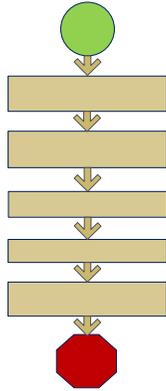


가

iVu TG

가

PC



가 iVu TG

CD

- *iVu TG* () (, P/N 143370)
- *iVu TG* () (, P/N 149160)
- *iVu TG* (P/N 143371)
- *iVu TG* (P/N 143372)



가 가 가 가



(ESD) 가

iVu TG

가

Banner

3

3

M4 x 4 mm

3

1: *iVu*

SMBIVURAL	SMBIVURAR	SMBIVUU

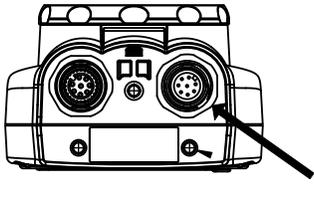
가

iVu TG

iVu TG (B).

I/O

2, 5, 9 15 m(6, 15, 30, 50)



B I/O



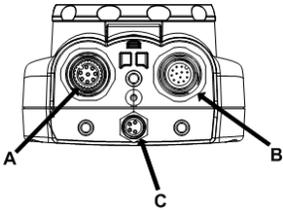
: . C-

I/O			
1		1	
2		10~30 V dc	
3		2	
4		(5 V dc)	
5			
6			
7		()	
8			

가 iVu TG

iVu

, I/O (B) I/O



A

B I/O

C USB

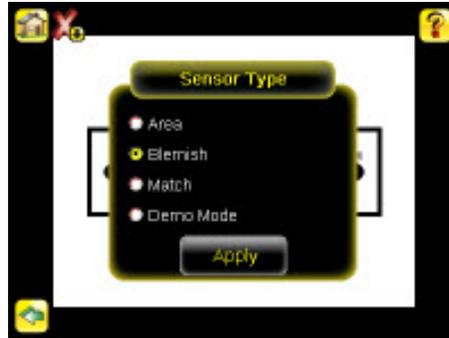


: . C-

I/O			
1		1	
2		10~30 V dc	
3		2	
4		(5 V dc)	
5			
6			
7		()	
8			

iVu TG 가

가

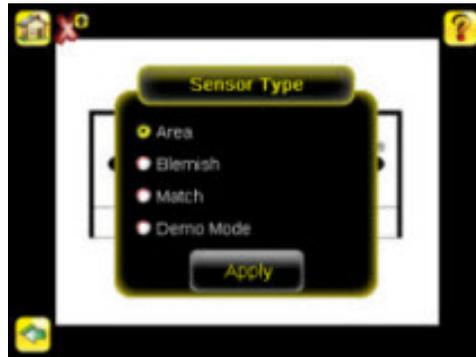


: Main Menu() > System() > Sensor Type() Demo Mode()

iVu TG 3가

가 (Plus 가) :

1. Main Menu() > System() > Sensor Type()
Sensor Type()



2. Area(), Blemish() Match()
3. Apply()

iVu 가

1. Main Menu() > Imager() > Auto Exposure() Auto Exposure()

2. : ()

Banner

- 가
- 3. Main Menu() > Imager() > Auto Exposure() Auto Exposure()
- Gain() Exposure()
- > >



- > >



- 4. Main Menu() > Imager() > Focus() Focus Number()



- 1. 1/16 : (B). (D) iVu

2.

)가



가

Focus Number(



3.

A	
B	
C	
D	
E	()
F	()

C-

1.

2.

Focus Number()가

3.

C-	
A	C-
B	
C	()
D	()
E	

(FOV)

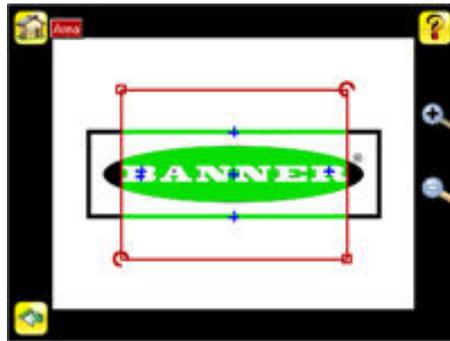
(ROI)

. ROI



1. ROI

ROI



2. ROI

Banner



: ROI

3.

4.

- Intensity Range() 가

1. Main Menu() > Inspection() Intensity Range()



2.

가 (,) .



ROI

- Area Range() . Area Range()
 가 100 x 200 20,000
 1. Main Menu() > Inspection() Area Range()



2.

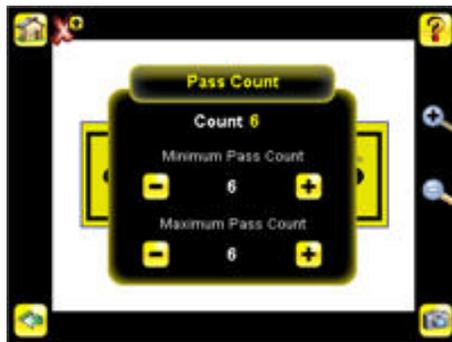
가 (+) . 가



- Pass Count() . Minimum Pass Count()



1. Main Menu() > Inspection() Pass Count()



2. Minimum Pass Count(6) Maximum Pass Count(6)

5. 가

6.



가 ROI 가

(FOV)

1. (ROI) ROI Banner

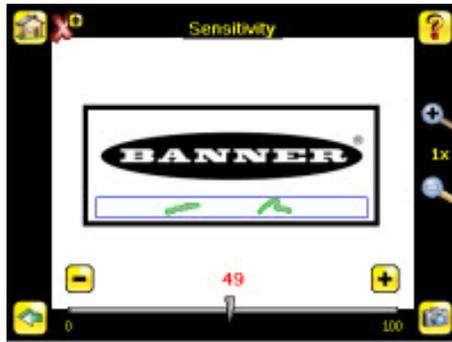


2. ROI

- Sensitivity() . Sensitivity() ROI 가

0 가 0 가 100 가 0 가 100 가 100 가

1. Main Menu() > Inspection() Sensitivity()

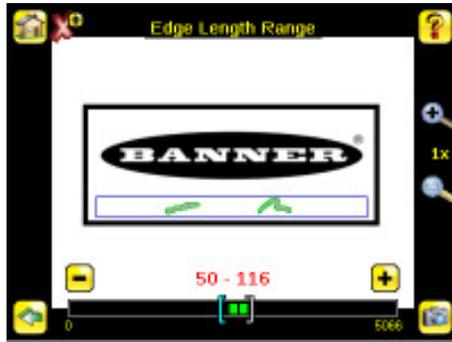


2. Trigger() 가 가
3. Trigger() 가 가

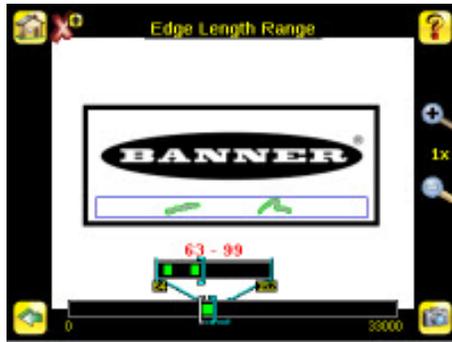


- Edge Length Range(가) ROI 가
- Edge Length Range(가) 가

1. Main Menu() > Inspection() Edge Length Range(가)

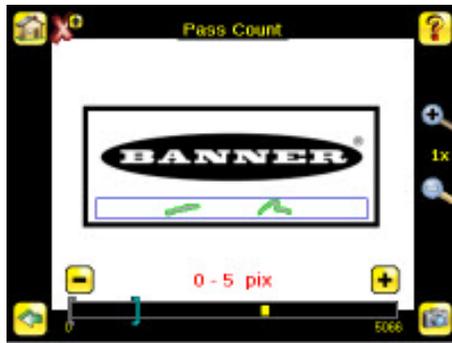


2. 가



• Pass Count() 가 가

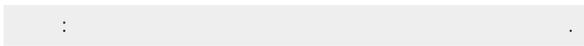
1. Main Menu() > Inspection() Pass Count()



2. /

3. 가

4.



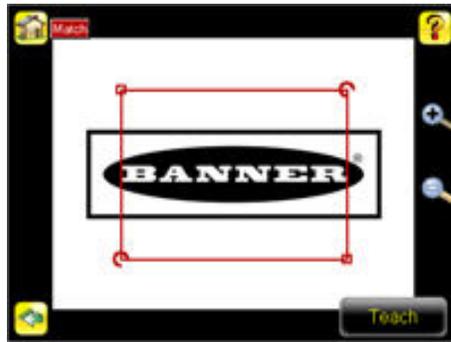
(FOV)

1. (ROI) . ROI (



2. ROI

ROI 가



3.

ROI

Banner



4. Teach()

Annotations Enabled()



5.

- Percent Match((%))

가

- Percent Match((%))

, 100

(%)

0

100

0



가 Percent Match((%))
 Percent Match((%))
 (20%) Rotation Range() ()

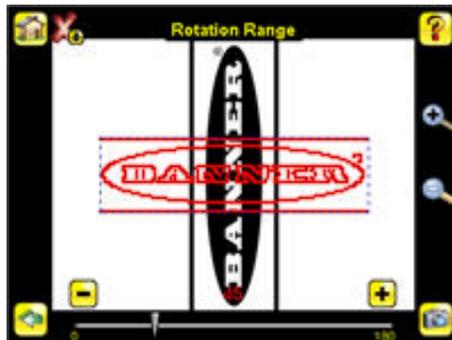
1. " " Manual Trigger()
 "N" 가 " "
2. Main Menu() > Inspection() Percent Match((%))



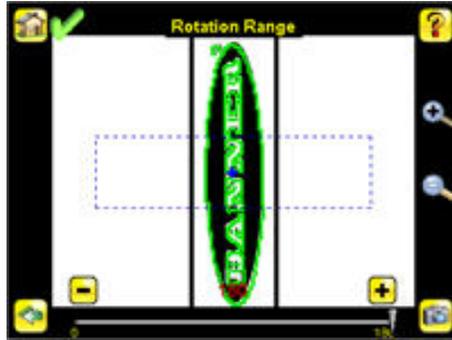
3. Manual Trigger()



- Rotation Range() . Rotation Range() 45
 0 180 가 45 가 . Ro-
 tation Range() :
 1. Main Menu() > Inspection() Rotation Range()

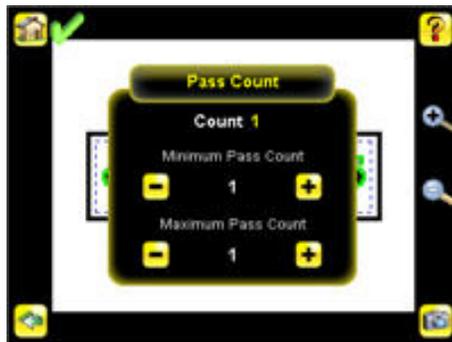


2. (180°)



- Pass Count() . Minimum Pass Count()

1. Main Menu() > Inspection() Pass Count()



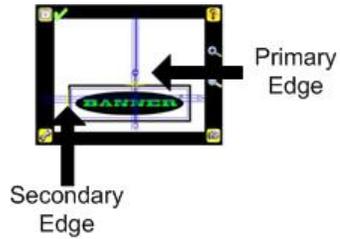
2. Minimum Pass Count() Maximum Pass Count()

6. 가
7.



가
Menu() > Sensor() > Motion() 가 Main Menu() > In-

- Number of Edges(가) 1 가 2 가
 . One Edge(1 가) 가 Two Edges(2 가) 가
 가 가 가 가



- Sensitivity() 가 가 0 100 가 , 0 100
 100 가 가 가 가 가 가 가
- Rotation() Enabled()

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