Datasheet
18 mm Ultrasonic Sensors with TEACH-mode programming

- Fast, easy-to-use TEACH-Mode programming; no potentiometer adjustments
- Short dead zone
- One NPN and one PNP output
- Two bi-colored status LEDs
- Rugged encapsulated design for harsh environments
- Choose 2 meter or 9 meter unterminated cable, or 5-pin Euro-style QD connector
- Choose either straight or right-angle housing
- Temperature compensation
- Configurable for normally open or normally closed operation
- Fast response time (5 milliseconds)

WARNING: Not To Be Used for Personnel Protection

Never use this device as a sensing device for personnel protection. Doing so could lead to serious injury or death. This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A sensor failure or malfunction can cause either an energized or de-energized sensor output condition.

Models

<table>
<thead>
<tr>
<th>Model Number</th>
<th>Sensing Range</th>
<th>Cable†</th>
<th>Supply Voltage</th>
<th>Output</th>
<th>Housing Configuration</th>
</tr>
</thead>
<tbody>
<tr>
<td>S18UBA</td>
<td>30 mm to 300 mm (1.2 in to 11.8 in)</td>
<td>5-wire, 2 m (6.5 ft) cable</td>
<td>10 V dc to 30 V dc</td>
<td>Bipolar NPN/PNP</td>
<td>Straight</td>
</tr>
<tr>
<td>S18UBAQ</td>
<td></td>
<td>5-pin Euro style QD</td>
<td></td>
<td></td>
<td>Right-Angle</td>
</tr>
<tr>
<td>S18UBAR</td>
<td></td>
<td>5-wire, 2 m (6.5 ft) cable</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>S18UBARQ</td>
<td></td>
<td>5-pin Euro style QD</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>


Configuration Instructions

Status Indicators

<table>
<thead>
<tr>
<th>Power On/Off LED State</th>
<th>Indicates</th>
</tr>
</thead>
<tbody>
<tr>
<td>Off</td>
<td>The power is off</td>
</tr>
<tr>
<td>On red</td>
<td>The target is weak or is outside of the sensing range</td>
</tr>
<tr>
<td>On green</td>
<td>The sensor is operating normally, target is good</td>
</tr>
</tbody>
</table>

† 9 m cables are available by adding suffix “W/30” to the model number of any cabled sensor (for example, S18UBA W/30).
A model with a QD connector requires a mating cable.
<table>
<thead>
<tr>
<th>Output/Teach LED State</th>
<th>Indicates</th>
</tr>
</thead>
<tbody>
<tr>
<td>Off</td>
<td>The target is outside of the window limits (normally open operation)</td>
</tr>
<tr>
<td>On yellow</td>
<td>The target is within the window limits (normally open operation)</td>
</tr>
<tr>
<td>On red</td>
<td>The sensor is in TEACH mode and is waiting for the first limit</td>
</tr>
<tr>
<td>Flashing red</td>
<td>The sensor is in TEACH mode and is waiting for the second limit</td>
</tr>
</tbody>
</table>

**Sensor Programming**

Use one of two TEACH methods to program the sensor:
- Teach individual minimum and maximum limits
- Use Auto-Window feature to center a sensing window around the taught position

The sensor may be programmed either via its push button, or via a remote switch. Remote programming also may be used to disable the push button, preventing unauthorized personnel from adjusting the programming settings. To access this feature, connect the gray wire of the sensor to 0 V dc to 2 V dc, with a remote programming switch between the sensor and the voltage.

![NOTE: The impedance of the Remote Teach input is 12 kΩ.]

Programming is accomplished by following the sequence of input pulses. The duration of each pulse (corresponding to a push button "click"), and the period between multiple pulses, are defined as "T": \(0.04 \text{ seconds} < T < 0.8 \text{ seconds}\).

**Teach Minimum and Maximum Limits**

**NOTE:**
- The sensor returns to Run mode if the first Teach condition is not registered within 120 seconds
- After the first limit is taught, the sensor remains in Program mode until the Teach sequence is finished
- To exit Program mode without saving any changes, press and hold the programming push button > 2 seconds (before teaching the second limit). The sensor reverts to the last saved limits

![Figure 1. TEACH Interface](image)

![Figure 2. Teaching independent minimum and maximum limits](image)

1. Enter Programming mode.
<table>
<thead>
<tr>
<th>Method</th>
<th>Action</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>Push Button²</td>
<td>Press and hold the TEACH button</td>
<td>Output LED: On red</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Power LED: On green (good signal) or On red (no signal)</td>
</tr>
<tr>
<td>Remote Input³</td>
<td>No action required; the sensor is ready for the first limit</td>
<td></td>
</tr>
</tbody>
</table>

2. Present the target for the first limit. The Power LED must be On green.
3. Teach the first limit.

<table>
<thead>
<tr>
<th>Method</th>
<th>Action</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>Push Button</td>
<td>Press the TEACH button one time.</td>
<td>Teach Accepted</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Output LED: Flashes Red</td>
</tr>
<tr>
<td>Remote Input</td>
<td>Single-pulse the remote line.</td>
<td>Teach Not Accepted</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Output LED: On Red</td>
</tr>
</tbody>
</table>

4. Present the target for the second limit. The Power LED must be On green.
5. Teach the second limit.

<table>
<thead>
<tr>
<th>Method</th>
<th>Action</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>Push Button</td>
<td>Press the TEACH button one time.</td>
<td>Teach Accepted</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Output LED: Yellow or OFF</td>
</tr>
<tr>
<td>Remote Input</td>
<td>Single-pulse the remote line.</td>
<td>Teach Not Accepted</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Output LED: Flashes Red</td>
</tr>
</tbody>
</table>

### Teaching Limits Using the Auto-Window Feature
Teaching the same limit twice for the same output automatically centers a 10 mm window on the taught position.

**NOTE:**
- The sensor returns to Run mode if the first Teach condition is not registered within 120 seconds
- After the first limit is taught, the sensor remains in Program mode until the Teach sequence is finished
- To exit Program mode without saving any changes, press and hold the programming push button > 2 seconds (before teaching the second limit). The sensor reverts to the last saved limits

![Diagram 3](#)

**Figure 3. Using the Auto-Window feature for programming each output**

![Diagram 4](#)

**Figure 4. An application for the Auto-Window feature (retroreflective mode)**

1. Enter Programming mode.
Method | Action | Result
--- | --- | ---
**Push Button** | Press and hold the TEACH button | Output LED: On red<br>Power LED: On green (good signal) or On red (no signal)
**Remote Input** | No action required; the sensor is ready for the first limit

2. Position the target for the center of the window. The Power LED must be On green.
3. Teach the limit.

Method | Action | Result
--- | --- | ---
**Push Button** | Press the TEACH button one time. | **Teach Accepted**<br>Output LED: Flashing Red
**Remote Input** | Single-pulse the remote line. | **Teach Not Accepted**<br>Output LED: ON Red

4. Teach the limit a second time.

Method | Action | Result
--- | --- | ---
**Push Button** | Without moving the target, press the TEACH button one time. | **Teach Accepted**<br>Output LED: Yellow or OFF
**Remote Input** | Without moving the target, single-pulse the remote line. | **Teach Not Accepted**<br>Output LED: Flashing Red

**Normally Open/Normally Closed Operation Select**
The sensor can be configured for either normally open or normally closed operation via the remote teach wire (gray). A series of three pulses on the line will toggle between normally open and normally closed operation. Normally open is defined as the output energizing when the target is present. Normally closed is defined as the output energizing when the target is absent. See Figure 2 on page 2 and Figure 3 on page 3.

To toggle between normally open or normally closed operation, triple-pulse the remote line. Either Normally Open or Normally Closed operation is selected, depending on previous condition.

**Lock the Buttons**
Enable or disable the buttons to prevent unauthorized adjustment of the program settings.

To lock or unlock the buttons, four-pulse the remote line. The buttons are enabled or disabled, depending on the previous condition.

**Installation**

**Principles of Operation**
Ultrasonic sensors emit one or multiple pulses of ultrasonic energy, which travel through the air at the speed of sound. A portion of this energy reflects off the target and travels back to the sensor. The sensor measures the total time required for the energy to reach the target and return to the sensor. The distance to the object is then calculated using the following formula:

\[ D = ct \div 2 \]

- \( D \) = distance from the sensor to the target
- \( c \) = speed of sound in air
- \( t \) = transit time for the ultrasonic pulse

To improve accuracy, an ultrasonic sensor may average the results of several pulses before outputting a new value.

**Temperature Effects**
The speed of sound is dependent upon the composition, pressure and temperature of the gas in which it is traveling. For most ultrasonic applications, the composition and pressure of the gas are relatively fixed, while the temperature may fluctuate.

In air, the speed of sound varies with temperature according to the following approximation:

In metric units:

\[ c_{m/s} = 20 \sqrt{273 + T_C} \]

In English units:

\[ c_{ft/s} = 49 \sqrt{460 + T_F} \]

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4 0.04 s < “click” < 0.8 s
5 0.04 s < T < 0.8 s
Temperature Compensation
Changes in air temperature affect the speed of sound, which in turn affects the distance reading measured by the sensor. An increase in air temperature shifts both sensing window limits closer to the sensor. Conversely, a decrease in air temperature shifts both limits farther away from the sensor. This shift is approximately 3.5% of the limit distance for a 20°C change in temperature.

The S18U series ultrasonic sensors are temperature compensated. This reduces the error due to temperature by about 90%. The sensor will maintain its window limits to within 1.8% over the -20°C to +60°C (−4°F to +140°F) range.

NOTE:
• Exposure to direct sunlight can affect the sensor’s ability to accurately compensate for changes in temperature.
• If the sensor is measuring across a temperature gradient, the compensation will be less effective.
• The temperature warmup drift upon power-up is less than 1.7% of the sensing distance. After 10 minutes, the apparent distance will be within 0.3% of the actual position. After 25 minutes, the sensing position will be stable.

Wiring Diagrams

![Wiring Diagrams](image)

NOTE: It is recommended that the shield wire be connected to earth ground or DC common.

Specifications

Sensing Range
30 to 300 mm (1.2 in to 11.8 in)

Supply Voltage
10 V dc to 30 V dc (10% maximum ripple); 65 mA max. (exclusive of load), 40 mA typical @ 25V input

Ultrasonic Frequency
300 kHz, rep. rate 2.5 ms

Supply Protection Circuitry
Protected against reverse polarity and transient voltages

Output Configuration
SPST solid-state switch conducts when target is sensed within sensing window; one NPN (current sinking) and one PNP (current sourcing) output in each model.

Output Protection
Protected against short circuit conditions

Delay at Power-Up
300 milliseconds

Temperature Effect
0.02% of distance/°C

Connections
2 m (6.5 ft) or 9 m (30 ft) shielded 5-conductor (with drain) PVC jacketed attached cable or 5-pin Euro-style quick-disconnect

Output Ratings
100 mA maximum

Remote TEACH Input
Impedance: 12 kΩ

Construction
Threaded Barrel: Thermoplastic polyester
Push Button: Santoprene
Push Button Housing: ABS/PC
Lightpipes: Acrylic

Minimum Window Size
5 mm

Adjustments
Sensing window limits: TEACH-Mode programming of near and far window limits may be set using the push button or remotely via TEACH input

Indicators
Range Indicator (Red/Green)
Green—Target is within sensing range
Red—Target is outside sensing range
OFF—Sensing power is OFF

Teach/Output Indicator (Amber/Red)
Yellow—Target is within taught limits
OFF—Target is outside taught window limits
Red—Sensor is in TEACH mode

Repeatability
0.5 mm

Output Response Time
5 milliseconds

Hysteresis
0.7 mm
Operating Conditions
Temperature: −20 °C to +60 °C (−4 °F to +140 °F)

Temperature Warmup Drift
Less than 1.7% of sensing distance upon power-up (see Temperature Compensation)

Environmental Rating
Leakproof design is rated IEC IP67; NEMA 6P

Vibration and Mechanical Shock
All models meet Mil Std. 202F requirements. Method 201A (vibration: 10 Hz to 60 Hz max., double amplitude 0.06 inch, maximum acceleration 10G). Also meets IEC 947-5-2 requirements: 30G 11 ms duration, half sine wave.

Application Notes
Objects passing inside the specified near limit may produce a false response.

Certifications

Dimensions

Required Overcurrent Protection

<table>
<thead>
<tr>
<th>Supply Wiring (AWG)</th>
<th>Required Overcurrent Protection (Amps)</th>
</tr>
</thead>
<tbody>
<tr>
<td>20</td>
<td>5.0</td>
</tr>
<tr>
<td>22</td>
<td>3.0</td>
</tr>
<tr>
<td>24</td>
<td>2.0</td>
</tr>
<tr>
<td>26</td>
<td>1.0</td>
</tr>
<tr>
<td>28</td>
<td>0.8</td>
</tr>
<tr>
<td>30</td>
<td>0.5</td>
</tr>
</tbody>
</table>

WARNING: Electrical connections must be made by qualified personnel in accordance with local and national electrical codes and regulations.

Overcurrent protection is required to be provided by end product application per the supplied table.

Overcurrent protection may be provided with external fusing or via Current Limiting, Class 2 Power Supply.

Supply wiring leads < 24 AWG shall not be spliced.

For additional product support, go to http://www.bannerengineering.com.
Response Curves

![Graph showing response curves for different lateral distances and sensing distances.](image)

Figure 7. Effective Beam Pattern (Typical)

Figure 8. Maximum Target Rotation Angle

Accessories

Quick-Disconnect Cables

<table>
<thead>
<tr>
<th>Model</th>
<th>Length</th>
<th>Style</th>
<th>Dimensions</th>
<th>Pinout (Female)</th>
</tr>
</thead>
<tbody>
<tr>
<td>MQDEC2-506</td>
<td>1.83 m (6 ft)</td>
<td>Straight</td>
<td>44 Typ.</td>
<td>1 = Brown</td>
</tr>
<tr>
<td>MQDEC2-515</td>
<td>4.57 m (15 ft)</td>
<td>Straight</td>
<td>ø 14.5</td>
<td>2 = White</td>
</tr>
<tr>
<td>MQDEC2-530</td>
<td>9.14 m (30 ft)</td>
<td>Straight</td>
<td>ø 14.5</td>
<td>3 = Blue</td>
</tr>
<tr>
<td>MQDEC2-550</td>
<td>15.2 m (50 ft)</td>
<td>Straight</td>
<td>ø 14.5 [0.57&quot;]</td>
<td>4 = Black</td>
</tr>
<tr>
<td>MQDEC2-506RA</td>
<td>1.83 m (6 ft)</td>
<td>Right-Angle</td>
<td>32 Typ. [1.26&quot;]</td>
<td>5 = Gray</td>
</tr>
<tr>
<td>MQDEC2-515RA</td>
<td>4.57 m (15 ft)</td>
<td>Right-Angle</td>
<td>30 Typ. [1.18&quot;]</td>
<td></td>
</tr>
<tr>
<td>MQDEC2-530RA</td>
<td>9.14 m (30 ft)</td>
<td>Right-Angle</td>
<td>ø 14.5 [0.57&quot;]</td>
<td></td>
</tr>
<tr>
<td>MQDEC2-550RA</td>
<td>15.2 m (50 ft)</td>
<td>Right-Angle</td>
<td>ø 14.5 [0.57&quot;]</td>
<td></td>
</tr>
</tbody>
</table>

Brackets

SMB18A
- Right-angle mounting bracket
- With a curved slot for versatile orientation
- 12-ga. stainless steel
- 18 mm sensor mounting hole
- Clearance for M4 (#8) hardware

Hole center spacing: A to B = 24.2
Hole size: A = ø 4.6, B = 17.0 x 4.6, C = ø 18.5

SMB18SF
- 18 mm swivel bracket with M18 x 1 internal thread
- Black thermoplastic polyester
- Stainless steel swivel locking hardware included

Hole center spacing: A = 36.0
Hole size: A = ø 5.3, B = ø 18.0
SMB18UR
- 2-piece universal swivel bracket
- 300 series stainless steel
- Stainless steel swivel locking hardware included
- Mounting hole for 18 mm sensor

Hole center spacing: A = 25.4, B = 46.7
Hole size: B = 6.9 × 32.0, C = Ø 18.3

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