the serial connection:
  - a. Go to Main Menu > System > Communications > Data Export > Connection and select Serial I/O from the drop-down.



- b. Go to Main Menu > System > Communications > Data Export > Data To Export and select the inspection data to export.



- c. Go to Main Menu > System > Communications > Data Export > Output Format and select the Start String, Delimiter, and End String.



- d. Go to Main Menu > System > Communications > Data Export > Advanced.



During the Data and Image export operation the sensor's output channels might become full. This can occur if the sensor is producing export data (frames) faster than the data can be exported from the device (due to bandwidth limitations) or faster than the client is reading the channel export data.

This setting affects how the sensor will behave in this situation.

- Select Hold READY to ensure that all frames are transmitted. In this case, the READY signal will remain inactive (sensor is busy) until the new frame has been added to the channel for transmission. Triggers might be missed during this time.
- Select Do not hold READY to cause the sensor to discard the new frame if the channel is full and thus activate the READY signal immediately after the current inspection is complete. In this case, the discarded frames will not be transmitted.

## 5.4 Testing and Troubleshooting iVu Plus Communications

### 5.4.1 Understanding the Communication Log

The iVu Plus sensor includes the following Communication Logs:

- Command Channel Log that can be used to ensure that commands are properly formed (syntax is correct), and provides a history of commands issued along with responses to these commands. To access the Command Channel Log, go to Main Menu > Logs > Communication Logs > Command Channel
- Data Export and Image Output logs that are purely output logs (that is, there is no receive activity to log)








Some notes about the logs:

- To see an expanded view of each entry, click on the small right-triangle control on each entry
- To save the log, click the save icon. The saved communication log can be loaded into the emulator for troubleshooting offline

The table below describes the icons used in the Communication Log, the up-arrow indicates an incoming request to the iVu from the control device; the down-arrow indicates an outgoing response from the iVu to the control device.

Icon	Description
	Port opened.

Icon	Description
	Port closed.
	Indicates that the command has been processed without errors.
	Indicates that the incoming entry is stalled (no new bytes), or end-of-frame delimiter was not received, or client is not reading data on ethernet.
	If the response frame contains an error or is dropped, the log entry icons for the request and the response frames will be colored red, and the displayed error count will increment by one.
	If the command takes a long time to process, the last long entry will change to an hourglass (for example, during trigger of long inspections).

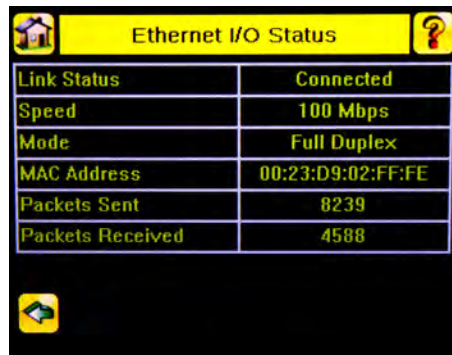
For Ethernet channels:

- The channel's log will show an Enabled entry that indicates which port is being listened to
- When a client connects, a log entry is added that indicates which IP address connected
- When a client closes the connection, a log entry indicates that the channel is no longer being listened to

### 5.4.2 Ethernet I/O

#### Ethernet I/O Status

The Ethernet I/O Status screen can be used to verify that the Ethernet wiring has been correctly set up. In addition to determining if the link has been established, incoming and outgoing traffic can be monitored.



### 5.4.3 Serial I/O

#### Using the Port Status Screen for Testing RS-232 Communications

The Port Status screen can be used to ensure data is entering and exiting the sensor. This can be useful for debugging issues such as improper wiring, mismatched baud rates, or other serial I/O issues. To access the Port Status screen, go to Main Menu > System > Communications > Serial I/O and click on the Status button.

- The upper field shows the bytes received (request frame) on the iVu from the control device.
- The lower field shows the bytes sent (response frame) from the iVu to the control device.









3. If the byte count does not match, re-verify that the settings on both devices match exactly. If no bytes are received, re-check the wiring.

If the correct response frame is received, then basic electrical and port settings are correct.

## 5.5 Command Channel Primer

### 5.5.1 Command Channel Commands

All iVu command channel request command frames use the following syntax:

```
>> command group item value<EOF>
```

#### Notes

<EOF> is the end-of-frame delimiter. See below for a description.

All commands are in ASCII and are case-insensitive

#### command

An action to be performed on a particular iVu group; for example, get, set, do, login, or logout.

#### group

Identifies the iVu group that the command should act upon; for example, info, system, trigger, or bcr\_input.

#### item

Further qualifies the action by specifying an item within the identified group; for example, comparedata or status.

#### value

For set commands, this identifies the data that must be set for the specified group item.

Note: Item is not used with get commands.

#### <EOF>

Identifies the end-of-frame for the command so that the iVu knows to begin processing. The iVu will return a response that includes the end-of-frame delimiter. The options for the <EOF> are set in the iVu Serial I/O menu, and are as follows:

- <comma>
- <colon>
- <semicolon>
- <CR>
- <CR><LF>
- <LF><CR>
- <ETX>



**NOTE:** When data is displayed on iVu screens such as the Port Status screen, printable delimiters are displayed as expected. Non-printable characters, such as <CR> are displayed in hex notation (\x0D).

## Command Flow

The command flow should be such that a new command request should not be issued until the iVu command channel acknowledges the previous command request.

For example, the following is a series of command requests and responses. The first request sets the trigger mode to command and, once the sensor responds with an "OK," the next command request is issued to do (or execute) the trigger.

```
>> set trigger mode command\x0D\x0A
<< OK\x0D\x0A
>> do trigger\x0D\x0A
<< OK\x0D\x0A
```

## String Delimiters and Escaping

By default setting, all strings used in commands are enclosed in quotation marks (""). All text in quotes is part of the command. Quotes (") or back-slashes (\) that are part of the string must be escaped with a back-slash. For example:

```
"abc\"def\"ghi\"jkl"
```

Set the String Delimiter parameters to 'None' if strings should not be enclosed in quotation marks.

## Command Channel Command Synopsis

There are a number of general types of commands to do, set, and get sensor data.

### Command Channel Response Frames

The iVu responds to all request frames with one or two responses depending on the type of command.

#### Do commands

All do commands are followed by one response that identifies the command status. For example:

```
>> do trigger\x0D\x0A
<< OK\x0D\x0A
```

#### Get commands

All get commands are followed by two responses: the first identifies the status of the command, and the second contains the retrieved information. For example:

```
>> get bcr_input comparedata\x0D\x0A
<< OK\x0D\x0A
<< "012345ABCDEF"\x0D\x0A
```

#### Set commands

All set commands are followed by one response that identifies the command status. For example:

```
>> set bcr_input comparedata "012345ABCDEF"\x0D\x0A
<< OK\x0D\x0A
```

### Command Channel Command Status

The command status is either OK or ERROR. If OK, then the command has fully and successfully completed. If an error is returned it is in the form *ERROR nnnnn\_ERROR\_IDENTIFIER* (for example ERROR 10001\_COMMAND\_NOT\_RECOGNIZED). Refer to [Command Channel Error Codes](#) on page 73 for a list of errors.

## 5.5.2 Conventions Used for Examples

There are a number of command channel examples included here, and the following are the conventions used in the examples:

- All examples use <CR><LF> for the end-of-frame delimiter, and this delimiter is always denoted in hex (\x0D\x0A) since that is what is displayed in the iVu logs and, for example, the Port Status screen.
- All commands are in bold text.
- For each example, a command request to the iVu sensor is prefaced with a >>, and a command response frame from the iVu sensor is prefaced by a << as shown below. These are only used to make the documentation clearer.

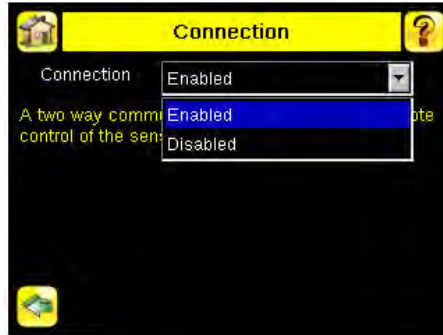
```
>> get info companyname\x0D\x0A
<< OK\x0D\x0A
<< "Banner Engineering Corp."\x0D\x0A
```

## 5.5.3 Examples

### How to Trigger the Sensor and Retrieve Barcode Data using the Command Channel

To trigger the sensor and retrieve barcode data, do the following:

1. Go to the Main Menu > System > Sensor Configuration > Serial I/O.
2. Click on the Channel Mode button.
3. In the Channel Mode dialog, select Command from the drop-down list.



4. Set Trigger to Command. Go to the Main Menu > Imager > Trigger screen, and from the drop-down select Command
5. Issue a trigger command as follows:

```
>> do trigger\x0D\x0A
<< OK\x0D\x0A
```

6. Check that the inspection passed.

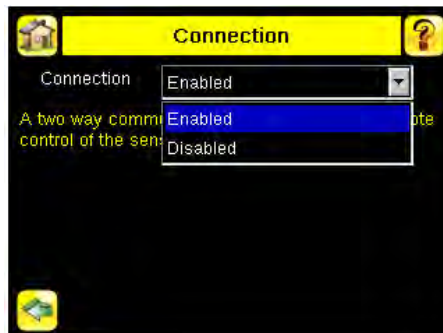
```
>> get inspection status\x0D\x0A
<< OK\x0D\x0A
<< Pass\x0D\x0A
```

7. Get the barcode data read by the iVu sensor.

```
>> get bcr_result\x0D\x0A
<< OK\x0D\x0A
<< "0043000011201"\x0D\x0A
```

### How to Modify Barcode Compare Data Using the Command Channel

1. Go to the Main Menu > System > Sensor Configuration > Serial I/O.
2. Click on the Channel Mode button.
3. In the Channel Mode dialog, select Command from the drop-down list.



4. Set Trigger to Command. Go to the Main Menu > Imager > Trigger screen, and from the drop-down select Command.
5. Set the compare data.

```
>> set bcr_input comparedata "0043000011201"\x0D\x0A
<< OK\x0D\x0A
```

6. Trigger the sensor.

```
>> do trigger\x0D\x0A
<< OK\x0D\x0A
```

7. Check that the inspection passed.

```
>> get inspection status\x0D\x0A
<< OK\x0D\x0A
<< Pass\x0D\x0A
```

8. Get the barcode data read by the iVu sensor.

```
>> get bcr_result data\x0D\x0A
<< OK\x0D\x0A
<< "0043000011201"\x0D\x0A
```

## 5.5.4 Command Channel Reference

### Info Command Group

Command	Group	Item	Description
Get	Info	CompanyName	The company name as a string.
Get	Info	ModelNumber	The sensor model number as a string.
Get	Info	FirmwareVersion	The sensor firmware version as a string.
Get	Info	SerialNumber	The sensor serial number as a string.
Get	Info	Name	The sensor name as a string.
Get	Info	BootNumber	The number of sensor bootups.
Get	Info	UpTimer	The elapsed time the sensor has been running in the format hh:mm:ss:msec.
Get	Info	HourCount	The number of hours the sensor has been running.
Get	Info	RemoteConnected	The remote display connected status as a boolean value (true or false).
Get	Info	RemoteModelNumber	The model number of the remote display as a string.
Get	Info	RemoteSerialNumber	The serial number of the remote display as a string.

### Examples

```
>> get info companyname\x0D\x0A
<< OK\x0D\x0A
<< "Banner Engineering Corp."\x0D\x0A
```

```
>> get info bootnumber\x0D\x0A
<< OK\x0D\x0A
<< 42\x0D\x0A
```

```
>> get info uptimer\x0D\x0A
<< OK\x0D\x0A
<< 4:42:42:324\x0D\x0A
```

### System Command Group

Command	Group	Item	Description
Do	System	Reboot	Reboots the sensor. Pre-empts other commands except Save.
Do	System	Save	Saves inspection and configuration parameters. Blocks until finished. Should be used sparingly.

Command	Group	Item	Description
Get	Ethernet	IPAddress	Get the current active IP address of the sensor as a string.
Get	Ethernet	SubnetMask	Get the current active subnet mask of the sensor as a string.
Get	Ethernet	Gateway	Get the current active Gateway address of the sensor as a string.
Set	Ethernet	IPAddress	Set IP address of the sensor. A valid IP address must be supplied as a string (for example: 192.168.0.1). A 'Reboot' command from the command channel must follow in order to make the new IP address effective. You may also set new Subnet Mask and Gateway address as required before a 'Reboot' command is sent to the sensor.
Set	Ethernet	SubnetMask	Set new subnet mask. A 'Reboot' command is required to be sent from the command channel in order to make the new mask effective.
Set	Ethernet	Gateway	Set new Gateway IP address. A 'Reboot' command is required to be sent from the command channel to make the new address effective.

### Examples

```
>> do system save\x0D\x0A
<< OK\x0D\x0A
```

## Status Command Group

Command	Group	Item	Description
Get	Status	Ready	Flag indicating whether the system is ready to trigger (true) or busy (false).
Get	Status	SystemError	Flag indicating whether a system error is active (true) or cleared (false).
Do	Status	ClearSystemError	Clears the system error LED and sets the internal flag to false.

### Examples

```
>> get status ready\x0D\x0A
<< OK\x0D\x0A
<< True\x0D\x0A
```

```
>> get status systemerror\x0D\x0A
<< OK\x0D\x0A
<< False\x0D\x0A
```

```
>> do status clearsystemerror\x0D\x0A
<< OK\x0D\x0A
```

## Trigger Command Group

Command	Group	Item	Description
Get	Trigger	Mode	The sensor's triggering mode. This value must match the modes supported by the sensor. This value can be modified using the sensor's touchscreen. This remotely modified value is not persisted to the sensors permanent memory. The 'Save' operation is required to persist this value.
Set	Trigger	Mode	The sensor's triggering mode. This value must match the modes supported by the sensor. This value can be modified using the sensor's touchscreen. This remotely modified value is not persisted to the sensors permanent memory. The 'Save' operation is required to persist this value.

Command	Group	Item	Description
Do	Trigger	Immediate	This command initiates a single trigger and inspection. The sensor does not transmit a response until the sensor has completed the action and returned to the READY state. This command requires the 'Command' trigger mode. The sensor must be in the ready state to perform the desired operation.
Do	Trigger	Gated	This command initiates the gated triggering mode. Images are repeatedly acquired until a valid object is detected or this mode is aborted. The sensor does not transmit a response until the sensor has completed the action and returned to the READY state. This command requires the 'Command' trigger mode. The sensor must be in the ready state to perform the desired operation.
Do	Trigger	AbortGated	This command aborts the gated triggering mode. The sensor does not transmit a response until the gated triggering option has been aborted and the sensor has returned to the READY state. This command requires the 'Command' trigger mode.

### Imager Command Group

Command	Group	Item	Description
Get	Imager	Gain	The sensor's value used to electronically brighten all image pixels This value can be modified using the sensor's touchscreen. This remotely modified value is not persisted to the sensors permanent memory. The 'Save' operation is required to persist this value.
Set	Imager	Gain	The sensor's value used to electronically brighten all image pixels This value can be modified using the sensor's touchscreen. This remotely modified value is not persisted to the sensors permanent memory. The 'Save' operation is required to persist this value.
Get	Imager	Exposure	The sensor's value used to control the amount of time the imager is allowed to gather light for the image. This value can be modified using the sensor's touchscreen. This remotely modified value is not persisted to the sensors permanent memory. The 'Save' operation is required to persist this value.
Set	Imager	Exposure	The sensor's value used to control the amount of time the imager is allowed to gather light for the image. This value can be modified using the sensor's touchscreen. This remotely modified value is not persisted to the sensors permanent memory. The 'Save' operation is required to persist this value.

#### Examples

```
>> get imager exposure\x0D\x0A
<< OK\x0D\x0A
<< Command\x0D\x0A
```

```
>> set imager exposure"11900"\x0D\x0A
<< OK\x0D\x0A
```

### Teach Command Group

Command	Group	Item	Description
Do	Teach	NextTrigger	This commands forces the sensor to perform the Remote Teach operation on the next trigger. This command can be performed using the sensor's touchscreen.

## Examples

```
>> do teach\x0D\x0A
<< OK\x0D\x0A
```

## ProductChange Command Group

Command	Group	Item	Description
Do	ProductChange	[Name]	Forces the sensor to switch to the specified inspection. The sensor does not transmit a response until the sensor has completed the action. Inspections results will be invalid until the next trigger.
Get	ProductChange	InspectionNames	List of all inspections stored in the sensor.

## Examples

```
>> get productchange inspectionnames\x0D\x0A
<< OK\x0D\x0A
```

```
>> do productchange "inspection2"\x0D\x0A
<< OK\x0D\x0A
```

## History Command Group

Command	Group	Item	Description
Get	History	Passed	This value indicates the number of passed inspections for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.
Get	History	Failed	This value indicates the number of failed inspections for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.
Get	History	MissedTriggers	This value indicates the number of missed triggers for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.
Get	History	StartFrameNumber	This value indicates the starting frame number for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.
Get	History	EndFrameNumber	This value indicates the latest frame number for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.
Get	History	TotalFrames	This value indicates the total number inspections (frames) for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.
Get	History	MinInspectionTime	This value indicates the minimum (fastest) inspection time for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.
Get	History	MaxInspectionTime	This value indicates the maximum (slowest) inspection time for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.
Get	History	MinBarcodeCount	This value indicates the minimum number of barcodes read for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.

Command	Group	Item	Description
Get	History	MaxBarcodeCount	This value indicates the maximum number of barcodes read for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.
Do	History	Clear	This command clears all history fields for the active inspection. History values include pass count, fail count, execution times and sensor specific history values. This command can be performed using the sensor's touchscreen.

#### Examples

```
>> get history passed\x0D\x0A
<< OK\x0D\x0A
<< 13\x0D\x0A
```

```
>> get history startframenumbers\x0D\x0A
<< OK\x0D\x0A
<< 3\x0D\x0A
```

```
>> do history clear\x0D\x0A
<< OK\x0D\x0A
```

### Inspection Command Group

Command	Group	Item	Description
Get	Inspection	Status	This status of the most recent inspection either Pass, Fail, or Idle (no triggers).
Get	Inspection	Name	The name of the active inspection.
Get	Inspection	FrameNumber	The most recent inspection frame number.
Get	Inspection	ExecutionTime	The most recent inspection execution time in msec.

#### Examples

```
>> get inspection status\x0D\x0A
<< OK\x0D\x0A
<< Fail\x0D\x0A
```

```
>> get inspection executiontime\x0D\x0A
<< OK\x0D\x0A
<< 37.739\x0D\x0A
```

### BCR\_INPUT Command Group

Command	Group	Item	Description
Get	BCR_INPUT	CompareData	The Barcode inspection compare data string. This string must start and end with the double quote character. This value can be modified using the sensor's touchscreen. This remotely modified value is not persisted to the sensors permanent memory. The 'Save' operation is required to persist this value.
Set	BCR_INPUT	CompareData	The Barcode inspection compare data string. This string must start and end with the double quote character. This value can be modified using the sensor's touchscreen. This remotely modified value is not persisted to the sensors permanent memory. The 'Save' operation is required to persist this value.



Command	Group	Item	Description
Get	BCR_INPUT	CompareMask	The Barcode inspection compare string mask in binary format; that is, masked characters are indicated by a "1" and unmasked characters are "0." Note that the mask character string must match the length of the compare string. This value can be modified using the sensor's touchscreen. This remotely modified value is not persisted to the sensors permanent memory. The 'Save' operation is required to persist this value.
Set	BCR_INPUT	CompareMask	The Barcode inspection compare string mask in binary format; that is, masked characters are indicated by a "1" and unmasked characters are "0." Note that the mask character string must match the length of the compare string. This value can be modified using the sensor's touchscreen. This remotely modified value is not persisted to the sensors permanent memory. The 'Save' operation is required to persist this value.

### BCR\_RESULT Command Group

Command	Group	Item	Description
Get	BCR_RESULT	Count	The total number of barcodes found. The most recent inspection value is used. Access to this value requires a valid trigger.
Get	BCR_RESULT	Data	The decoded barcode data strings. Each string starts and ends with the double quote character. Multiple values are separated by the field delimiter. The most recent inspection value is used. Access to this value requires a valid trigger.
Get	BCR_RESULT	Type	The decoded barcode symbol type(s). Multiple values are separated by the field delimiter. The most recent inspection value is used. Access to this value requires a valid trigger.

### BCR\_HISTORY Command Group

Command	Group	Item	Description
Get	BCR_HISTORY	MinCount	This value indicates the minimum number of barcodes read for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.
Get	BCR_HISTORY	MaxCount	This value indicates the maximum number of barcodes read for the active inspection. This value is cleared (reset) whenever history is cleared. This value is cleared (reset) when the device starts up or is rebooted.

## 5.5.5 Command Channel Command Status Register

The command status is a verification of the command type.

Command Status	Value (16-bit integer)
Unknown	0
Read	1
Write	2
Execute	3

## 5.5.6 Command Channel Error Codes

Table 4: Plus BCR Command Channel Error Codes

Numeric ID	Text ID	Description
00000	SUCCESS	Command processed successfully

Numeric ID	Text ID	Description
10000	EMPTY_FRAME_RECEIVED	Indicates that the request was empty. The command channel requires a command, any arguments, and an end-of-frame delimiter.
10001	COMMAND_NOT_RECOGNIZED	The command specified is not recognized
10100	GROUP_MISSING	A Group ID must be specified immediately after the command
10101	GROUP_NOT_FOUND	The specified Group ID is invalid / unknown
10102	GROUP_ITEM_MISSING	A Group Item ID must be specified immediately after the Group ID
10103	GROUP_ITEM_NOT_FOUND	The specified Group Item ID is invalid / unknown
10152	NOT_READABLE	Attempt to get a value that is not readable
10153	NOT_WRITEABLE	Attempt to set a value that is not writeable
10250	NOT_A_METHOD	Method ID specified is not a method
10251	WRONG_ARGUMENT_COUNT	Total method arguments specified do not match method
10252	COMMAND_NOT_FINISHED	Attempt to issue command when a previous command has not finished
10300	INVALID_ARGUMENT_TYPE	Item ID specified must be a item (not a group or method)
10301	DATA_VALUE_MISSING	Command missing item's data value
10350	ARGUMENTS_DETECTED	Get command received with unneeded arguments
10351	INVALID_ARGUMENT_TYPE	Item ID specified must be a item (not a group or method)
10340	MINIMUM_VALUE_EXCEEDED	New item value is below the minimum
10341	MAXIMUM_VALUE_EXCEEDED	New items value is above the maximum
10500	DATA_SET_EMPTY	Data export operation returned no results.
10900	SENSOR_NOT_READY	Command specified requires sensor to be in the READY state.
10920	SENSOR_TYPE_NOT_ACTIVE	Command specified belongs to a different sensor type.
15000	VALUE_INVALID	Text value is invalid / unknown
15050	VALUE_INVALID	Text value is invalid - expecting True or False
15100	STRING_TOO_LONG	String value specified exceeds maximum allowable length
20000	BARCODE_TIMEOUT	Attempt to obtain Barcode result data when decoder has timed out
20001	NO_BARCODES_FOUND	Attempt to obtain Barcode result data when no barcodes were found
20002	COMPARE_DATA_DISABLED	Operation requires Barcode compare to be enabled
20003	COMPARE_MASK_INVALID	Compare mask invalid. Expecting string of 1's and 0's with length equal to compare data string
20004	NUMBER_TO_FIND_NOT_ONE	Barcode number to find must be set to one for this operation.
80000	REMOTE_DISPLAY_NOT_CONNECTED	Remote Display must be connected to obtain this value
80001	REMOTE_DISPLAY_NOT_SUPPORTED	This sensor does not have Remote Display capability
80100	COMMAND_MODE_EXPECTED	The Trigger Mode must be set to "Command" perform this operation
80101	COMMAND_TIMED_OUT	The command timed out before finishing
80102	TRIGGER_REQUIRED	Access to the specified data requires a triggered inspection
80103	TRIGGER_NOT_GATED	Command requires a active Gated Trigger
80150	COMMAND_TIMED_OUT	The command timed out before finishing
80200	SYSTEM_ERROR_NOT_ACTIVE	The System Error must be active to execute this command

## 6 Industrial Ethernet Overview

### 6.1 Device Setup

#### 6.1.1 Set IP Address

When shipped, the device is assigned a default IP address - 192.168.0.1, a default Subnet Mask - 255.255.255.0, and a default gateway - 0.0.0.0. To change these defaults, click on Main Menu > System > Communications > Ethernet I/O.

#### 6.1.2 Set Industrial Ethernet Protocol (EIP/Modbus/TCP/PCCC)

The Industrial Ethernet communication channel is disabled by default. In order to enable this channel, click on Main Menu > System > Communications > Industrial Ethernet > Connection. Select the channel of interest (EIP, Modbus/TCP or PCCC). Only one type of connection can be established at any given time.

Information about an established connection can be obtained from Main Menu > System > Communications > Industrial Ethernet > Status screen. Click on the connection of interest to view details.

This device provides extensive logging for the communication that occurs over the Industrial Ethernet connection. Logs can either be viewed from Main Menu > System > Communications > Industrial Ethernet > View Logs, or Main Menu > Logs > Communication Logs > Industrial Ethernet.

#### 6.1.3 Set Trigger Mode

The sensor can be triggered using either the hardware trigger or through over the Industrial EtherNet. In order to only accept triggers generated through the Industrial EtherNet communication channel, click on the Main Menu > Imager > Trigger, and select Industrial EtherNet Only from the drop-down menu.

## 6.2 Supported Functions

The iVu Plus Series sensor is controlled over EtherNet/IP and Modbus/TCP using the input and output data it makes available as a slave device for those protocols.

Here are some of the Sensor operations that can be performed using input and output values:

- Product Change
- Teach Enable
- Trigger the sensor
- Read output indicators (pass/fail/ready/error)
- Read counters (pass, fail, system error, missed trigger, frame count, iteration count)
- Read iVu sensor results
- On Barcode, change compare string and its mask

### 6.2.1 iVu Input Values

The operation of the iVu Plus Series sensor can be controlled through input bits and commands.

#### Register/Input Coil Bits

The following commands can only be executed using bits:

Input Coil Bit	Command	Description
0	Product Change	Execute a product change (inspection number specified in the "Product Change Number" 32-bit integer register).
1	Teach Latch	Latch a teach flag. Teach is executed on next trigger.
2	Trigger	Causes system to trigger an inspection if ready.
3	Gated Trigger	Causes system to start looking for requested barcodes (BCR products only)
5	Set BCR String	Sets barcode compare string (BCR products only)
6	Set BCR Mask	Sets masks for barcode compare string (BCR products only)
15	Command	Set this bit to 1 to execute the command entered in the Command ID Register.

## 6.2.2 iVu Output Values

Using output values, the following information can be obtained:

- ACK bits (acknowledgement bits) for input commands, including error codes
- System indicators (Ready, Pass/Fail, Read/No Read, Output signals, Command Error, etc.)
- Inspection History (Iteration Count, Pass Count, Fail Count, etc.)
- Current Inspection Results (data of the sensor type contained in the inspection)
- Command Responses

Refer to the sections on protocols for more information.

### ACK Flags

For each of the Command Flags there is a corresponding ACK flag. The Vision Sensor sets the ACK flag when the corresponding action is complete. Command flags cause actions to occur on the low-to-high transition of that flag. You must clear the command flag after the corresponding ACK flag has been observed to be high.

As an example, to use the Trigger ACK flag, the programming steps for triggering an inspection would be:

1. Wait for ready.
2. Set Trigger command flag to 1.
3. Wait for Trigger ACK to go to 1.
4. Set Trigger command flag to 0.

### Command Responses

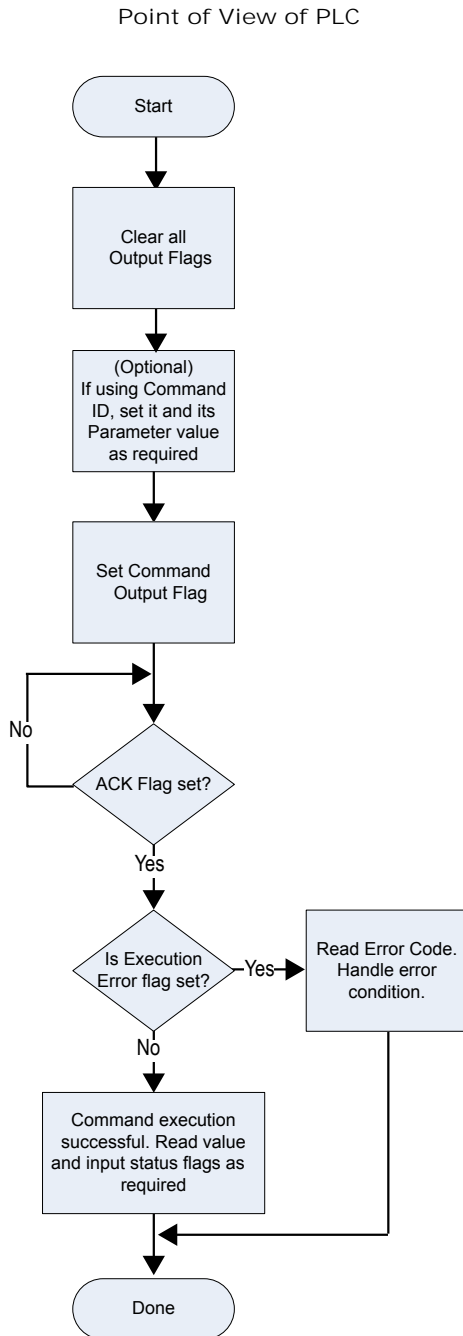
iVu Plus Series Command Channel commands executed using command IDs may have a response value. Depending on the Data Type, the response value will be contained in one or multiple registers. Refer to iVu Command Channel Commands section of this document and the iVu Plus Communication's Users Guide for more information about the iVu Command Channel.

## 6.3 Sensor Operation

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Any Industrial Ethernet protocol can be used to trigger inspections, remote teach and perform command functions. On iVuPlus BCR models, compare strings can also be set.

### 6.3.1 General Command Execution



Following rules apply for the usage of input bit commands:

- Only one output bit can be set at a time.
- Corresponding ACK bits are only set high on completion of the command (if output bit is still high).
- Corresponding ACK bits are cleared when the output bit is cleared.
- When multiple output bits are set simultaneously, the Execution Error input bit is set and an Error Code value is reported on the input register.
- The Execution Error input bit is cleared when all ACK bits get cleared, or a new valid command is received.

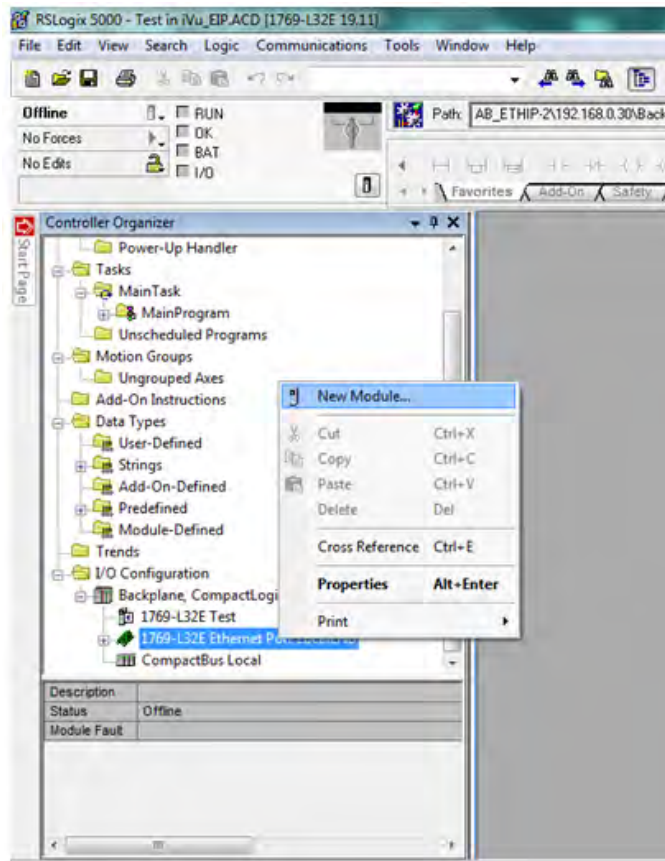
## 6.4 EtherNet/IP

The iVu Plus device is controlled by a ControlLogix PLC using assembly objects. From the point-of-view of a PLC, there are three input assemblies and two output assemblies.

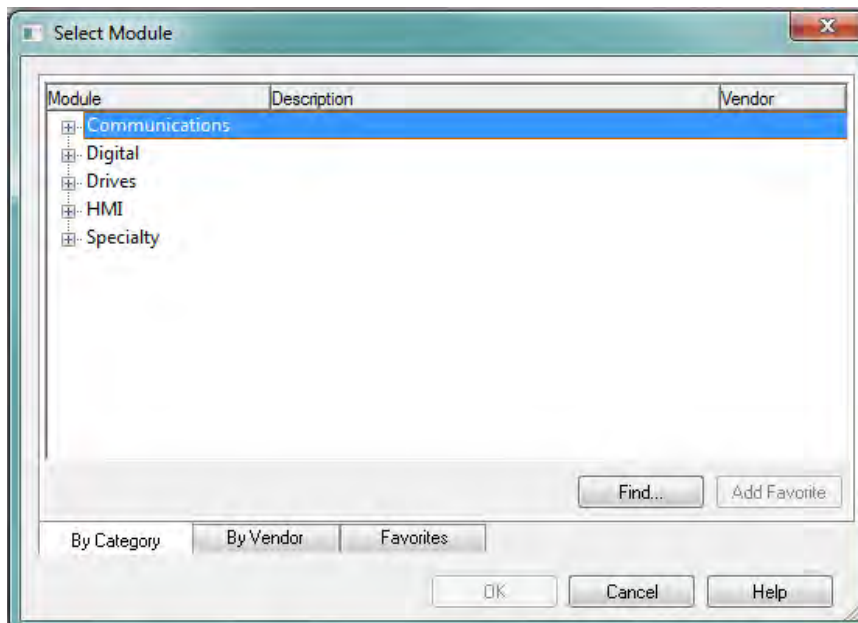
### 6.4.1 RSLogix5000 Configuration

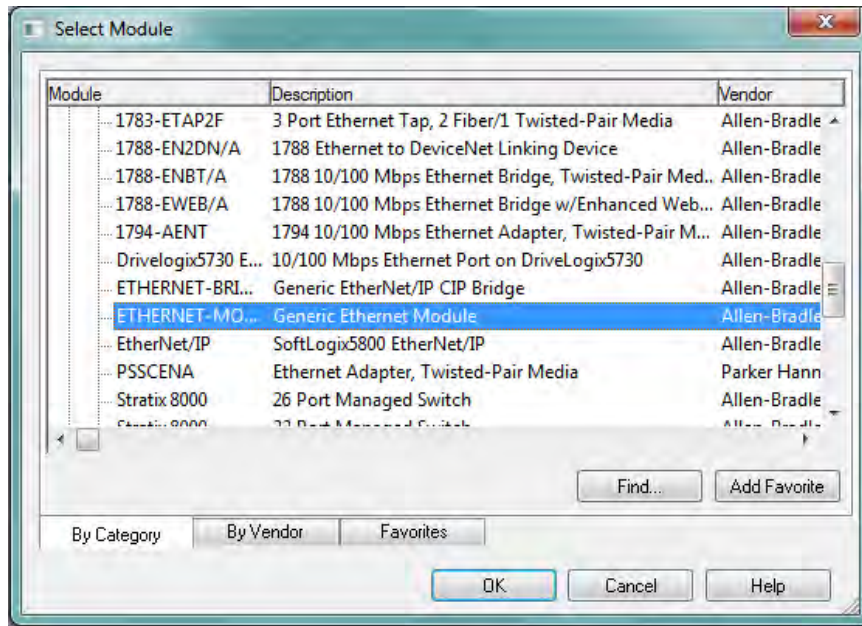
To create an implicit Class 1 configuration to the iVu Plus using EIP when using a ControlLogix family PLC, configure the iVu Plus as a "Generic Ethernet Module" under the ENET\_MODULE. The following is a sample setup of Banner sensor:

1. Add a generic Ethernet module to the PLC's Ethernet card.



2. Select Module.





3. Configure Module Properties.



NOTE: The data type in the Comm Format must be changed to an INT.

See [Inputs to iVu \(Outputs from PLC\)](#) on page 84 and [Outputs from the iVu \(Inputs to the PLC\)](#) on page 85 for more information on each specific assembly instance.

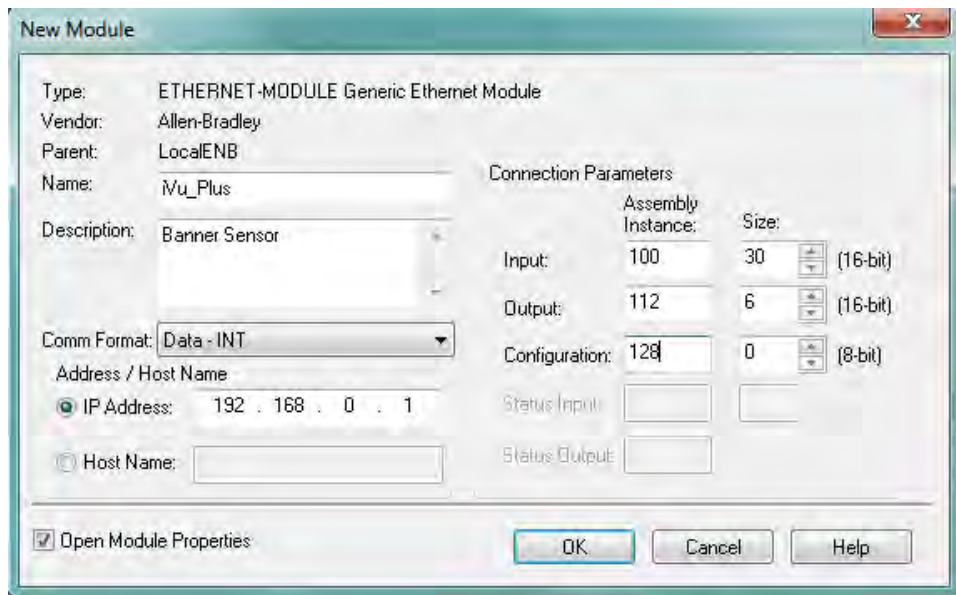


Figure 3. PLC Input Assembly (100), PLC Output Assembly (112)

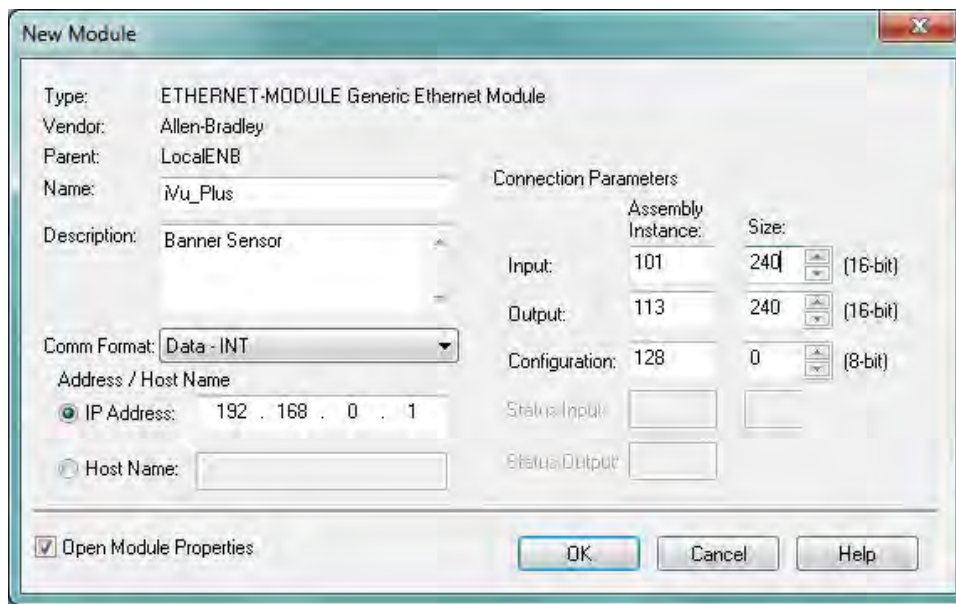


Figure 4. PLC Input Assembly (101), PLC Output Assembly (113)

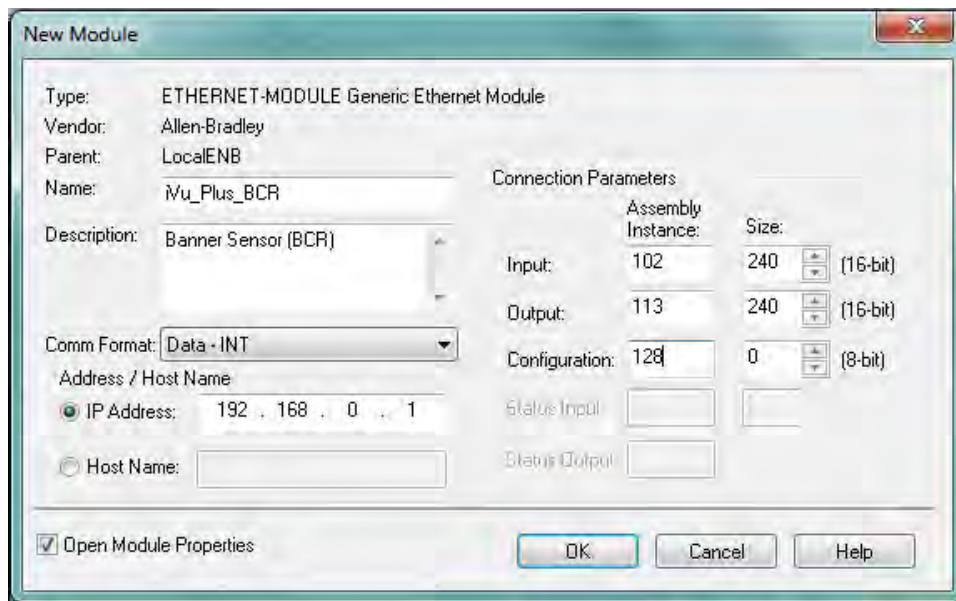


Figure 5. iVu Plus BCR—PLC Input Assembly (102), PLC Output Assembly (113)



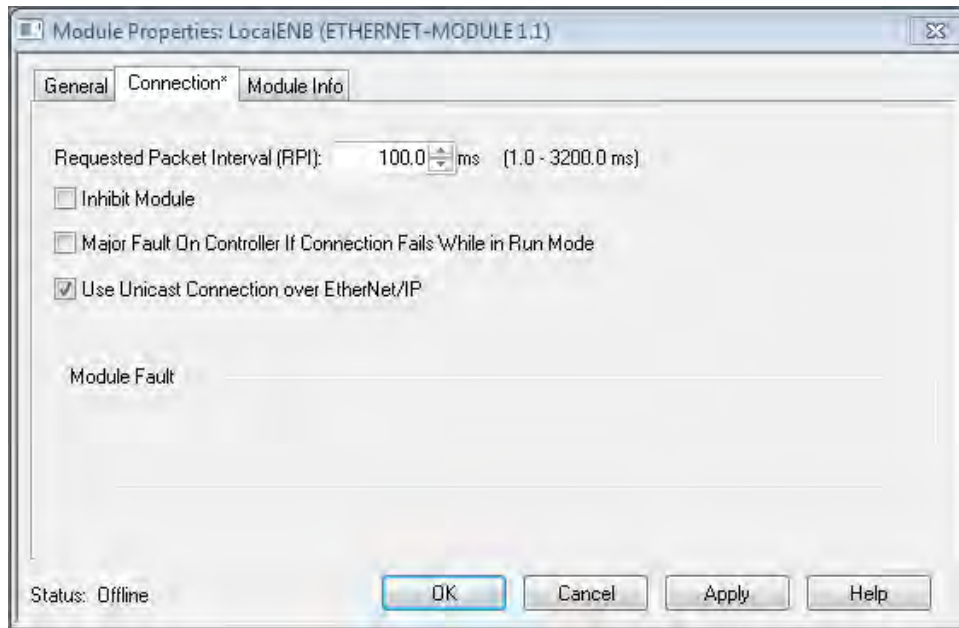
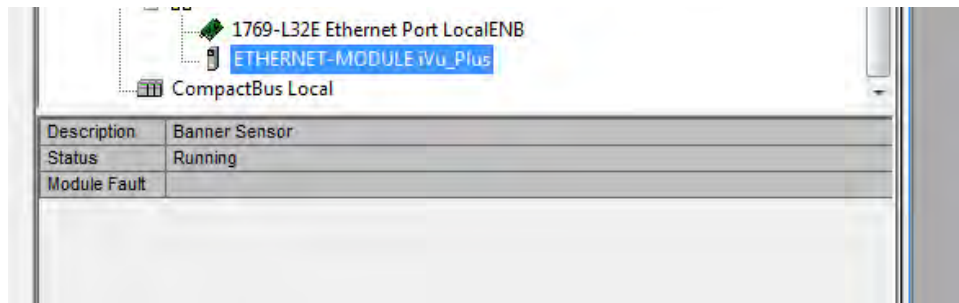


Figure 6. Select or deselect Unicast Connection as desired



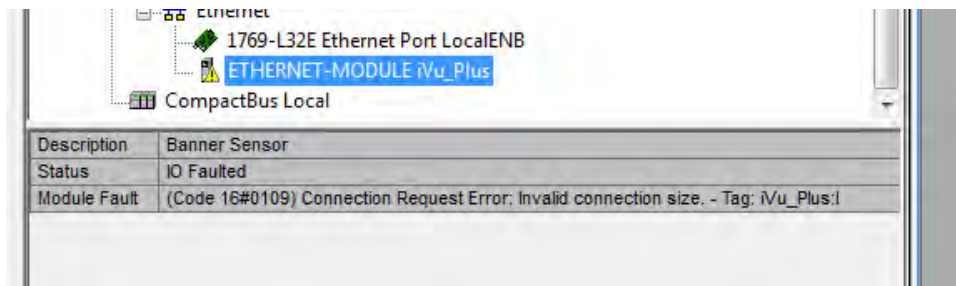
NOTE: The minimum allowed RPI is 50 ms.

4. If the module configuration was successful, the following information should be displayed:

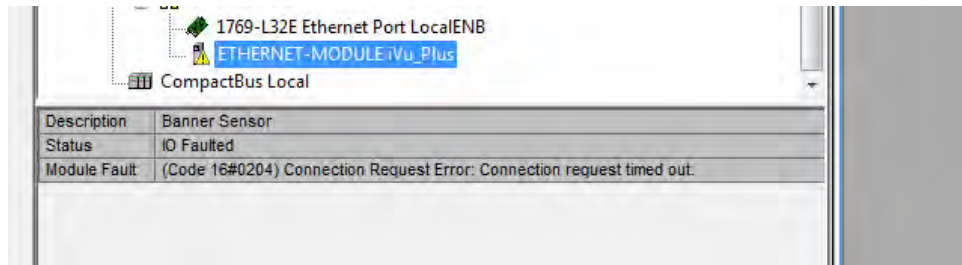


If the module configuration was not successful, the RSLogix 5000 software will indicate errors similar to the ones displayed below:

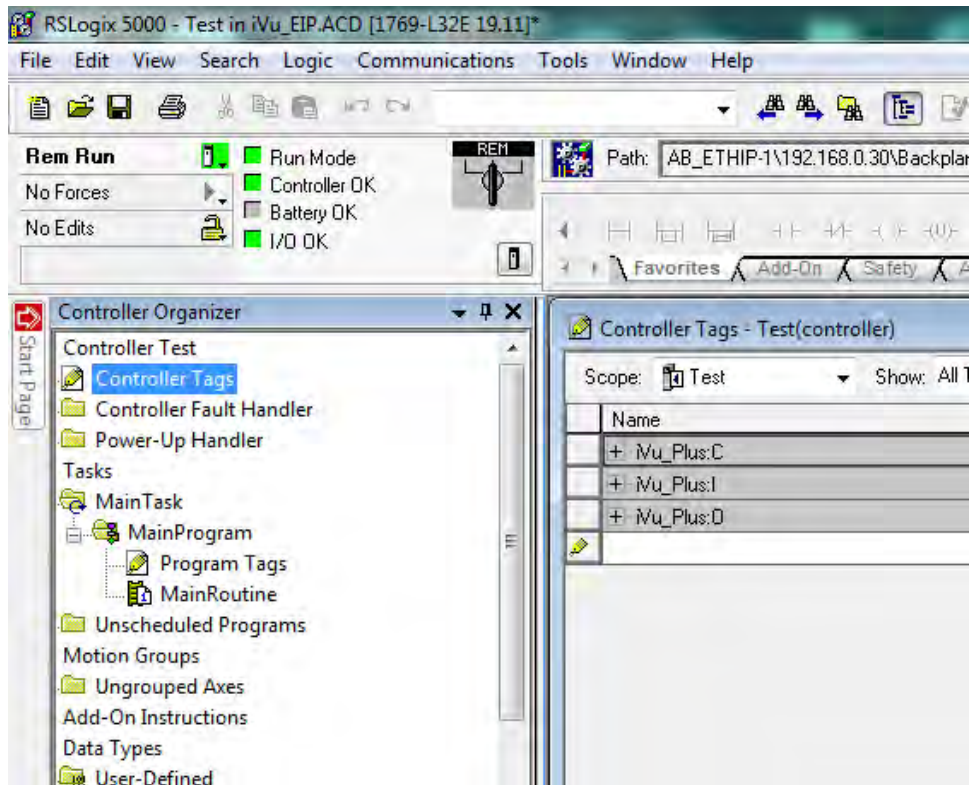
- ERROR: Assembly Instance number and/or size incorrect.



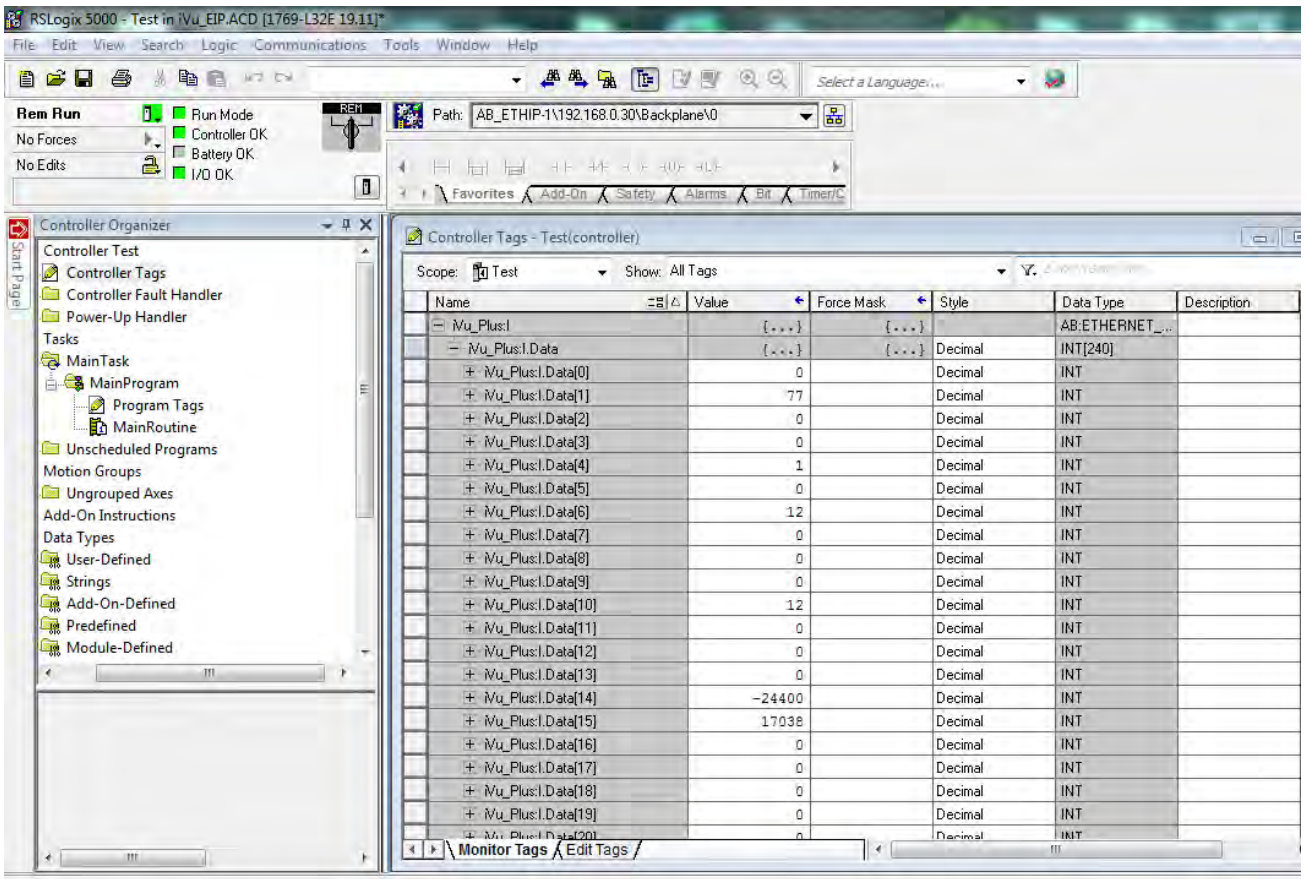
- ERROR: iVu Plus not powered up or EtherNet cable not attached.



5. Locate the memory map setup from Banner module to PLC memory map.



- C = Configuration (not used)
- I = Inputs to PLC (outputs from iVu Plus)
- O = Outputs from PLC (inputs to iVu Plus)



The iVu Plus memory map expanded. I = Inputs to PLC (outputs from iVu Plus).

Sample map demonstrating string values:

Name	Value	Force Mask	Style	Data Type	Description
+ IVu_Plus:I.Data[55]	1		Decimal	INT	
+ IVu_Plus:I.Data[56]	1		Decimal	INT	
+ IVu_Plus:I.Data[57]	1		Decimal	INT	
+ IVu_Plus:I.Data[58]	20		Decimal	INT	
+ IVu_Plus:I.Data[59]	20		Decimal	INT	
+ IVu_Plus:I.Data[60]	0		Decimal	INT	
+ IVu_Plus:I.Data[61]	22121		Decimal	INT	
+ IVu_Plus:I.Data[62]	20597		Decimal	INT	
+ IVu_Plus:I.Data[63]	30060		Decimal	INT	
+ IVu_Plus:I.Data[64]	8307		Decimal	INT	
+ IVu_Plus:I.Data[65]	27977		Decimal	INT	
+ IVu_Plus:I.Data[66]	26465		Decimal	INT	
+ IVu_Plus:I.Data[67]	8293		Decimal	INT	
+ IVu_Plus:I.Data[68]	25939		Decimal	INT	
+ IVu_Plus:I.Data[69]	29550		Decimal	INT	
+ IVu_Plus:I.Data[70]	29295		Decimal	INT	

Figure 7. Memory Map: Default



NOTE: ControlLogix string format. "iVu Plus Image Sensor"

+ iVu_Plus:I.Data[55]	1	Decimal	INT
+ iVu_Plus:I.Data[56]	1	Decimal	INT
+ iVu_Plus:I.Data[57]	1	Decimal	INT
+ iVu_Plus:I.Data[58]	20	Decimal	INT
+ iVu_Plus:I.Data[59]	20	Decimal	INT
+ iVu_Plus:I.Data[60]	0	Decimal	INT
+ iVu_Plus:I.Data[61]	'Vi'	ASCII	INT
+ iVu_Plus:I.Data[62]	'Pu'	ASCII	INT
+ iVu_Plus:I.Data[63]	'u1'	ASCII	INT
+ iVu_Plus:I.Data[64]	' s'	ASCII	INT
+ iVu_Plus:I.Data[65]	'mI'	ASCII	INT
+ iVu_Plus:I.Data[66]	'ga'	ASCII	INT
+ iVu_Plus:I.Data[67]	' e'	ASCII	INT
+ iVu_Plus:I.Data[68]	'eS'	ASCII	INT
+ iVu_Plus:I.Data[69]	'sn'	ASCII	INT
+ iVu_Plus:I.Data[70]	'xo'	ASCII	INT

All data is initially transferred as "INT" data type. An ASCII string looks like gibberish in this format. Changing the "style" to ASCII instead of "Decimal" reveals the correct string data.

Figure 8. Memory Map: "Style" changed to ASCII

### 6.4.2 Inputs to iVu (Outputs from PLC)

#### PLC Assembly Instance 0x70 (112) - 6 Registers (iVu Inputs/PLC Outputs)

WORD #	WORD NAME	DATA TYPE
0	Input Bits Register (see <a href="#">Input and Output Flags Bits</a> on page 87)	16-bit integer
1-2	Product Change Number	32-bit integer
3-5	<i>reserved</i>	

#### PLC Assembly Instance 0x71 (113) - 240 Registers (iVu Inputs/PLC Outputs)

WORD #	WORD NAME	DATA TYPE
0	Inputs Bit Register (see <a href="#">Input and Output Flags Bits</a> on page 87)	16-bit integer
1-2	Product Change Number	32-bit integer
3-49	<i>reserved</i>	32-bit integer
50	Command ID	16-bit integer
51	Command Parameter Int16	16-bit integer
52-53	Command Parameter Int32	32-bit integer
54-55	Command Parameter Float	Float
56-57	String Length	32-bit integer
58-107	String Parameter	100 Byte Array
108	<i>reserved</i>	16-bit integer
109-110	Barcode String/Mask Length	32-bit integer
111-210	Barcode String/Mask	200 Byte Array
211-239	<i>reserved</i>	

### 6.4.3 Outputs from the iVu (Inputs to the PLC)

#### PLC Assembly Instance 0x64 (100) - 30 Registers (iVu Outputs/PLC Inputs)

WORD #	WORD NAME	DATA TYPE
0	Input Bits ACK Register (see <a href="#">Input and Output Flags Bits</a> on page 87)	16-bit integer
1	Output Bits Register (see <a href="#">Input and Output Flags Bits</a> on page 87)	16-bit integer
2-3	Error Code	32-bit integer
4-5	Inspection Number	32-bit integer
6-7	Iteration Count	32-bit integer
8-9	Pass Count	32-bit integer
10-11	Fail Count	32-bit integer
12-13	Missed Triggers	32-bit integer
14-15	Current Inspection Time	Float
16	Sensor P/F Coil	
17-29	<i>reserved</i>	

#### PLC Assembly Instance 0x65 (101) - 240 Registers (iVu Outputs/PLC Inputs)

Table 5: Sensor Type - Barcode (iVu Plus BCR)

WORD #	WORD NAME	DATA TYPE
0	Input Bits ACK Register (see <a href="#">Input and Output Flags Bits</a> on page 87)	16-bit integer
1	Output Bits Register (see <a href="#">Input and Output Flags Bits</a> on page 87)	16-bit integer
2-3	Error Code	32-bit integer
4-5	Inspection Number	32-bit integer
6-7	Iteration Count	32-bit integer
8-9	Pass Count	32-bit integer
10-11	Fail Count	32-bit integer
12-13	Missed Triggers	32-bit integer
14-15	Current Inspection Time	Float
16	Sensor Pass/Fail Coil	
17-29	<i>reserved</i>	
30-52	Inspection Name	2-Word Length + 20-unicode chars
53-54	Frame Number	32-bit integer
55	Sensor Type ID	16-bit integer
55	Sensor Type ID	16-bit integer
56	Barcode Count	16-bit integer
57	Barcode-1 Type	16-bit integer
58	Barcode-1 Actual Decoded Data Length	16-bit integer
59-60	Barcode-1 Data Array Length	32-bit integer
61-162	Barcode-1 Data Array	100 Byte Array
163-170	<i>reserved</i>	
171	Command Status	16-bit integer
172	Command Response Int16	16-bit integer
173-174	Command Response Int32	32-bit integer
175-176	Command Response Float	Float
177-178	Command Response Length	32-bit integer
179-228	Command Response Data	100 Byte Array

WORD #	WORD NAME	DATA TYPE
229-239	<i>reserved</i>	

## PLC Assembly Instance 0x66 (102) (iVu Outputs/PLC Inputs)

Table 6: Sensor Type (iVu Plus BCR)

WORD #	WORD NAME	DATA TYPE
0	Input Bits ACK Register (see <a href="#">Input and Output Flags Bits</a> on page 87)	16-bit integer
1	Output Bits Register (see <a href="#">Input and Output Flags Bits</a> on page 87)	16-bit integer
2-3	Error Code	32-bit integer
4-5	Inspection Number	32-bit integer
6-7	Iteration Count	32-bit integer
8-9	Pass Count	32-bit integer
10-11	Fail Count	32-bit integer
12-13	Missed Triggers	32-bit integer
14-15	Current Inspection Time	Float
16	Sensor Pass/Fail Coil	
17-29	<i>reserved</i>	
30	Barcode Count	16-bit integer
31	Barcode-1 Type	16-bit integer
32	Barcode-1 Length	16-bit integer
33-50	Barcode-1 Data	32-bit length + 32-byte array
51	Barcode-2 Type	16-bit integer
52	Barcode-2 Length	16-bit integer
53-70	Barcode-2 Data	32-bit length + 32-byte array
71	Barcode-3 Type	16-bit integer
72	Barcode-3 Length	16-bit integer
73-90	Barcode-3 Data	32-bit length + 32-byte array
91	Barcode-4 Type	16-bit integer
92	Barcode-4 Length	16-bit integer
93-110	Barcode-4 Data	32-bit length + 32-byte array
111	Barcode-5 Type	16-bit integer
112	Barcode-5 Length	16-bit integer
113-130	Barcode-5 Data	32-bit length + 32-byte array
131	Barcode-6 Type	16-bit integer
132	Barcode-6 Length	16-bit integer
133-150	Barcode-6 Data	32-bit length + 32-byte array
151	Barcode-7 Type	16-bit integer
152	Barcode-7 Length	16-bit integer
153-170	Barcode-7 Data	32-bit length + 32-byte array
171	Barcode-8 Type	16-bit integer
172	Barcode-8 Length	16-bit integer
173-190	Barcode-8 Data	32-bit length + 32-byte array
191	Barcode-9 Type	16-bit integer
192	Barcode-9 Length	16-bit integer
193-210	Barcode-9 Data	32-bit length + 32-byte array
211	Barcode-10 Type	16-bit integer

WORD #	WORD NAME	DATA TYPE
212	Barcode-10 Length	16-bit integer
213-230	Barcode-10 Data	32-bit length + 32-byte array
231-239	<i>reserved</i>	

### 6.4.4 Input and Output Flags Bits

Inputs Bits Register (Command Flag Bits)

#### Bit Position

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Command									Set BCR Mask	Set BCR String		Gated Trigger	Trigger	Teach Latch	Product Change

Input Bits ACK Register (ACK Flag Bits)

#### Bit Position

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Command ACK									Set BCR Mask ACK	Set BCR String ACK		Gated Trigger ACK	Trigger ACK	Teach Latch ACK	Product Change ACK

Output Bits Register (iVu Status Flag Bits)

#### Bit Position

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Execution Error	System Error	Teach Error	Missed Trigger					Output 3	Output 2	Output 1		Ready Latch	Read/No Read	Pass/Fail	Ready

### 6.4.5 Configuration Assembly Object

The iVuPlus EIP implementation does not support an assembly object configuration instance. However, one is required for creation of implicit Class 1 connections on a ControlLogix family PLC. Therefore, a configuration instance is defined as instance number 0x80 (128 decimal). Its size is zero.

### 6.4.6 Data Formats

The iVuPlus EIP implementation supports 32-bit Integers in LSW\_MSW data format. The least significant word is stored first, then the most significant word. This format is used for Allen-Bradley ControlLogix PLCs.

The string format is compatible with the Allen-Bradley ControlLogix built-in string data type. This format is a 32 bit (DINT) length followed by character bytes (SINT). This results in the following string format as viewed from the iVu Plus:

Word	0	1	2		3		4		...	...
	Length LSW	Length MSW	byte 1	byte 0	byte 3	byte 2	byte 5	byte 4		

## 6.4.7 Minimum Requested Packet Interval (RPI) Value

iVuPlus devices can operate with input and output Requested Packet Intervals (RPis) as low as 50 milliseconds. The device may not operate reliably if a lower RPI value is selected.

## 6.5 Modbus/TCP

The Modbus/TCP protocol provides device control using register and coil banks defined by the slave device. This section defines the iVu Plus Modbus/TCP register and coil banks. From the point of view of the slave device (PLC), there is one output coil registers and two Input Coil registers. The bits in the Output Coil Registers cause actions to occur. The corresponding ACK bits in the Input Coil register get set when the action is complete. The Status Coil register provides status of certain system states. By specification, Modbus/TCP uses TCP port 502.

Note that the output coils correspond to the Output and ACK Flags, and the input coils correspond to the Input Flags.

Modbus Function Codes Supported:

- 01: Read Coil Status
- 02: Read Input Status
- 03: Read Holding Registers
- 04: Read Input Registers
- 05: Force Single Coil
- 06: Preset Single Register
- 07: Read Exception Status
- 15: Write Multiple Coils
- 16: Preset Multiple Registers

### 6.5.1 Holding Registers

The Holding registers are used by the PLC to push values to the iVu Plus sensor. These values are accessed in the register address range of 40001 - 40240. To write, use Function Codes 6/16 (Preset Single/Multiple Registers). Also available in this range of registers are the registers containing output data. These outputs are available using the address range of 41001 - 41480. To read these output into the PLC use Function Code 03 (Read Holding Registers).

Table 7: Modbus/TCP iVu Input Registers Map

REGISTER	WORD NAME	DATA TYPE
40001	Input Coil Bits (see <i>Input and Output Coils</i> on page 90)	16-bit integer
40002-3	Product Change Number	32-bit integer
40004-50	<i>reserved</i>	32-bit integer
40051	Command ID	16-bit integer
40052	Command Parameter Int16	16-bit integer
40053-54	Command Parameter Int 32	32-bit integer
40055-56	Command Parameter	Float
40057-58	Command Parameter String Length	32-bit integer
40059-108	Command Parameter String	100 Byte Array
40109	<i>reserved</i>	16-bit integer
40110-111	BCR String/Mask Length	32-bit integer
40112-211	BCR String/Mask	200 Byte Array
40212-240	<i>reserved</i>	



## 6.5.2 Output Registers

The Output registers are used to send output values from the iVu Plus to the PLC. Note that some devices (such as Modicon family PLCs) cannot access data using the 30000 range of register addresses. For these devices, the output values are also available using the 40000 range of addresses (at offset 41000). To access the Modbus/TCP Output Registers use Function Code 04 (Read Input Registers).

### Output Registers Map

Table 8: Sensor Type - Barcode-1 (iVu Plus BCR)

REGISTER	WORD NAME	DATA TYPE
30001	Input Coil ACK Bits (see <a href="#">Input and Output Coils</a> on page 90)	16-bit integer
30002	Status Coil Bits (see <a href="#">Input and Output Coils</a> on page 90)	16-bit integer
3003-4	Error Code	32-bit integer
30005-6	Inspection Number	32-bit integer
30007-8	Iteration Count	32-bit integer
30009-10	Pass Count	32-bit integer
30011-12	Fail Count	32-bit integer
30013-14	Missed Triggers	32-bit integer
30015-16	Current Inspection Time	Float
30017	Sensor Pass/Fail Coil	
30018-30	<i>reserved</i>	
30031-53	Inspection Name	2-Word Length + 20-unicode chars
30054-55	Frame Number	32-bit integer
30056	Sensor Type ID	16-bit integer
30057	Barcode Count	16-bit integer
30058	Barcode-1 Type	16-bit integer
30059	Barcode-1 Actual Decoded Data Length	16-bit integer
30060-61	Barcode-1 Data Array Len.	32-bit integer
30062-163	Barcode-1 Data Array	100 Byte Array
30164-171	<i>reserved</i>	
30172	Command Status	16-bit integer
30173	Command Response Int16	16-bit integer
30174-75	Command Response Int32	32-bit integer
30176-77	Command Response	Float
30178-79	Command Response Len.	32-bit integer
30180-229	Command Response Data	100 Byte Array
30230-240	<i>reserved</i>	
30241	Barcode Count	16-bit integer
30242	Barcode-1 Type	16-bit integer

REGISTER	WORD NAME	DATA TYPE
30243	Barcode-1 Length	16-bit integer
30244-61	Barcode-1 Data	32-bit length + 32-byte array
30262	Barcode-2 Type	16-bit integer
30263	Barcode-2 Length	16-bit integer
30264-81	Barcode-2 Data	32-bit length + 32-byte array
30282	Barcode-3 Type	16-bit integer
30283	Barcode-3 Length	16-bit integer
30284-301	Barcode-3 Data	32-bit length + 32-byte array
30302	Barcode-4 Type	16-bit integer
30303	Barcode-4 Length	16-bit integer
30304-21	Barcode-4 Data	32-bit length + 32-byte array
30322	Barcode-5 Type	16-bit integer
30323	Barcode-5 Length	16-bit integer
30324-41	Barcode-5 Data	32-bit length + 32-byte array
30342	Barcode-6 Type	16-bit integer
30343	Barcode-6 Length	16-bit integer
30344-61	Barcode-6 Data	32-bit length + 32-byte array
30362	Barcode-7 Type	16-bit integer
30363	Barcode-7 Length	16-bit integer
30364-81	Barcode-7 Data	32-bit length + 32-byte array
30382	Barcode-8 Type	16-bit integer
30383	Barcode-8 Length	16-bit integer
30384-401	Barcode-8 Data	32-bit length + 32-byte array
30402	Barcode-9 Type	16-bit integer
30403	Barcode-9 Length	16-bit integer
30404-21	Barcode-9 Data	32-bit len + 32-byte array
304022	Barcode-10 Type	16-bit integer
30423	Barcode-10 Length	16-bit integer
30424-41	Barcode-10 Data	32-bit len + 32-byte array

### 6.5.3 Input and Output Coils

The Modbus/TCP Input Coil Bits are used to push single bit commands from the PLC/HMI to the iVu Plus sensor. To access the Modbus/TCP Coil ACK Bits (reg. 30001) and Status Coil Bits (reg. 30002) use Function Code 02 (Read Input Status).

## Input Coil Bits

## Bit Position

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Command									Set BCR Mask	Set BCR String		Gated Trigger	Trigger	Teach Latch	Product Change

## Input Coil ACK Bits

## Bit Position

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Command ACK									Set BCR Mask ACK	Set BCR String ACK		Gated Trigger ACK	Trigger ACK	Teach Latch ACK	Product Change ACK

## Status Coil Bits

## Bit Position

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Execution Error	System Error	Teach Error	Missed Trigger					Output 3	Output 2	Output 1		Ready Latch	Read/No Read	Pass/Fail	Ready

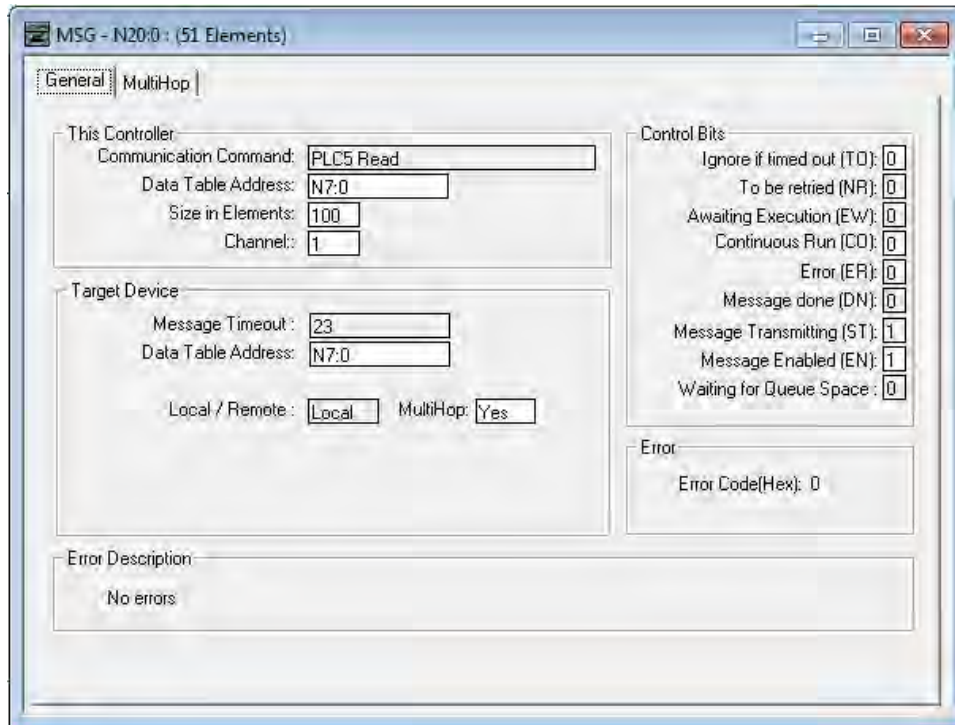
## 6.6 PLC5 and SLC 5 (PCCC)

Allen-Bradley's PLC5 and SLC 500 family of devices use PCCC communications protocol. iVu Plus supports these PLCs using input and output register arrays. The Output Flags, ACK Flags and Input Flags bit definitions are the same as defined in the EIP Assembly Objects section. The terms "Input" and "Output" are from the point of view of the PLC.

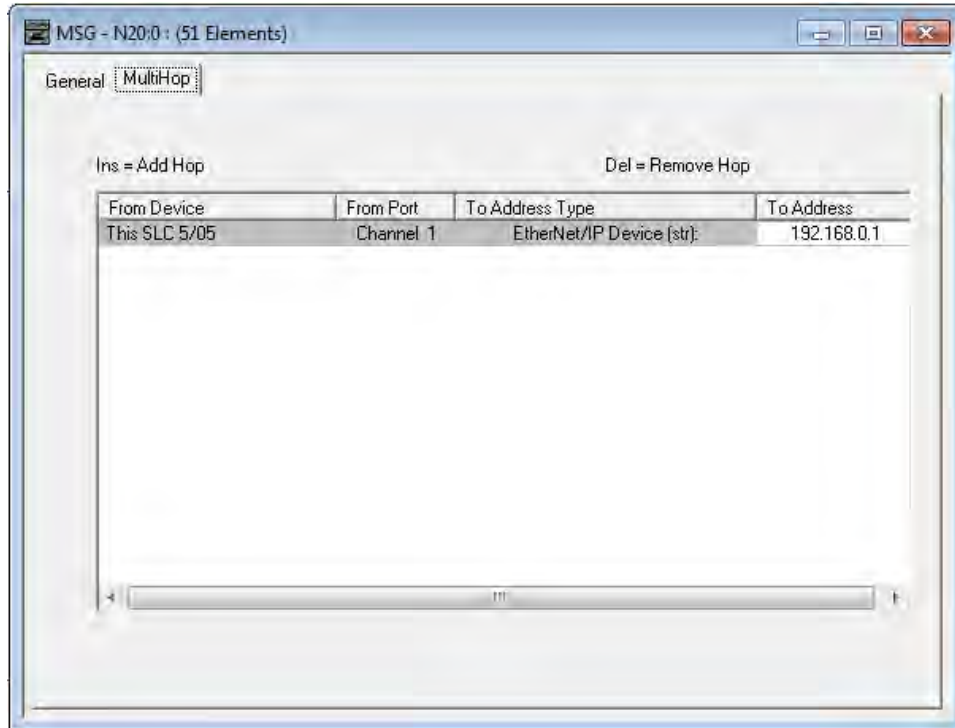
### 6.6.1 Configuration

The images below represent a typical configuration:

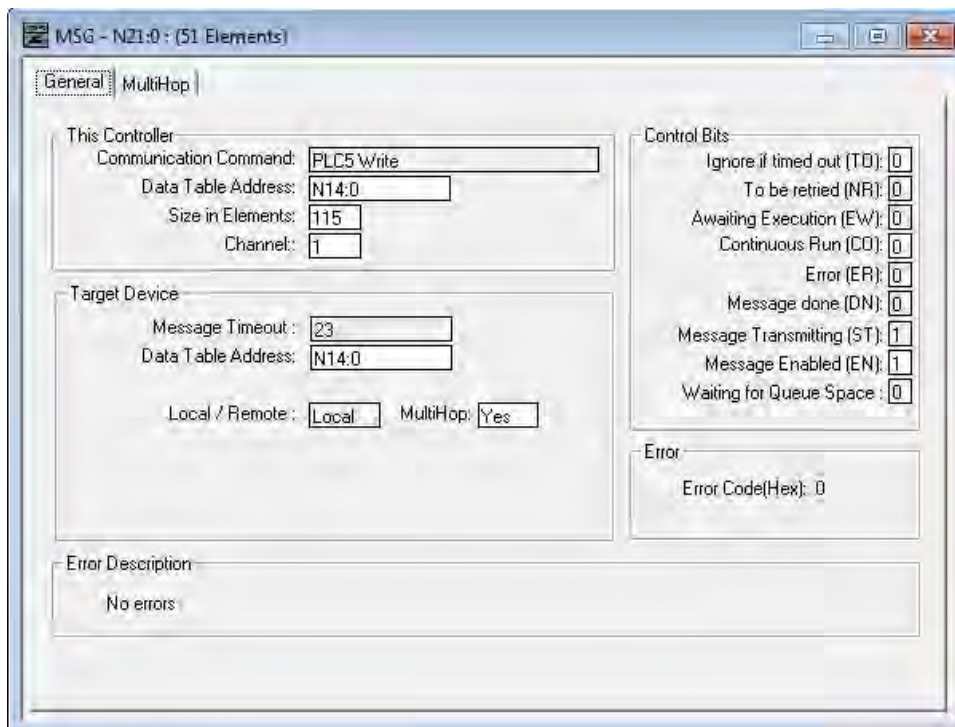
1. Read. Message command\_reading from N7 tabe on iVu Plus



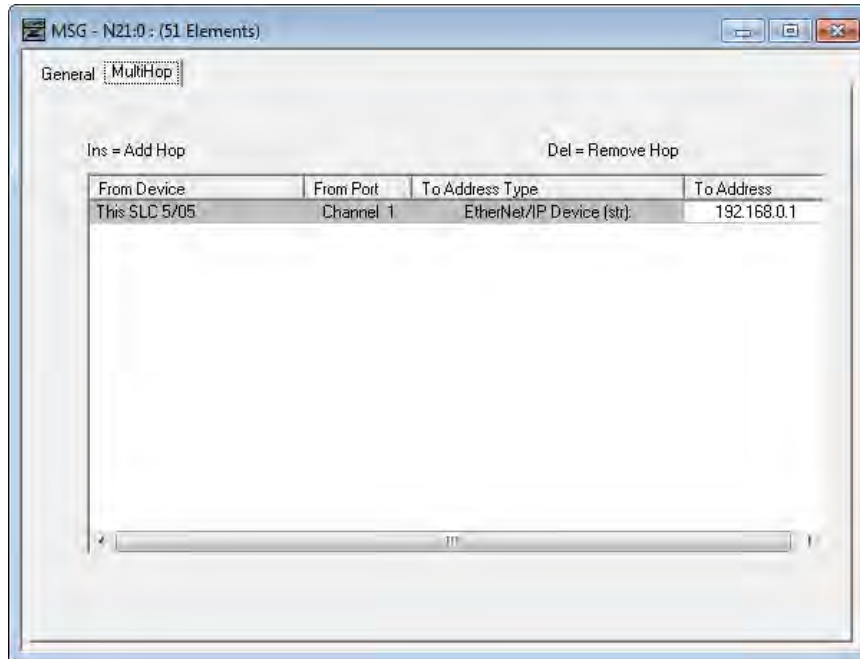
2. Read. IP Address of the iVu Plus is entered here.



3. Write. Message command\_writing to N14 table on iVu Plus



4. Write. IP Address of the iVu Plus is entered here.



### 6.6.2 Inputs to iVu (Outputs from PLC)

The Input registers are used by the PLC to push values to the iVu Plus sensor. MSG (message) commands are used to Read (N7) and Write (N14) to the sensor.

Table 9: PLC Output Registers Map (N14) (iVu Inputs)

WORD #	WORD NAME	DATA TYPE
0	Input Bits Register (see <a href="#">Input and Output Flags</a> on page 96)	16-bit integer
1-2	Product Change Number	32-bit integer
3-49	<i>reserved</i>	32-bit integer
50	Command ID	16-bit integer
51	Command Parameter Int16	16-bit integer
52-53	Command Parameter Int 32	32-bit integer
54-55	Command Parameter	Float
56-57	Command Parameter String Length	32-bit integer
58-107	Command Parameter String	100 Byte Array
108	<i>reserved</i>	16-bit integer
109-110	BCR String/Mask Length	32-bit integer
111-120	BCR String/Mask	200 Byte Array
211-239	<i>reserved</i>	

### 6.6.3 Outputs from iVu (Inputs to PLC)

The Output registers are used to push output values from the iVu Plus to the PLC. MSG (message) commands are used to Read (N7) and Write (N14) to the sensor.

PLC Input Registers Map (N7) (iVu Outputs)

Table 10: Sensor Type - Barcode-1 (iVu Plus BCR)

WORD #	WORD NAME	DATA TYPE
0	Input Bits ACK Register (see <a href="#">Input and Output Flags</a> on page 96)	16-bit integer
1	Output Bits Register (see <a href="#">Input and Output Flags</a> on page 96)	16-bit integer
2-3	Error Code	32-bit integer
4-5	Inspection Number	32-bit integer
6-7	Iteration Count	32-bit integer
8-9	Pass Count	32-bit integer
10-11	Fail Count	32-bit integer
12-13	Missed Triggers	32-bit integer
14-15	Current Inspection Time	Float
16	Sensor Pass/Fail Coil	
17-29	<i>reserved</i>	
30-52	Inspection Name	2-Word Length + 20-unicode chars
53-54	Frame Number	32-bit integer
55	Sensor Type ID	16-bit integer
56	Barcode Count	16-bit integer
57	Barcode-1 Type	16-bit integer
58	Barcode-1 Actual Decoded Data Length	16-bit integer
59-60	Barcode-1 Data Array Length	32-bit integer
61-162	Barcode-1 Data Array	100 Byte Array
163-170	<i>reserved</i>	
171	Command Status	16-bit integer
172	Command Response Int16	16-bit integer
173-174	Command Response Int32	32-bit integer
175-176	Command Response	Float
177-178	Command Response Length	32-bit integer
179-228	Command Response Data	100 Byte Array
229-239	<i>reserved</i>	
240	Barcode Count	16-bit integer
241	Barcode-1 Type	16-bit integer
242	Barcode-1 Length	16-bit integer
243-260	Barcode-1 Data	32-bit length + 32-byte array
261	Barcode-2 Type	16-bit integer
262	Barcode-2 Length	16-bit integer
263-280	Barcode-2 Data	32-bit length + 32-byte array
281	Barcode-3 Type	16-bit integer
282	Barcode-3 Length	16-bit integer
283-300	Barcode-3 Data	32-bit length + 32-byte array
301	Barcode-4 Type	16-bit integer
302	Barcode-4 Length	16-bit integer
303-320	Barcode-4 Data	32-bit length + 32-byte array
321	Barcode-5 Type	16-bit integer
322	Barcode-5 Length	16-bit integer
323-340	Barcode-5 Data	32-bit length + 32-byte array
341	Barcode-6 Type	16-bit integer
342	Barcode-6 Length	16-bit integer

WORD #	WORD NAME	DATA TYPE
343-360	Barcode-6 Data	32-bit length + 32-byte array
361	Barcode-7 Type	16-bit integer
362	Barcode-7 Length	16-bit integer
363-380	Barcode-7 Data	32-bit length + 32-byte array
381	Barcode-8 Type	16-bit integer
382	Barcode-8 Length	16-bit integer
383-400	Barcode-8 Data	32-bit length + 32-byte array
401	Barcode-9 Type	16-bit integer
402	Barcode-9 Length	16-bit integer
403-420	Barcode-9 Data	32-bit length + 32-byte array
421	Barcode-10 Type	16-bit integer
422	Barcode-10 Length	16-bit integer
423-440	Barcode-10 Data	32-bit length + 32-byte array

### 6.6.4 Input and Output Flags

The Input Bits are used to command execution of basic functions. The Output Bits are used to push single bit outputs from the iVu Sensor to the PLC. The 32 bits of iVu output can also be accessed using the bits of the first two Output Registers (Input Bits ACK Register(word 0) and Output Bits Register (word1)).

#### Input Bits Register

##### Bit Position

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Command									Set BCR Mask	Set BCR String		Gated Trigger	Trigger	Teach Latch	Product Change

#### Input Bits ACK Register

##### Bit Position

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Command ACK									Set BCR Mask ACK	Set BCR String ACK		Gated Trigger ACK	Trigger ACK	Teach Latch ACK	Product Change ACK

#### Output Bits Register

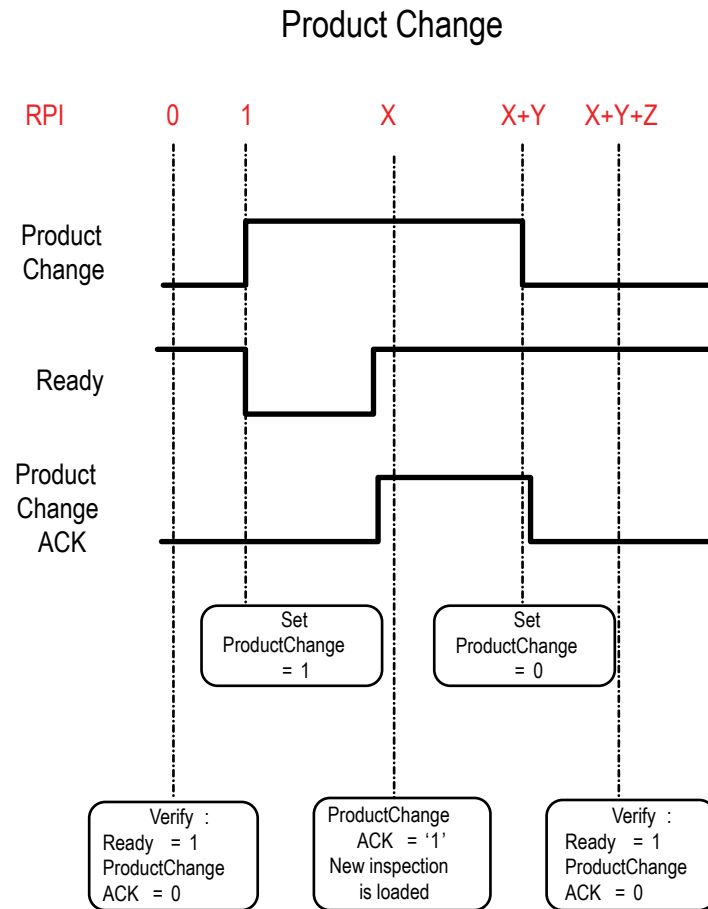
##### Bit Position

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Execution Error	System Error	Teach Error	Missed Trigger					Output 3	Output 2	Output 1		Ready Latch	Read/No Read	Pass/Fail	Ready

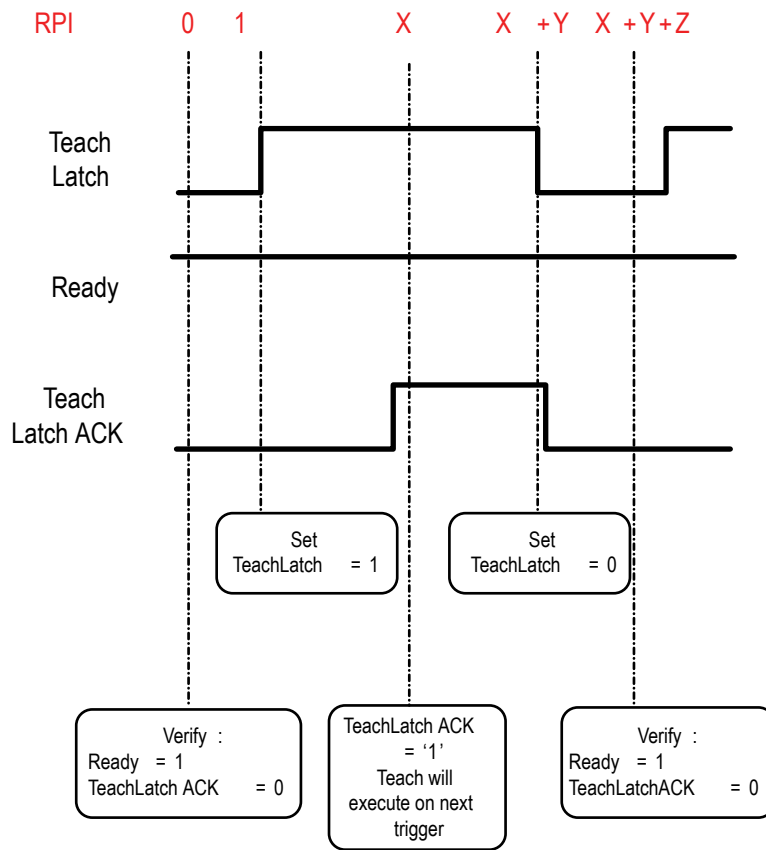


## 6.7 Sample Timing Diagram

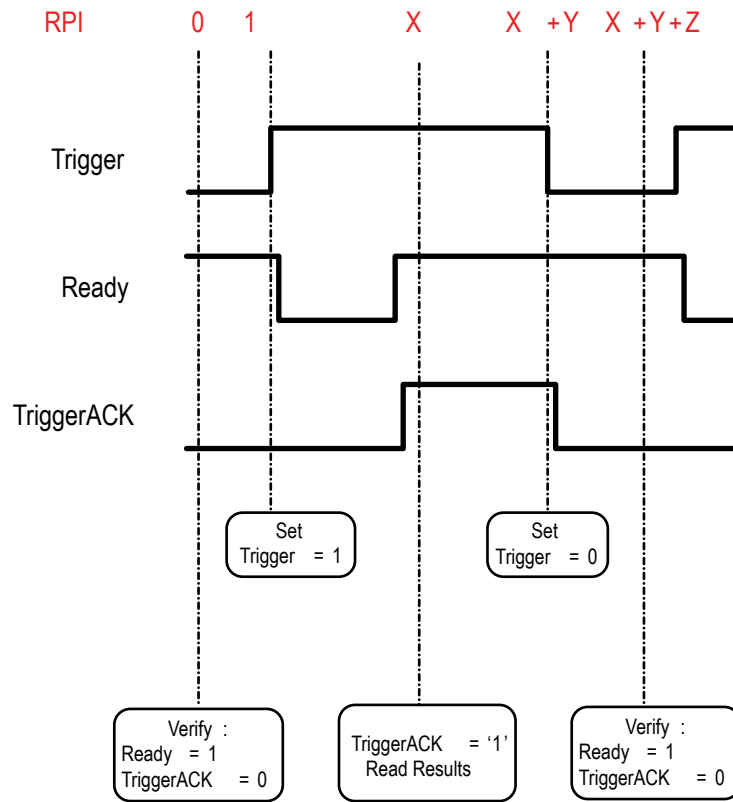
X, Y, Z: Represent snapshot in time



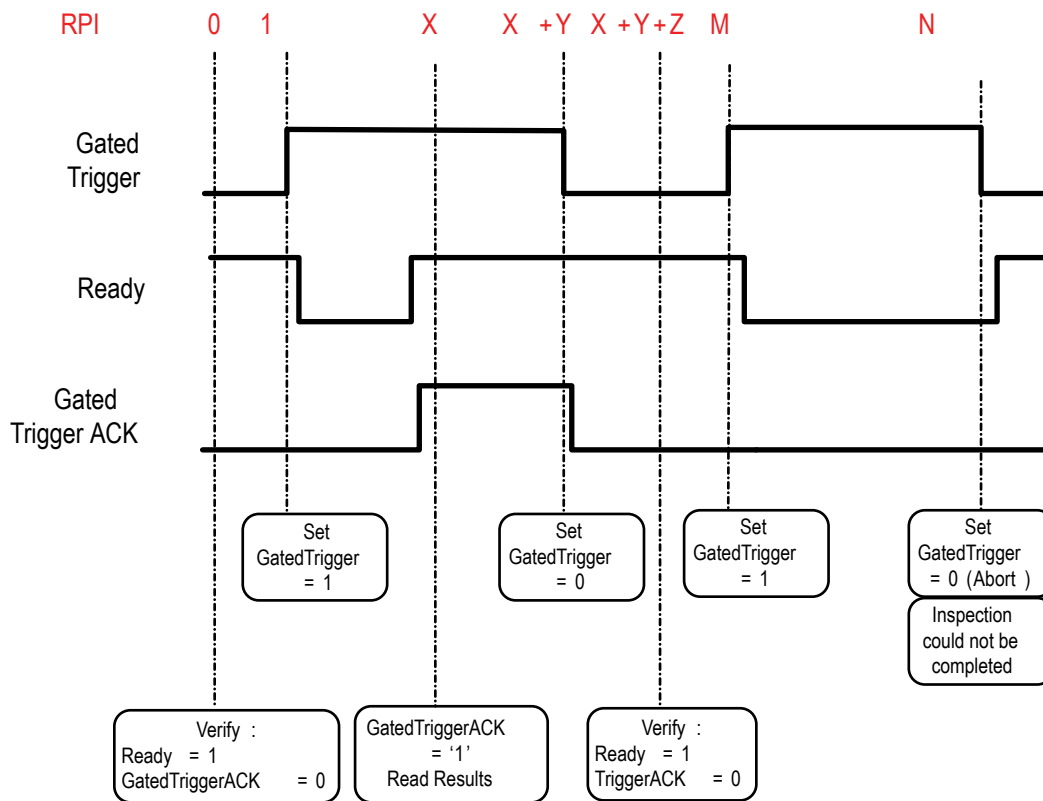
### Teach Latch



## Trigger



## Gated Trigger



## 6.8 Command Channel Command Status Register

The command status is a verification of the command type.

Command Status	Value (16-bit integer)
Unknown	0
Read	1
Write	2
Execute	3

## 6.9 Diagnostic Guide

iVu Plus sensors provide several methods to help diagnose communication issues when using Ethernet communications.

### 6.9.1 Ethernet Diagnostics

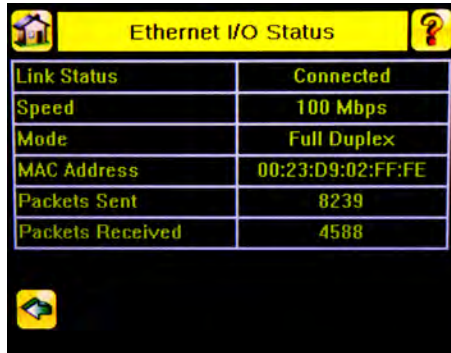
To verify Ethernet connectivity, follow these steps:

1. Verify that all the cables are connected and properly seated.

2. Examine the small orange Ethernet link light located on the top of camera body, between the Pass/Fail and System Status LEDs. The light should be either on or blinking.
3. Go to the System > Logs > System Log page, and verify that the log entry indicates that the Ethernet link is up:



4. Go to the System > Communications > Ethernet I/O page, and press on the Status button. Verify that the Ethernet Link Status is "Connected", and that the link parameters, such as baud rate and duplex are as expected. For example:

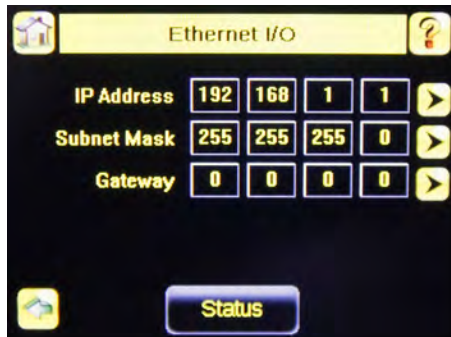


5. If the Link Status indicates that there is no link, please inspect the wiring, and verify that your Ethernet switch is powered up.
6. If the link parameters are not as expected (wrong baud rate or duplex) try the following:
  - a. Log into your managed switch and verify that the port to which iVu camera is connected is correctly configured. Alternatively, consult with your IT person to perform this verification.
  - b. Verify that your cable is of the right type, and is properly connected to the switch and to the camera.

### 6.9.2 Networking and TCP/IP Diagnostics

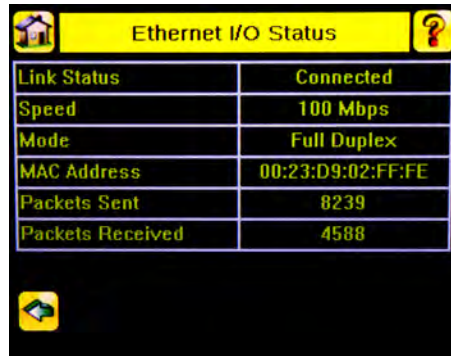
To verify networking and TCP/IP connectivity, follow these steps:

1. Verify that the Ethernet link has been established.
2. Visit the System > Communications > Ethernet I/O page, and examine the sensor IP address, subnet mask, and the Gateway address:

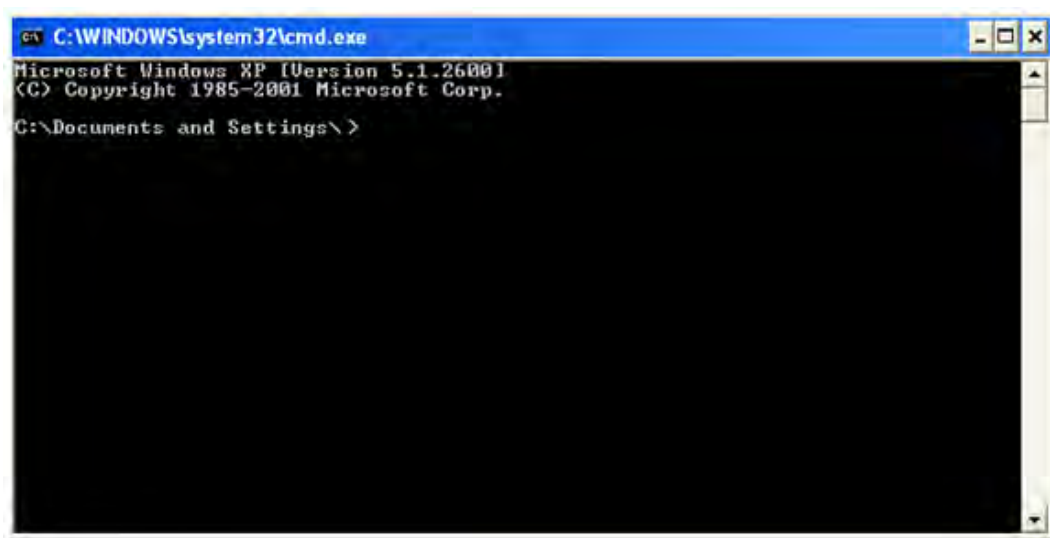


3. Verify with your IT person that these settings are correct.
  - If necessary, make the required modifications and reboot the sensor

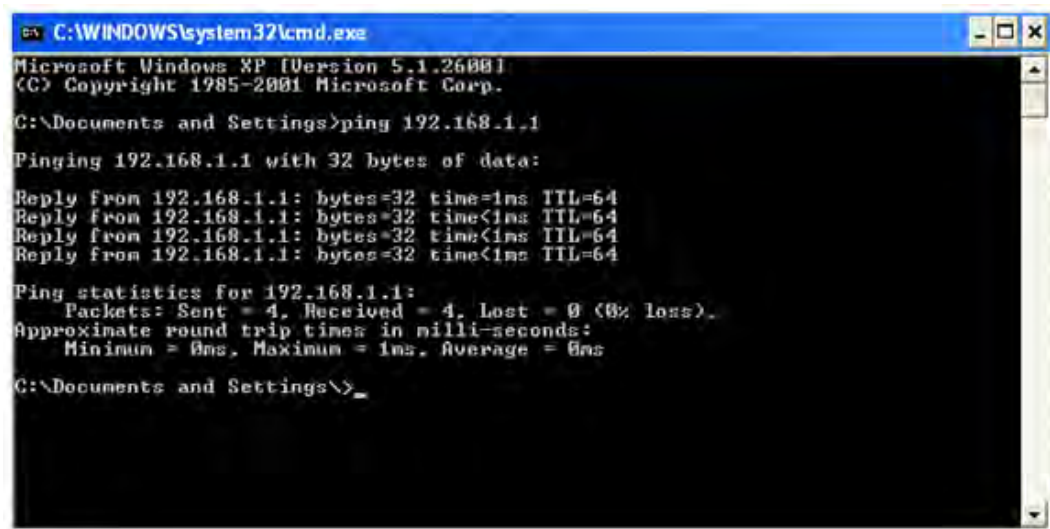
- Press the Status button on the same page, and go to the Ethernet I/O Status page:



- On the PC attached to your LAN, open the Command window. To do this, press Start > Run, and then type in `cmd` and press the OK button.
- A command window will display:



- Type in a ping command, specifying the sensor IP address as an argument. You should see a series of responses from the camera:



8. You should also see the Packets Received and Packets Sent count on the Ethernet I/O Status page in the camera increment by at least 4.
9. If the output of the ping command shows request timeouts, try the following:
  - Verify that the camera is located on the correct subnet, has the correct IP address, and is connected to the correct switch or router.
  - If you are running several overlapping subnets, you may want to consult your IT person to ensure that the routing for the network is configured correctly.
  - If you are trying to access the camera through a gateway or a VPN router, please verify that these devices are configured such that they allow traffic from iVu camera to reach the destination device.

### 6.9.3 Industrial Protocols Troubleshooting

#### Modbus/TCP Protocol

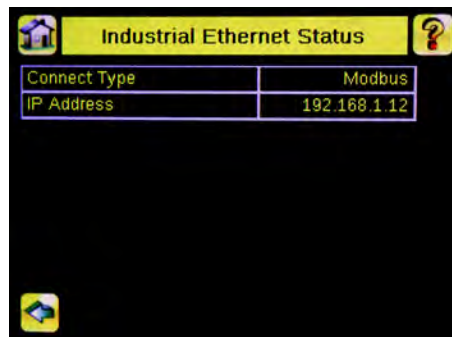
Modbus/TCP protocol relies on the fundamental TCP/IP connectivity to establish connections and transport data. Once you have verified Networking and TCP/IP connectivity, you should have little or no problems establishing a Modbus/TCP connection.

iVu supports one Modbus/TCP connection from a single client, and will reject additional connection requests.

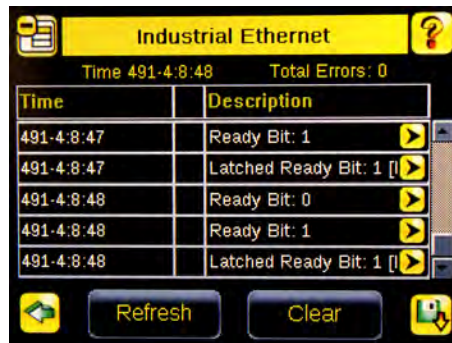
Prior to attempting to establish the Modbus/TCP connection, you will have to configure your device, and teach it about the iVu sensor. You will have to tell it the IP address of the iVu sensor that you have previously configured. Configurations steps vary for each device, so you will have to consult the appropriate manual for these steps.

If your device has user-configurable Modbus/TCP port, please verify that it is set to port number 502. iVu will not accept connections on any other port.

Once you have established a Modbus/TCP connection, you can verify that iVu has accepted it by going to the System > Communications > Industrial Ethernet > Status page, and viewing the connection status:



If you experience issues accessing data, please consult the relevant sections of the manual for the Modbus/TCP register maps supported by the sensor, and consult the Industrial Protocols Log. The log, when configured to Detailed Logging mode, provides record of individual register access sequence, and records any errors:



#### EtherNet/IP and PCCC Protocols

EtherNet/IP and PCCC protocols rely on CIP protocol to establish communications and exchange data. CIP protocol, in turn, utilizes TCP/IP.

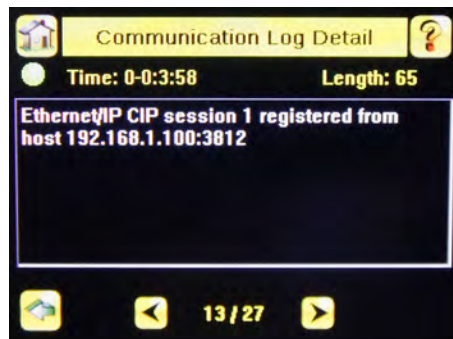
In addition, EtherNet/IP implements I/O messaging. I/O messaging allows two devices, iVu sensor and the PLC, to continuously synchronize data sets between each other. These data sets are called Input and Output Assemblies. iVu device consumes PLC output assemblies, and produces PLC input assemblies. This exchange occurs continuously, and the rate specified by the RPI (requested Packet Interval) value.

I/O messaging is based on UDP/IP, and utilizes Multicast addressing when sending PLC input assemblies. It is the default mode of operation for I/O messages in PLCs. Newer PLCs also support Unicast (direct) addressing for PLC input assemblies, but need to be specially configured.

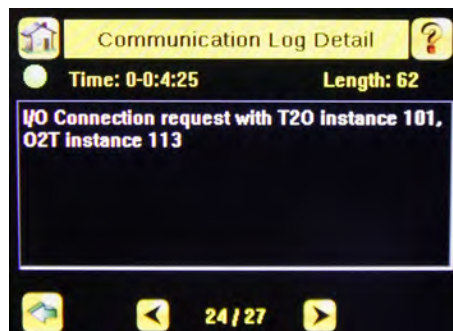
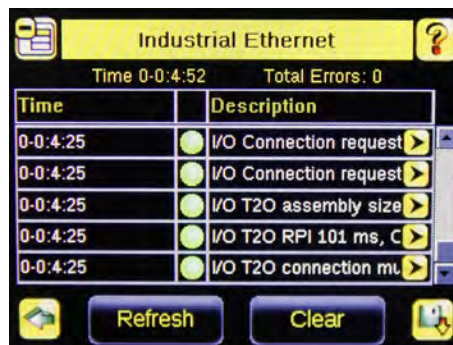
Because I/O messaging uses IDP/IP and Multicast, it requires special, managed switches, and customized switch configuration. Managed switches, when properly configured, prevent multicast devices from flooding the network with data. Please consult your IT person to make sure that you have the correct switch type, and that these switches have IGMP snooping enabled, to allow them to manage multicast groups.

In addition, some switches with built-in firewalls block UDP traffic by default. If this is the case, and if the path between your devices involves several switches or routers, it is possible that some of them might block the UDP traffic necessary for I/O messages. Please consult your IT person to verify that your network is configured correctly. Also consult Rockwell publications ENET-AP001D-EN-P, *EtherNet/IP Performance*, and ENET-SO001A-EN-E, *EtherNet Design Considerations for Control System Networks* for further information on how to configure your EtherNet network for EtherNet/IP.

Establishing CIP and EtherNet/IP I/O communications is a complicated process. There are a number of steps during which an error can occur. Industrial Protocols log contains a detail description of the communications process, and should be consulted if any errors are suspected.

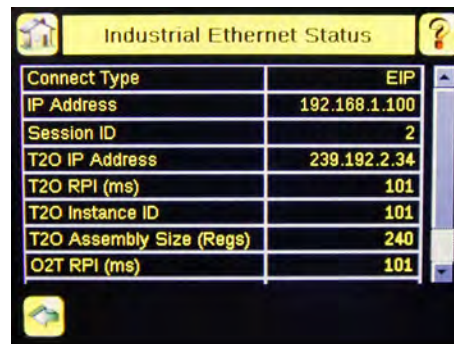


A great level of detail is also provided in the log when the I/O connection is established:





After the CIP and I/O connections are established, the Industrial Protocols Status page will show the details of the connection:



Industrial Ethernet Status	
Connect Type	EIP
IP Address	192.168.1.100
Session ID	2
T2O IP Address	239.192.2.34
T2O RPI (ms)	101
T2O Instance ID	101
T2O Assembly Size (Regs)	240
O2T RPI (ms)	101

Most of the errors in establishing the CIP and I/O connections have to do with specifying the proper Input and Output assembly IDs and sizes. Please refer to the appropriate sections of this manual for this information.

## 6.10 Additional Information

### 6.10.1 iVu Command Channel Commands (iVu Command Channel over Industrial EtherNet)

This section describes how to use the iVu Command Channel over Industrial EtherNet. Please see the iVu Plus Communications User's Guide for more information on the iVu Command Channel protocol. The following commands need to be executed using the Command ID register and the Command Input bit/Input Coil bit.

Command	Command ID			Description	Data Type
	Do	Set	Get		
Trigger					
Trigger Mode		1	10001	The sensor's triggering mode. This value must match the modes supported by the sensor	Int16
Product Change					
Product Change By Name	21			This command forces the sensor to switch to the specified inspection. The sensor does not transmit a response until the sensor has completed the action. Inspections results immediately after a product change will be invalid until a new trigger is received.	Byte Array
Imager					
Gain		51	10051	The sensor's value used to electronically brighten all image pixels	Int32
Exposure		52	10052	The sensor's value used to control the amount of time the imager is allowed to gather light for the image.	Int32
Status					
Clear System Error	81			This command clears the system error LED and resets the internal system error flag to false.	N/A
System					
Reboot Sensor	101			This command reboots the sensor. If sensor configuration data is being currently being saved, this command will block until that operation completes	N/A
Save Configuration	102			This command saves all modified inspection and configuration parameters. This command blocks until all values have been persisted	N/A

Command	Command ID			Description	Data Type
	Do	Set	Get		
Info					
Sensor Name			10151	Sensor user assignable name.	Byte Array
Model Number			10152	Sensor model number	Byte Array
Serial Number			10153	Sensor serial number	Byte Array
Firmware Version			10154	Sensor firmware (software) version	Byte Array
Hour Counter			10155	The total number of hours the sensor has been energized.	Byte Array
History					
Clear History	301			This command clears all history fields for the active inspection. History values include pass count, fail count, execution times and sensor specific history values.	N/A
Inspection					
Inspection Name			10501	The name of the active inspection.	Byte Array
BCR inputs					
Compare String			11001	The Barcode inspection compare data string. This string must start and end with the double quote character	Byte Array
Compare Mask			11002	The Barcode inspection compare string mask in binary format; that is, masked characters are indicated by a "1" and unmasked characters are "0." Note that the mask character string must match the length of the compare string	Byte Array

Trigger Mode	1000	Description
External	1	Inspections will be initiated via the electrical trigger wire
Internal	2	Inspections will run continuously at the specified period (electrical trigger inputs are ignored)
FreeRun	3	Inspections will run continuously (electrical trigger inputs are ignored)
ExternalGated	4	Gated barcode inspection will be started and/or aborted via the electrical trigger wire
ContinuousScan	5	Inspections will run continuously (electrical trigger inputs are ignored)
IndustrialEthernet	10	Inspections will only be triggered by Industrial Ethernet coils and commands.
Command	20	Inspections will only be triggered by the Command Channel trigger commands.

## Error Codes

The iVu Plus sensor provides error codes in cases when commands failed to execute successfully. If such an error occurs, the Execution Error flag is set in the Output Bits/Status Register. When this bit is set, read the Error Code register to know the reason of failure. Below is the list of error codes:

Numeric ID	Text ID	Description
0	SUCCESS	Command processed successfully.
500	IE_TRIGGER_MODE_EXPECTED	The Trigger Mode must be set to 'Industrial Ethernet' to perform this operation.
510	IE_COMMAND_NOT_FOUND	The numeric Command ID specified was not found.
520	IE_COIL_ACTION_FAILED	The coil action resulted in a failure.
521	IE_COIL_ALREADY_BUSY	The coil was asserted before previous execution completed.

Numeric ID	Text ID	Description
522	IE_COIL_NOT_FINISHED	The coil was de-asserted prior to execution completing.
523	IE_COIL_ANOTHER_ACTION_PENDING	The coil was asserted prior to another coil execution completing.
524	IE_COIL_MULTIPLES_DETECTED	Multiple coils were asserted simultaneously.
525	IE_COIL_ACK_INHIBITED	The coil action's output ACK was inhibited because the input coil was no longer set.
00000	SUCCESS	Command processed successfully
10000	EMPTY_FRAME_RECEIVED	Indicates that the request was empty. The command channel requires a command, any arguments, and an end-of-frame delimiter.
10001	COMMAND_NOT_RECOGNIZED	The command specified is not recognized
10100	GROUP_MISSING	A Group ID must be specified immediately after the command
10101	GROUP_NOT_FOUND	The specified Group ID is invalid / unknown
10102	GROUP_ITEM_MISSING	A Group Item ID must be specified immediately after the Group ID
10103	GROUP_ITEM_NOT_FOUND	The specified Group Item ID is invalid / unknown
10152	NOT_READABLE	Attempt to get a value that is not readable
10153	NOT_WRITEABLE	Attempt to set a value that is not writeable
10250	NOT_A_METHOD	Method ID specified is not a method
10251	WRONG_ARGUMENT_COUNT	Total method arguments specified do not match method
10252	COMMAND_NOT_FINISHED	Attempt to issue command when a previous command has not finished
10300	INVALID_ARGUMENT_TYPE	Item ID specified must be a item (not a group or method)
10301	DATA_VALUE_MISSING	Command missing item's data value
10340	MINIMUM_VALUE_EXCEEDED	New item value is below the minimum
10341	MAXIMUM_VALUE_EXCEEDED	New items value is above the maximum
10350	ARGUMENTS_DETECTED	Get command received with unneeded arguments
10351	INVALID_ARGUMENT_TYPE	Item ID specified must be a item (not a group or method)
10500	DATA_SET_EMPTY	Data export operation returned no results.
10900	SENSOR_NOT_READY	Command specified requires sensor to be in the READY state.
10920	SENSOR_TYPE_NOT_ACTIVE	Command specified belongs to a different sensor type.
10950	DEVICE_TYPE_INVALID	Command not supported on this device type.
15000	VALUE_INVALID	Text value is invalid / unknown
15050	VALUE_INVALID	Text value is invalid - expecting True or False
15100	STRING_TOO_LONG	String value specified exceeds maximum allowable length
20002	COMPARE_DATA_DISABLED	Operation requires Barcode compare to be enabled
20003	COMPARE_MASK_INVALID	Compare mask invalid. Expecting string of 1's and 0's with length equal to compare data string
20004	NUMBER_TO_FIND_NOT_ONE	Barcode number to find must be set to one for this operation.
20005	COMPARE_MASK_DISABLED	Operation requires Barcode compare mask to be enabled.
20200	NO_AREAS_FOUND	Attempt to obtain value when no areas were found.
20600	NO_MATCHES_FOUND	Attempt to obtain value when no matches were found.
20800	NO_MATCHES_FOUND	Attempt to obtain value when no sort patterns were found.
80000	REMOTE_DISPLAY_NOT_CONNECTED	Remote Display must be connected to obtain this value
80001	REMOTE_DISPLAY_NOT_SUPPORTED	This sensor does not have Remote Display capability
80100	COMMAND_MODE_EXPECTED	The Trigger Mode must be set to "Command" perform this operation

Numeric ID	Text ID	Description
80101	COMMAND_TIMED_OUT	The command timed out before finishing
80102	TRIGGER_REQUIRED	Access to the specified data requires a triggered inspection
80150	COMMAND_TIMED_OUT	The command timed out before finishing
80200	SYSTEM_ERROR_NOT_ACTIVE	The System Error must be active to execute this command
80300	TEACH_SENSOR_TYPE_INVALID	Teach requires Match Sensor type.
80350	MULTIPLE_INSPECTIONS_DISABLED	Requires multiple inspections to be enabled
80351	MULTIPLE_INSPECTIONS_EMPTY	No inspections are available in multiple inspection mode.
80400	PRODUCT_CHANGE_WHEN_NOT_READY	Sensor must be in the READY state to perform a product change.
80401	PRODUCT_CHANGE_INVALID_INSPECTION	Attempt to product change to a unknown or invalid inspection.
80402	PRODUCT_CHANGE_TIMEOUT	The Product Change operation timed out.
80403	PRODUCT_CHANGE_TO_SAME_INSPECTION	Attempt to product change to the same inspection.
80404	SENSOR_NAME_NOT_FOUND	Attempt to use a command without a sensor name in a multi-sensor inspection

## Examples of Operation

The following examples show how the iVu Command Channel can be utilized via the Industrial Ethernet connection.

### Clear System Error

1. Write the number 81 as a 16-bit integer into the Command ID register.
2. Toggle the Command bit from 0 to 1 (bit 15 in the Input Bits/Input Coil Bits register).
3. Wait for the Command ACK flag to go from 0 to 1 (bit 15 in the Input Bits ACK/Input Coil Bits ACK register).
4. Verify that the Execution Error flag is not set (i.e. value should be 0). This is bit 15 in the Output Bits/Status Coil Bits register. If the value is 1, read the Error Code register for more information.
5. Task Complete. Toggle the Command bit back to 0 (bit 15 in the Input Bits/Input Coil Bits register).

### Get/Set Trigger Mode

Get the current Trigger Mode from the iVu Plus.

1. Write the number 10001 as a 16-bit integer into the Command ID register.
2. Toggle the Command bit from 0 to 1 (bit 15 in the Input Bits/Input Coil Bits register).
3. Wait for the Command ACK flag to go from 0 to 1 (bit 15 in the Input Bits ACK/Input Coil Bits ACK register).
4. Verify that the Execution Error flag is not set (i.e. value should be 0). This is bit 15 in the Output Bits/Status Coil Bits register. If the value is 1, read the Error Code register for more information.
5. Task Complete. Toggle the Command bit back to 0 (bit 15 in the Input Bits/Input Coil Bits register). Read the current Trigger Mode value in the Command Response Int16 register.

iVu model	Trigger Mode	Int16 value
TG, BCR	External	1
TG	Internal	2
TG	Free Run	3
TG, BCR	Industrial EtherNet Only	10
TG, BCR	Command	20
BCR	Continuous Scan	5
BCR	External Gated	4

Set the desired Trigger Mode for the iVu Plus:

1. Write the number 1 as a 16-bit integer into the Command ID register.
2. Write the desired Trigger Mode's Int16 value from the above table into the Command Parameter Int16 register.
3. Toggle the Command bit from 0 to 1 (bit 15 in the Input Bits/Input Coil Bits register).

4. Wait for the Command ACK flag to go from 0 to 1 (bit 15 in the Input Bits ACK/Input Coil Bits ACK register).
5. Verify that the Execution Error flag is not set (i.e. value should be 0). This is bit 15 in the Output Bits/Status Coil Bits register. If the value is 1, read the Error Code register for more information.
6. Task Complete. Toggle the Command bit back to 0 (bit 15 in the Input Bits/Input Coil Bits register).

### *Set New Barcode Compare String*

This procedure assumes that the Data Compare feature is enabled (found in the Inspection menu for the iVu Plus BCR).

1. Write the number 11001 as a 16-bit integer into the Command ID register.
2. Fill in the Command Parameters String registers with the ASCII data to be used as the new barcode compare string.
3. Write a 32-bit integer value equal to the number of ASCII characters present in the new barcode compare string data into the Command Parameter String Length register.
4. Toggle the Command bit from 0 to 1 (bit 15 in the Input Bits/Input Coil Bits register).
5. Wait for the Command ACK flag to go from 0 to 1 (bit 15 in the Input Bits ACK/Input Coil Bits ACK register).
6. Verify that the Execution Error flag is not set (i.e. value should be 0). This is bit 15 in the Output Bits/Status Coil Bits register. If the value is 1, read the Error Code register for more information.
7. Task Complete. Toggle the Command bit back to 0 (bit 15 in the Input Bits/Input Coil Bits register). The new barcode compare string will be utilized for the next inspection.

### *Get/Set Exposure Time*

Get the current Exposure Time from the iVu Plus.

1. Write the number 10052 as a 16-bit integer into the Command ID register.
2. Toggle the Command bit from 0 to 1 (bit 15 in the Input Bits/Input Coil Bits register).
3. Wait for the Command ACK flag to go from 0 to 1 (bit 15 in the Input Bits ACK/Input Coil Bits ACK register).
4. Verify that the Execution Error flag is not set (i.e. value should be 0). This is bit 15 in the Output Bits/Status Coil Bits register. If the value is 1, read the Error Code register for more information.
5. Task Complete. Toggle the Command bit back to 0 (bit 15 in the Input Bits/Input Coil Bits register). Read the current Exposure Time value (in microseconds) in the Command Response Int32 register.

Set the desired Exposure Time for the iVu Plus.

1. Write the number 52 as a 16-bit integer into the Command ID register.
2. Write the desired Exposure Time (in microseconds) as a 32-bit integer value into the Command Parameter Int32 register. The minimum acceptable value is 117 usec and the maximum value is 1,000,000 usec.
3. Toggle the Command bit from 0 to 1 (bit 15 in the Input Bits/Input Coil Bits register).
4. Wait for the Command ACK flag to go from 0 to 1 (bit 15 in the Input Bits ACK/Input Coil Bits ACK register).
5. Verify that the Execution Error flag is not set (i.e. value should be 0). This is bit 15 in the Output Bits/Status Coil Bits register. If the value is 1, read the Error Code register for more information.
6. Task Complete. Toggle the Command bit back to 0 (bit 15 in the Input Bits/Input Coil Bits register). The new exposure time will be used for the next inspection. Please note that this value is not saved to the iVu's permanent memory unless the Save Configuration task is completed.

### *Save iVu Configuration*

This command saves all modified inspection and configuration parameters to the iVu Plus, including Command Channel changes to exposure time and gain, trigger mode, barcode compare string and/or mask, and Remote Teach sessions.

1. Write the number 102 as a 16-bit integer into the Command ID register.
2. Toggle the Command bit from 0 to 1 (bit 15 in the Input Bits/Input Coil Bits register).
3. Wait for the Command ACK flag to go from 0 to 1 (bit 15 in the Input Bits ACK/Input Coil Bits ACK register).
4. Verify that the Execution Error flag is not set (i.e. value should be 0). This is bit 15 in the Output Bits/Status Coil Bits register. If the value is 1, read the Error Code register for more information.
5. Task Complete. Toggle the Command bit back to 0 (bit 15 in the Input Bits/Input Coil Bits register).

## 7 Debugging Inspections

### 7.1 iVu Emulator

The iVu Emulator is a Windows application that allows you to operate in a Windows environment exactly as you would on the iVu Series sensor itself. In general, the Emulator is an inspection debugging tool where you can:

1. Import stored inspections and configuration from an iVu Plus BCR sensor.
2. Modify inspection parameters on the emulator.
3. Restore the updated configuration back to the sensor.

### 7.2 How to Round-Trip Debug Using the Emulator

The iVu Emulator is a Windows application that allows you to operate in a Windows environment exactly as you would on the sensor itself. In general, the Emulator is an inspection debugging tool: you can import stored inspections and configuration from an iVu sensor, then modify its parameters on the emulator, and restore the updated configuration back to the sensor. When you install the iVu Emulator, by default, it is installed in the following folder:

C:\Program Files\Banner Engineering\iVu Series

You can run the Emulator from this folder, but you will need to move files between the USB drive and PC. To avoid moving files, you can copy the Emulator executable to the USB drive, and run the Emulator directly from the USB drive.

This "how-to" describes the procedures for doing round-trip debugging either using the iVu Emulator installed on a PC or using it directly from the USB Thumb Drive.



**NOTE:** This document refers to saving configuration and inspection logs in folders based on the sensor name. If you have not yet named the sensor, then folders will be named using the first 8-characters of the sensor serial number.

#### 7.2.1 How to Debug Using the Emulator from a PC

1. Plug a USB Thumb Drive into the sensor.
2. Save Inspection Logs to the Thumb Drive.
  - a. On the Main Menu > Inspection Logs > View Logs screen, click the Save icon to save the inspection logs.
  - b. When prompted, select Yes to save sensor configuration along with the Inspection Logs. The location of these files on the USB Thumb Drive will be displayed after the operation is completed. The Inspection Logs are saved in <USB>:\BANNER\<SENSOR\_NAME>\InspLog and the sensor configuration is saved in <USB>:\BANNER\<SENSOR\_NAME>. For example, if the sensor name is myName:
    - Configuration File (CONFIG.CFG) path: <USB>:\BANNER\myName
    - Inspection Logs path: <USB>:\BANNER\myName\InspLog



**NOTE:** If the sensor has no name, then the folder is the first 8-characters of the serial number.

3. Remove the USB drive from the sensor and insert it into an available USB port on a Windows PC that has the iVu Emulator installed.



**Important:** Make sure the iVu Emulator is NOT running before going to the next step.

4. Copy the Sensor Configuration from the USB Thumb Drive to the folder where the Emulator is installed on the PC. For example, if the sensor name is myName and the iVu Emulator is installed in the default location on the PC, copy the file <USB>:\BANNER\myName\CONFIG.CFG to C:\Program Files\Banner Engineering\iVu Series.
5. Copy the Inspection Logs from the USB Thumb Drive (for example, <USB>:\BANNER\myName\InspLog) to the InspLog folder on the PC (for example, C:\Program Files\Banner Engineering\iVu Series\InspLogs).
6. Start the emulator.
7. Set the Trigger option to Internal—
  - a. Go to Main Menu > Imager > Trigger, and select Internal.
  - b. Set the Trigger Interval as desired.

The iVu Emulator will run with the saved configuration from Step 6 using the saved Inspection Logs from Step 7 as images.

8. Make the desired adjustments.

9. Close the iVu Emulator program. All configuration changes will be saved to the CONFIG.CFG file.
10. Copy the sensor configuration (that is, CONFIG.CFG) from the PC working directory to the USB Thumb Drive (for example <USB>:\BANNER\myName\CONFIG.CFG).
11. Remove the USB Thumb Drive from the PC, and connect to the sensor.
12. Restore the configuration to the sensor.
  - a. Go to Main Menu > System > Configuration > Load Configuration.
  - b. Select the Configuration to restore.
  - c. Click the Load button to start the restore sensor configuration.

You will need to reboot the sensor when the restore is complete.

## 7.2.2 How to Debug Using the Emulator from the USB Flash Drive

1. Plug a USB Thumb Drive into the sensor.
2. Save Inspection Logs to the sensor.
  - a. On the Main Menu > Inspection Logs > View Logs screen, click the Save icon to save the inspection logs.
  - b. When prompted, select Yes to save sensor configuration along with the Inspection Logs. The location of these files on the USB Thumb Drive will be displayed after the operation is completed—the Inspection Logs are saved in <USB>:\BANNER\<<SENSOR\_NAME>\InspLog and the sensor configuration is saved in <USB>:\BANNER\<<SENSOR\_NAME>. For example, if the sensor name is myName:
    - Configuration File (CONFIG.CFG) path: <USB>:\BANNER\myName
    - Inspection Logs path: <USB>:\BANNER\myName\InspLog



NOTE: If the sensor has no name, the folder name is the first 8-characters of the serial number.

3. Remove the USB drive from the sensor and insert it into an available USB port on a Windows PC that has the iVu Emulator installed.
4. Copy the iVuEmulator.exe program file to the USB Thumb Drive in the same location as the CONFIG.CFG file (for example, <USB>:\BANNER\myName).
5. Launch the <USB>:\BANNER\myName\iVuEmulator.exe program.
6. Set the Trigger option to Internal—
  - a. Go to Main Menu > Imager > Trigger, and select Internal.
  - b. Set the Trigger Interval as desired.

The iVu Emulator will run with the saved configuration using the saved Inspection Logs as images.

7. Make the desired adjustments.
8. Close the iVu Emulator program. All configuration changes will be saved to the CONFIG.CFG file.
9. Remove the USB Thumb Drive from the PC, and connect to the sensor.
10. Restore the configuration to the sensor.
  - a. Go to Main Menu > System > Configuration > Load Configuration.
  - b. Select the Configuration to restore.
  - c. Click the Load button to start the restore sensor configuration.

You will need to reboot the sensor when the restore is complete.

## 8 Updating the Sensor

### 8.1 Update Process

---

Banner Engineering may release new versions of the sensor firmware in the future. New firmware releases can be downloaded from Banner's website or can be obtained by ordering the latest Product CD. The following steps will guide you through the process of updating the iVu firmware.

Step 1: Copy firmware of desired product to USB Thumb Drive.

1. Launch the iVu Series software

From Product CD:

- Place the latest Product CD into your CD ROM drive. The iVu Series Software will automatically start.
- If your computer is not set for Auto-Play, you may start the iVu Series Software by browsing to the CD drive from My Computer screen and double-clicking on 'iVuSeries.exe'.

From Banner Website:

- Visit Banner's Website: <http://www.bannerengineering.com>
- Browse to Vision Products page and select the iVu product you are using.
- Click on the Software tab to view software releases.
- Determine which version you want to download (Current Version recommended, for example "iVu Series Software Version 2010R4").
- Click on the circular Download button. This will initiate the download process. Depending on your browser settings, you may be asked to confirm or provide a location to save the file. Choose to download on your desktop. Note the file name.
- Double-click the file to start extracting the files and run the iVu Series Software.

2. Select the product you are using and browse to Firmware Update page.

3. Click on 'Run Firmware Update Wizard' and program will start.

4. Follow on-screen instructions. Clicking on 'Copy firmware to USB' will copy the selected firmware to the USB Thumb Drive.

Step 2: Install firmware on iVu

1. Remove the USB Thumb Drive from the PC, and plug it into the sensor.

2. On the sensor, select System -> Firmware Update. The name of the firmware file you copied on the USB Thumb Drive will be displayed.

3. Choose correct file and click on the 'Load' button.

4. Follow the steps on the screen to update the firmware.

### 8.2 How to Set or Modify a Device Name

---

You can set a Device Name for your iVu Series sensor or modify an existing name on the sensor using the software keypad. You can also change the device name this using the iVu Emulator as described below.



NOTE: If you are in a language other than English, you cannot modify the device name using the software keypad. Use the procedure described below.



NOTE: If you have not set the device name previously, then folders will be named using the first 8-characters of the device serial number.

1. Plug a USB Thumb Drive into the device.
2. Save Device Configuration to the USB Thumb Drive (Main Menu > System > Configuration > Save to USB). The location of these files on the USB Thumb Drive will be displayed after the operation is complete—the device configuration is saved in <USB>:\BANNER\<DEVICE\_NAME>. For example, if the device name is myName:, the path will be <USB>:\BANNER\myName).
3. Remove the USB drive from the device and insert it into an available USB drive on a Windows PC.
4. If running the Emulator from the USB, launch the iVuEmulator.exe program. If running the Emulator installed on a PC, make sure the Emulator is not running, and copy the Device Configuration from the USB Thumb Drive to the folder where the Emulator is installed on the PC. For example, if the device name is myName and the iVu Emulator



is installed in the default location on the PC, copy the file <USB>:\BANNER\myName\CONFIG.CFG to C:\Program Files\Banner Engineering\iVu Series.

5. Launch the iVuEmulator.exe program.
6. Go to the Information screen (Main Menu > System > Information).
7. Click the white box next to the Device Name label, and enter the desired Device Name.
8. Click the Back button on the lower-left corner of the screen to save the Device Name.
9. Close the Emulator program and the Device Name will be saved to the CONFIG.CFG file.
10. If running the Emulator on the PC, copy the CONFIG.CFG file back to the original folder on the USB drive—<USB>:\BANNER\<DEVICE\_NAME> (for example <USB>:\BANNER\myName).



NOTE: The device will look in the original folder (for example, myName) for the CONFIG.CFG file.

11. Remove the USB Thumb Drive from the PC, and connect to the device.
12. Restore the configuration to the device.
  - a. Go to Main Menu > System > Configuration > Load from USB.
  - b. Select the Configuration to restore.
  - c. Click the Load button to start the restore device configuration.



NOTE: Once the new device name is restored in the device, all files saved to USB will now reside in the folder corresponding to the new device name.

You will need to reboot the device when the restore is complete.



NOTE: If a Device Configuration from one device is loaded onto another device, the Device Name from the Device Configuration will not be stored in the device.

## 8.3 How to Reset the Sensor Password

If you forget the password for your sensor, you can remove the current password using a reset key that is generated by the Password Reset Utility, which is located on the Product CD. The following steps will guide you through the specific steps to reset the password:

1. On your iVu Series sensor, click the Forgot? button located on the bottom of the Enter Current Password screen.
2. Write down the 6-digit Device Key.
3. On a Windows PC, insert the iVu product CD into the CD ROM drive.
4. From the product CD menu (started upon inserting the CD), launch the Password Reset Utility.
5. Enter the Device Key into the text box in the Utility—identified as Step 1 in the Password Reset Utility.
6. Click the Generate Reset Key button.
7. Write down the four-digit Password Reset Key—identified as Step 2 in the Password Reset Utility.
8. On the iVu Series sensor, check the Next button on the Password Reset screen.
9. Enter the 4-digit reset key on the Enter Reset Key screen.
10. Click Apply.

The password is now cleared.

## 8.4 How to Use Bitmap Image Files with the iVu Emulator

You can use bitmap (.bmp) image files with the iVu Emulator for developing and simulating iVu inspections. The iVu Emulator only accepts image files in .bmp format. If you have other image file formats, use an image viewer/editor program, such as PhotoShop, Gimp, or Paint, to convert the files to 8-bit grayscale .bmp format.



NOTE: Images smaller than 640 × 480 will be black-filled starting in the upper-right. Images larger than 640 × 480 will be cropped starting in the upper-left.

1. Copy the .bmp files into the InspLog folder in the iVu Emulator install folder.

For example, copy .bmp files into the C:\Program Files\Banner Engineering\iVu Series\InspLog folder.



NOTE: Remove any existing .bmp or Log files in that folder to avoid confusion because the Emulator automatically runs all .bmp/Log files sequentially according to filename.

2. Launch the iVu Emulator program.
3. Select Internal Trigger on the Trigger Selection screen (Main Menu > Image > Trigger) and select Internal.
4. Set the Trigger Interval as desired.

The iVu Emulator will be running using the .bmp files from Step 1.



NOTE: Banner does not recommend setting up inspections using these 8-bit grayscale images because you will always end up modifying the configuration after loading it on the sensor on the line. A better choice would be to set up the inspection on the emulator using Inspection Logs from the sensor.

## 9 LED Indicator Troubleshooting

In normal operation, the Power LED is steady green, and the Pass/Fail is green or red depending on the triggered inspection. The Ethernet I/O LED will be lit or off depending on connection status.



1	Power LED	Green: Power Red: Error
2	Pass/Fail LED	Green: Pass Red: Fail
3	Ethernet I/O LED	Green: Connected No Light: Disconnected

The iVu also indicates abnormal conditions as described below.

### 9.1 Errors

Problem Indicator	Solution
The Pass/Fail LED is blinking green a number of times, separated by an LED red blink, and the sensor repeats this pattern over and over. This indicates that no inspections are occurring.	Reboot the sensor.
The Power LED is lit steady red. These type of errors are reported in the System log and appear highlighted in red.	Do the following: <ol style="list-style-type: none"> <li>1. Look in the System Log to see the error.</li> <li>2. Clear the LED; that is, go to the Main Menu &gt; Logs &gt; System Logs and press the Clear System Error button at the bottom of the screen (a sensor reboot is not required).</li> <li>3. If the error occurs again, you can try rebooting the sensor to see if that fixes the problem. If the problem persists, contact Banner customer support.</li> </ol>

### 9.2 Warnings

Warnings are atypical conditions that the sensor detects and fixes. Warning are highlighted in yellow in the System Log, and can typically be ignored.

## 10 Product Support and Maintenance

This section provides general Banner resources and specific documentation for installers and operators of this iVu Plus BCR Vision Sensor.



### WARNING: Not To Be Used for Personnel Protection

Never use this device as a sensing device for personnel protection. Doing so could lead to serious injury or death. This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A sensor failure or malfunction can cause either an energized or de-energized sensor output condition.

### 10.1 Product Support

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Banner provides the following resources for quickly setting up and operating the device.

#### Documentation

#### Online Help

When setting up or monitoring inspections using the iVu sensor's integrated display, you can get online help on any screen by clicking the Help icon in the upper-right of the screen.

#### PDF Documentation

The product documentation is available in a convenient printable format (PDF) on the installation CD or at [www.bannerengineering.com](http://www.bannerengineering.com).

#### Banner Website

The most current product information, documentation, and software updates are available on the Banner website: [www.bannerengineering.com](http://www.bannerengineering.com).

#### Warranty Service

Contact Banner Engineering for troubleshooting of this device. Do not attempt any repairs to this Banner device; it contains no field-replaceable components. If the device or a device component is determined to be defective by a Banner Applications Engineer, they will advise you of Banner's RMA (Return Merchandise Authorization) procedure.



Important: If instructed to return the device, pack it with care. Damage that occurs in return shipping is not covered by warranty.

#### Factory Support

To help Banner better assist you, be ready to provide the following information:

- iVu firmware version (to find the version number, click Main Menu > System > Sensor Information)
- Device Model Number and Date Code, which are found on the bottom of the device.
- Exact wording of any messages that appeared on your screen
- A description of what you were doing and what happened
- A description of how you tried to solve the problem
- Error Codes (see [LED Indicator Troubleshooting](#) on page 115)

### 10.2 Maintenance

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Maintenance tasks include keeping the hardware free of dust and dirt and possibly updating the iVu firmware as new versions become available.

#### Cleaning the Sensor

Regularly remove any dust or dirt from the device using a soft cloth. If needed, slightly dampen the cloth with a weak solution of neutral detergent. Avoid getting dirt on the imager (the area behind the lens). If the imager is dirty, use anti-static compressed air to blow off the dust.

#### Updating the iVu firmware

The current version of iVu firmware is available for download from the Banner website. See the Banner Website for the firmware download link.

## 10.3 Banner Engineering Corp Limited Warranty

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Banner Engineering Corp. warrants its products to be free from defects in material and workmanship for one year following the date of shipment. Banner Engineering Corp. will repair or replace, free of charge, any product of its manufacture which, at the time it is returned to the factory, is found to have been defective during the warranty period. This warranty does not cover damage or liability for misuse, abuse, or the improper application or installation of the Banner product.

THIS LIMITED WARRANTY IS EXCLUSIVE AND IN LIEU OF ALL OTHER WARRANTIES WHETHER EXPRESS OR IMPLIED (INCLUDING, WITHOUT LIMITATION, ANY WARRANTY OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE), AND WHETHER ARISING UNDER COURSE OF PERFORMANCE, COURSE OF DEALING OR TRADE USAGE.

This Warranty is exclusive and limited to repair or, at the discretion of Banner Engineering Corp., replacement. IN NO EVENT SHALL BANNER ENGINEERING CORP. BE LIABLE TO BUYER OR ANY OTHER PERSON OR ENTITY FOR ANY EXTRA COSTS, EXPENSES, LOSSES, LOSS OF PROFITS, OR ANY INCIDENTAL, CONSEQUENTIAL OR SPECIAL DAMAGES RESULTING FROM ANY PRODUCT DEFECT OR FROM THE USE OR INABILITY TO USE THE PRODUCT, WHETHER ARISING IN CONTRACT OR WARRANTY, STATUTE, TORT, STRICT LIABILITY, NEGLIGENCE, OR OTHERWISE.

Banner Engineering Corp. reserves the right to change, modify or improve the design of the product without assuming any obligations or liabilities relating to any product previously manufactured by Banner Engineering Corp.

# Index

## A

Advanced 29  
auto exposure 30

## C

command channel  
  image export 54  
command channel log 62  
command channel sample  
  application 53  
command group  
  history 71  
  info 68  
  inspection 72  
  productchange 71  
  status 69  
  system 68  
  trigger 69  
communication channel  
  command channel 52  
  data export 52  
  image export 52  
  Industrial Ethernet 52  
Communication Logs 46  
communications channels 52  
Configuration menu 19

## D

data export 52  
data export log 62  
data export sample application 54  
debugging 110  
Display Settings menu 28

## E

emulator 110  
Ethernet 12, 52  
ethernet communications 55  
exposure 30  
external strobe 34

## F

fail hold time 29

field of view 35  
firmware update 30  
focus number 33

## G

gain 31

## H

history command group 71  
home screen 14

## I

image export 52, 54  
image export sample application 55  
imager  
  auto exposure 30  
  exposure 30  
  gain 31  
imager menu 30  
Industrial Ethernet 52  
info command group 68  
Information 20  
inspection command group 72  
Inspection Logs 44  
inspection menu 36  
internal strobe 35  
iVu emulator 110

## L

LCD Timeout 29  
Load from USB 20  
lock sensor 21  
logs  
  command channel 62  
  data export 62  
  communication 46  
  inspection 44  
  system 45

## M

menu  
  Display Settings 28  
  Configuration 19  
  Mode 19  
  System 19

Mode menu 19

## P

productchange command group 71

## R

RS-232 12, 52

## S

sample application  
  command channel 53  
  data export 54  
  image export 55  
Save to USB 20  
sensor display 14  
status command group 69  
strobe  
  external 34  
  internal 35  
system command group 68  
System Logs 45  
System menu 19

## T

Touchscreen Calibration 29  
trigger command group 69

## U

USB  
  loading from 20  
  saving to 20