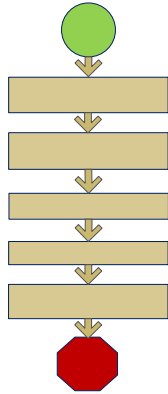


가

iVu TG

가

PC



가 iVu TG

CD

- *iVu TG* ( ) ( , P/N 143370)
- *iVu TG* ( ) ( , P/N 149160)
- *iVu TG* (P/N 143371)
- *iVu TG* (P/N 143372)



가 가 가 가



(ESD) 가

iVu TG

가

Banner

3

3

M4 x 4 mm

3

1: *iVu*

SMBIVURAL	SMBIVURAR	SMBIVUU

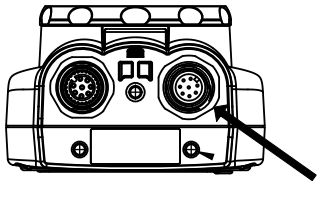
가

iVu TG

iVu TG (B).

I/O

2, 5, 9 15 m(6, 15, 30, 50 )



B I/O



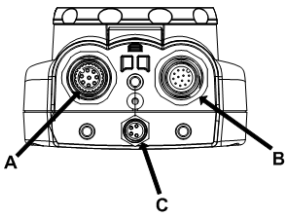
: . C-

I/O			
1		1	
2		10~30 V dc	
3		2	
4		(5 V dc )	
5			
6			
7		( )	
8			

가 iVu TG

iVu

, I/O (B) I/O



A

B I/O

C USB

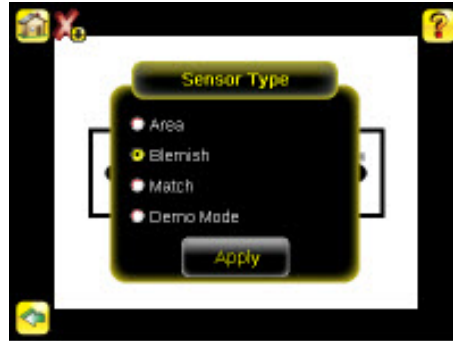


: . C-

I/O			
1		1	
2		10~30 V dc	
3		2	
4		(5 V dc )	
5			
6			
7		( )	
8			

iVu TG 가

가

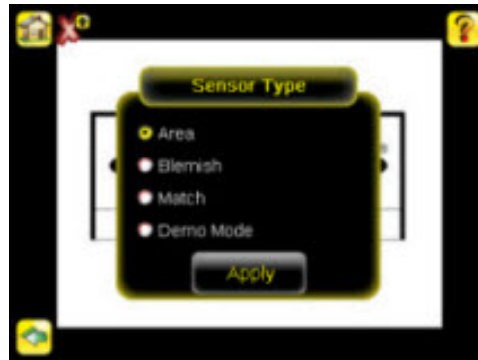


: Main Menu( ) > System( ) > Sensor Type( ) Demo Mode( )

iVu TG 3가

가 (Plus 가) :

1. Main Menu( ) > System( ) > Sensor Type( )  
Sensor Type( )



2. Area( ), Blemish( ) Match( )
3. Apply( )

iVu 가

1. Main Menu( ) > Imager( ) > Auto Exposure( ) Auto Exposure( )

2.
  - ( )
  -

Banner

- 가
- 3. Main Menu( ) > Imager( ) > Auto Exposure( ) Auto Exposure( )
- Gain( ) Exposure( )
- > >



- > >



- 4. Main Menu( ) > Imager( ) > Focus( ) Focus Number( )



- 1. 1/16 : (B). (D) iVu

2.

)가



Focus Number( )가



3.

	A	
	B	
	C	
	D	
	E	( )
	F	( )

C-

1.

2.

Focus Number( )가

3.

C-		
	A	C-
	B	
	C	( )
	D	( )
	E	

(FOV)

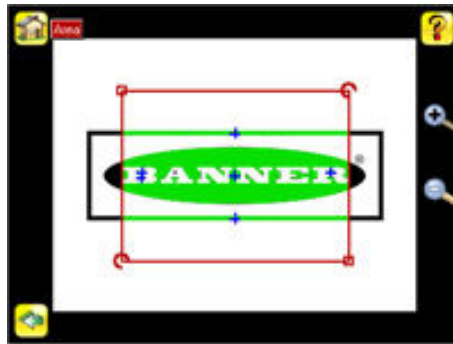
(ROI)

. ROI



1. ROI

ROI



2. ROI

Banner



: ROI

3.  
4.

- Intensity Range( ) 가
- 1. Main Menu( ) > Inspection( ) Intensity Range( )



2.

가 ( , ) .



ROI

- Area Range( ) . Area Range( )  
 가 100 x 200 20,000  
 1. Main Menu( ) > Inspection( ) Area Range( )



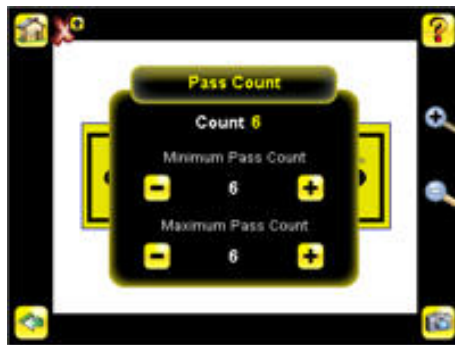
2. 가 ( + ) . 가



- Pass Count( ) . Minimum Pass Count( )



1. Main Menu( ) > Inspection( ) Pass Count( )



2. Minimum Pass Count( 6 ) Maximum Pass Count( 6 )

5. 가

6.



가 ROI 가

(FOV)

1. (ROI) ROI Banner



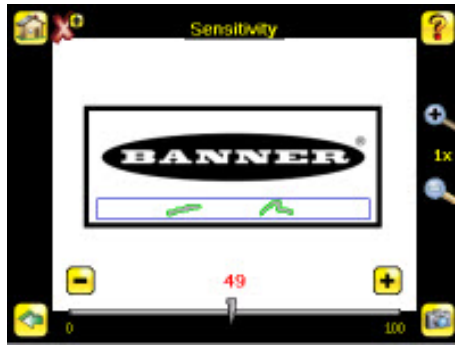


2. ROI

- Sensitivity( ) . Sensitivity( ) ROI 가

0 가 0 가 100 가 0 가 100 100 가

1. Main Menu( ) > Inspection( ) Sensitivity( )

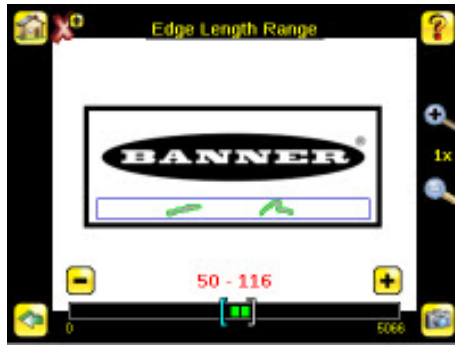


2. 가 가
3. Trigger( ) 가 가

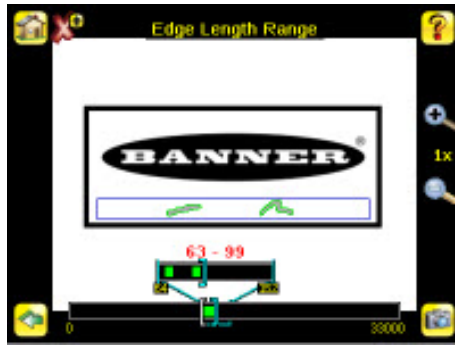


- Edge Length Range(가 ) ROI 가
- Edge Length Range(가 ) 가

1. Main Menu( ) > Inspection( ) Edge Length Range(가 )

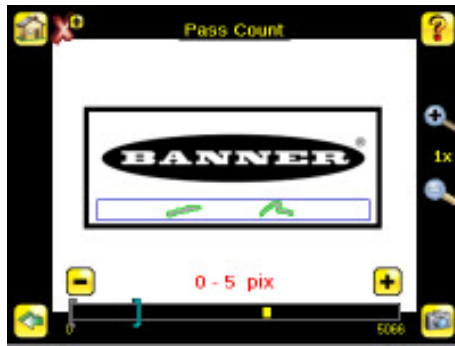


2. 가



• Pass Count( ) 가 가

1. Main Menu( ) > Inspection( ) Pass Count( )



2. /  
3. 가  
4.



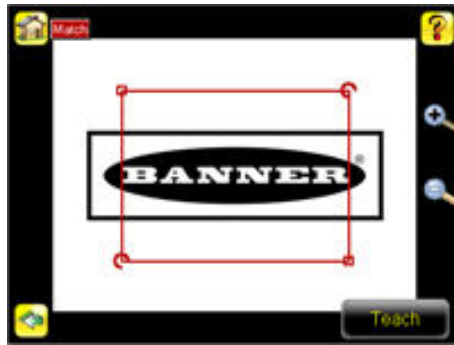
(FOV)

1. (ROI) . ROI (



2. ROI

ROI 가



3.

ROI

Banner



4. Teach( )

Annotations Enabled( )



5.

- Percent Match( %) 가 Percent Match(%) 0 100 0



가 Percent Match( (%) )  
 Percent Match( (%) )  
 ( 20% ) Rotation Range( ) ( )

1. " " Manual Trigger( )  
 "N" 가 " "
2. Main Menu( ) > Inspection( ) Percent Match( (%) )



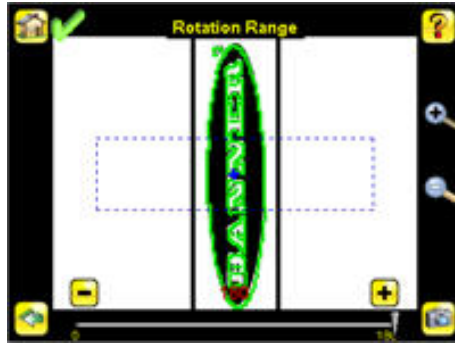
3. Manual Trigger( )



- Rotation Range( ) . Rotation Range( ) 45  
 0 180 가 45 가 . Ro-  
 tation Range( ) :  
 1. Main Menu( ) > Inspection( ) Rotation Range( )

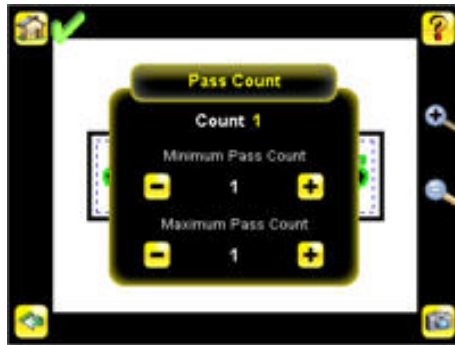


2. ( 180° )



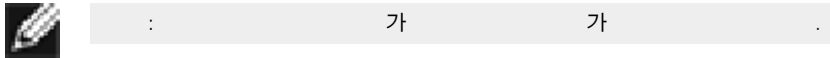
- Pass Count( ) . Minimum Pass Count( )

1. Main Menu( ) > Inspection( ) Pass Count( )



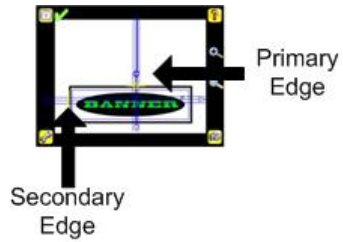
2. Minimum Pass Count( ) Maximum Pass Count( )

6. 가  
7.



가 Main Menu( ) > Sensor( ) > Motion( ) 가 Main Menu( ) > In-

- Number of Edges(가 ) 1 가 2 가  
 . One Edge(1 가 ) 가 Two Edges(2 가 ) 가



- Sensitivity( ) 가 가 0 100 가 , 0 100
- Rotation( ) 가 가 Enabled( )

## Banner Engineering Corp

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